

Lecture Notes: Minimum Enclosing Disc

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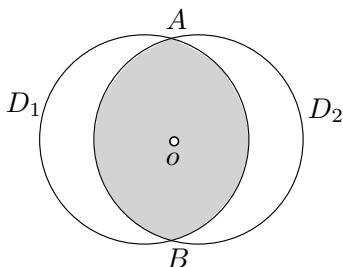
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Let P be a set of n points in \mathbb{R}^2 . We want to find a disc D with the smallest radius to cover all the points in P . We refer to D as the *minimum enclosing disc* (MED) of P and denote it as $med(P)$. The lemma below explains why calling D the MED is appropriate.

Lemma 1. *There is only one disc with the smallest radius covering all the points in P .*

Proof. Assume, on the contrary, that there are two such discs D_1 and D_2 ; see the figure below. Then, P must be covered by the shaded area. Let A and B the intersection points of the two discs. Consider the disc D centering at the midpoint o of the segment AB and having a radius equal to the length of segment oA . D covers the shaded area (and hence, also P) but is smaller than D_1 and D_2 , giving a contradiction.



□

Today we will learn a randomized algorithm for solving the problem in $O(n)$ expected time. As we will see, this is another beautiful application of backward analysis.

1 Geometric Facts

Lemma 2. *The boundary of $med(P)$ passes at least two points of P .*

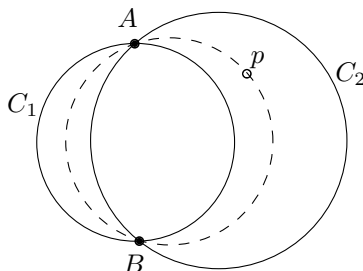
Proof. Let C be the boundary of $med(P)$. If C passes no points of P , shrink C infinitesimally to obtain a smaller disc still covering P , which contradicts the definition of C .

Suppose that C passes only one point $p \in P$. Let o be the center of C . Consider sliding a point o' from o towards p infinitesimally, and look at the circle C' centered at o' with radius equal to the length of segment $o'p$. C' is smaller than C but still contains P in the interior. This is also a contradiction. □

The following geometric fact will be useful:

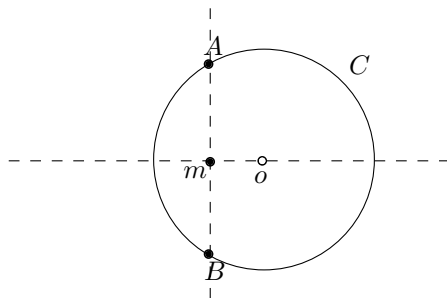
Lemma 3. Let C_1 and C_2 be two intersecting circles such that the radius of C_2 is larger than or equal to that of C_1 . Let α be the area inside both circles. Let p be an arbitrary point that is in C_2 but not in C_1 . Then, there exists a circle C that is smaller than C_2 , larger than C_1 , passes p , and contains the area α .

The figure belows gives an illustration of the lemma, where C is the circle in dash line.



Proof. The lemma can be proved using basic geometry. We give only a sketch here (the complete proof is tedious and rudimentary).

Let us first discuss a relevant fact. Fix two distinct points A, B . Consider all the circles passing both A and B . The centers of these circles must be on the perpendicular bisector of segment AB . Every such circle C can be divided into (i) a left arc, which is the part of C on the left of segment AB , and (ii) a right arc, which is the part of C on the right. As the center o of C moves away from the midpoint m of segment AB towards right, the left arc “sweeps” towards segment AB , while the right arc “sweeps” away from the segment; furthermore, C grows continuously. The behavior is symmetric when o moves away from m towards left.



Going back to the context of the lemma, let A and B be the intersection points of C_1 and C_2 . Imagine morphing a circle C from C_2 to C_1 while making sure that C passes A and B . Stop as soon as the right arc of C hits p . This is the circle we are looking for. \square

2 Two Points Are Known

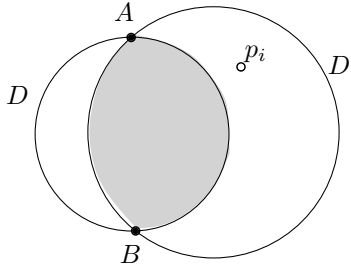
Let us first look at a variant of the MED problem. Let p_1, p_2 be two points in P such that there is at least one disc which has p_1, p_2 on the boundary and covers the entire P . We want to find the smallest such disc, denoted as $med(P, \{p_1, p_2\})$. Algorithm 1 presents our solution in pseudocode. Its running time is clearly $O(n)$. To prove its correctness, it suffices to show:

Lemma 4. Define, for each $i \in [1, n]$, $P_i = \{p_1, \dots, p_i\}$. For $i \geq 3$, let $D = med(P_{i-1}, \{p_1, p_2\})$. If p_i is not covered by D , then the boundary of $med(P_i, \{p_1, p_2\})$ must pass p_i .

Algorithm 1: Two-Points-Fixed-MED($P, \{p_1, p_2\}$)

```
/* suppose  $P = \{p_1, p_2, \dots, p_n\}$  */
1  $D \leftarrow$  the smallest disc covering  $p_1, p_2$ 
2 for  $i = 3$  to  $n$  do
3   if  $p_i$  not in  $D$  then
4      $D \leftarrow$  the disc whose boundary passes  $p_1, p_2, p_i$ 
5 return  $C$ 
```

Proof. Let $D' = \text{med}(P_i, \{p_1, p_2\})$. Assume on the contrary that the boundary of D' does not pass p_i . Hence, p_i falls inside D' ; see the figure below. The radius of D' cannot be smaller than that of D because the latter was the MED on P_{i-1} whereas D' is just one disc covering P_{i-1} . The entire P_{i-1} must fall in the shaded area. By Lemma 3, there exists a disc smaller than D' covering P_i , giving a contradiction. \square



3 One Point Is Known

Next, we will generalize the two-points-fixed problem a bit. Let p_1 be a point in P such that there is at least one disc covering P whose boundary passes p_1 . We want to find the smallest such circle, denoted as $\text{med}(P, \{p_1\})$.

Algorithm 2: One-Point-Fixed-MED($P, \{p_1\}$)

```
/* suppose  $P = \{p_1, p_2, \dots, p_n\}$  */
1 randomly permute  $p_2, \dots, p_n$ 
2  $D \leftarrow$  the smallest disc covering  $p_1, p_2$ 
3 for  $i = 3$  to  $n$  do
4   if  $p_i$  not in  $D$  then
5      $D \leftarrow$  Two-Points-Fixed-MED( $\{p_1, \dots, p_i\}, \{p_1, p_i\}$ )
6 return  $D$ 
```

The algorithm's correctness is ensured by:

Lemma 5. For $i \geq 3$, let $D = \text{med}(P_{i-1}, \{p_1\})$. If p_i is not covered by D , then the boundary of $\text{med}(P_i, \{p_1\})$ must pass p_i .

Proof. Left as an exercise. \square

Let us analyze the running time of the algorithm. Let t_i be the expected running time of the for-loop (Lines 3-5) for a specific i . Thus, the total expected running time is $O(\sum_{i=3}^n \mathbf{E}[t_i])$. Now, focus on t_i for a specific i . Set $D = \text{med}(P_i, \{p_1\})$. We know that, besides p_1 , the boundary of D is determined by at most 2 other points in P — let them be π_1, π_2 (if the boundary passes more than 2 points of P other than p_1 , set π_1, π_2 to 2 arbitrary points of them). Hence, if $p_i \neq \pi_1$ and $p_i \neq \pi_2$, then $t_i = O(1)$; otherwise, $t_i = O(i)$ (Lemma 4). Standard backward analysis shows that $\mathbf{E}[t_i] \leq \frac{2}{i-1}O(i) + O(1) = O(1)$. Therefore, the expected running time of Algorithm 2 is $O(n)$, which subsumes the time of random permutation at Line 1.

4 No Point Is Known

We are ready to tackle the MED problem in its most general form:

Algorithm 3: MED(P)

```

/* suppose  $P = \{p_1, p_2, \dots, p_n\}$  */
1 randomly permute  $p_1, \dots, p_n$ 
2  $D \leftarrow$  the smallest disc covering  $p_1, p_2$ 
3 for  $i = 3$  to  $n$  do
4   if  $p_i$  not in  $D$  then
5      $D \leftarrow$  One-Point-Fixed-MED( $\{p_1, \dots, p_i\}, \{p_i\}$ )
6 return  $C$ 

```

Lemma 6. For $i \geq 3$, let $D = \text{med}(P_{i-1})$. If p_i is not covered by D , then the boundary of $\text{med}(P_i)$ passes p_i .

Proof. Left as an exercise. □

We can once again apply backward analysis to prove that Algorithm 3 runs in $O(n)$ expected time. The details are left as an exercise.