

# Grid Decomposition

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This lecture will introduce **grid decomposition**, which is a fundamental technique for solving many computational geometry problems. We will demonstrate the technique by using it to solve the **closest pair** and **close pairs** problems.

## Closest Pair and Close Pairs

Let  $P$  be a set of points  $\mathbb{R}^d$ . The objective of the **closest pair problem** is to output a pair of distinct points  $p, q \in P$  that have the smallest distance to each other, or formally:

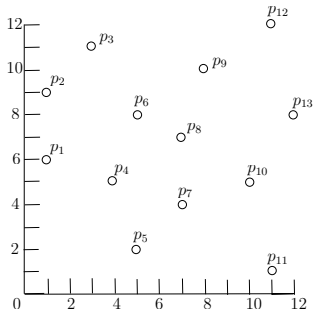
$$\text{dist}(p, q) = \min_{p', q' \in P, p' \neq q'} \text{dist}(p', q').$$

where  $\text{dist}(\cdot, \cdot)$  represents the Euclidean distance of two points.

Let  $P$  be a set of points  $\mathbb{R}^d$  and  $r$  a real value. The objective of the **close pairs problem** is to output all pairs of distinct points  $p, q \in P$  satisfying:

$$\text{dist}(p, q) \leq r.$$

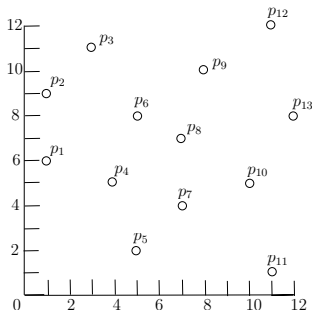
## Example: Closest Pair



The answer is  $(p_6, p_8)$ .

### Example: Close Pairs

Assume  $r = 4\sqrt{2}$ .



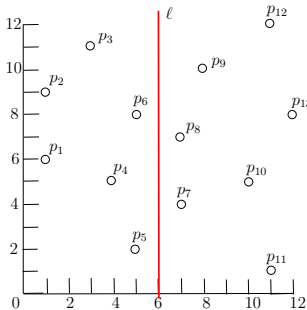
The answer is  $\{(p_1, p_4), (p_1, p_2), (p_2, p_3), (p_2, p_6), (p_2, p_4), \dots\}$ .

Both problems can be easily solved in  $O(n^2)$  time where  $n = |P|$ . We will settle the closest pair problem in  $O(n \log n)$  expected time and the close pair problem in  $O(n + k)$  expected time, where  $k$  is the number of pairs reported.

## Closest Pair in 2D

We will focus on 2D.

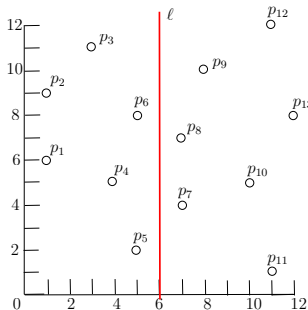
Divide  $P$  evenly using a vertical line  $\ell$ . Let  $P_1$  (or  $P_2$ ) be the set of points on the left (or right) of  $\ell$ . Recursively find the closest pairs in  $P_1$  and  $P_2$ , respectively.



The closest pair of  $P_1$  is  $(p_2, p_3)$  and that of  $P_2$  is  $(p_7, p_8)$ .

## Closest Pair in 2D

It remains to find the closest pair  $(p_1, p_2)$  satisfying  $p_1 \in P_1$  and  $p_2 \in P_2$  (i.e.,  $p_1, p_2$  come from different sides). Call it the **crossing** closest pair.

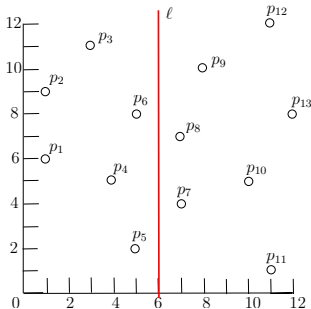


The crossing closest pair is  $(p_6, p_8)$ . The global closest pair must be among the two “local” pairs  $(p_2, p_3)$ ,  $(p_7, p_8)$ , and the crossing pair  $(p_6, p_8)$ .



## Closest Pair in 2D

We now explain how to find the crossing closest pair. Let  $r_1$  be the distance of the closest pair in  $P_1$  and  $r_2$  be the distance of the closest pair in  $P_2$ . Define  $r = \min\{r_1, r_2\}$ .

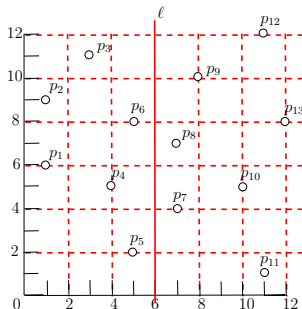


In the above example,  $r_1 = \sqrt{8}$ ,  $r_2 = 3$ , and  $r = \min\{r_1, r_2\} = \sqrt{8}$ .

**Observation:** We care about the crossing closest pair only if its distance is smaller than  $r$ .

## Closest Pair in 2D

Impose a grid  $G$  where (i) each cell is an axis-parallel square with side length  $r/\sqrt{2}$ , and (ii)  $\ell$  is a line in the grid.



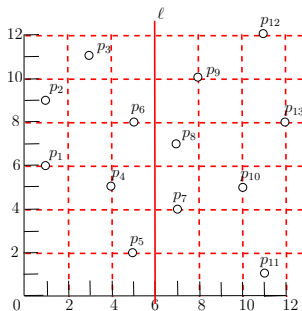
Each point  $p$  can be covered by at most 4 cells.

## Closest Pair in 2D

For each cell  $c$ , denote by  $c(P)$  the set of points in  $P$  covered by  $c$ .

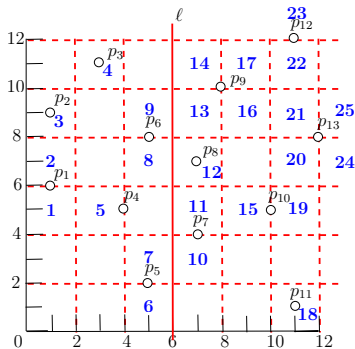
**Observation:** For every  $c$ ,  $|c(P)| \leq 2 = O(1)$ !

**Proof:** The diagonal of  $c$  has length  $r$ . Convince yourself that  $c$  covering more than 2 points would contradict the definition of  $r$ .  $\square$



## Closest Pair in 2D

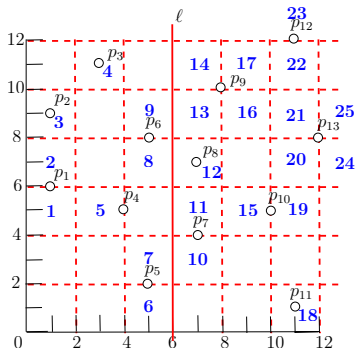
Group the points by the cells they belong. A cell is **non-empty** if it covers at least one point. There can be at most  $4n$  non-empty cells.



In the above example, there are 25 non-empty cells.

## Closest Pair in 2D

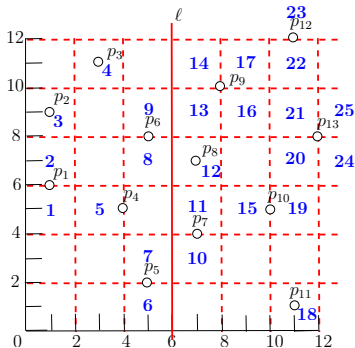
Each cell can be uniquely identified by its centroid's coordinates, which we refer to as the cell's **id**. For each cell  $c$ , we create a linked list containing all the points in  $c(P)$  (i.e., the set of points covered by  $c$ ). This can be done using hashing in  $O(n)$  expected time.



## Closest Pair in 2D

Let  $c_1, c_2$  be two non-empty cells. We say that  $c_1$  is an  $r$ -neighbor of  $c_2$  (and vice versa) if their mindist is at most  $r$ .

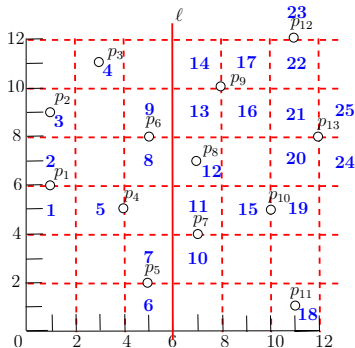
To find a crossing closest pair within distance  $r$ , it suffices to consider non-empty cells  $c_1, c_2$  satisfying (i)  $c_1$  is on the left of  $\ell$ , and  $c_2$  is on the right, and (ii)  $c_1$  and  $c_2$  are  $r$ -neighbors.



For example, we need to consider the cell pair (5, 11), but not (5, 15).

## Closest Pair in 2D

**Observation:** Each non-empty cell  $c$  on the left of  $\ell$  has  $O(1)$   $r$ -neighbor cells on the right of  $\ell$ .



For example, for Cell 8, we need to consider 8 pairs: (8, 10), (8, 11), (8, 12), (8, 13), (8, 14), (8, 15), (8, 16), (8, 17).

## Closest Pair in 2D

The above discussion motivates the following algorithm for finding a crossing closest pair within distance  $r$ :

1. **for** every non-empty cell  $c_1$  on the left of  $\ell$
2.     **for** every  $r$ -neighbor cell  $c_2$  of  $c_1$  on the right of  $\ell$
3.         calculate the distance of each pair of points  $(p_1, p_2) \in c_1(P) \times c_2(P)$
4. **return** the closest one among all the pairs inspected at Line 3, if the pair has distance at most  $r$ .

As mentioned, for each  $c_1$ , there are  $O(1)$  cells  $c_2$  to consider. Since  $c_1(P)$  and  $c_2(P)$  each contain at most 2 points, each execution of Line 3 takes only  $O(1)$  time. The overall algorithm takes  $O(n)$  expected time in total.

**Think:** How to find the cells  $c_2$  for each  $c_1$  in  $O(1)$  expected time?



## Closest Pair in 2D: Analysis

Let  $f(n)$  be the expected running time of our algorithm, it follows that

$$f(n) \leq 2 \cdot f(n/2) + O(n)$$

while  $f(n) = O(1)$  for  $n \leq 2$ .

The recurrence solves to  $f(n) = O(n \log n)$ .

In the closest-pair problem, we utilized the property that each cell in the grid has  $O(1)$   $r$ -neighbor cells.

We now proceed to tackle the close-pairs problem by using the same property. Recall that our objective is to achieve  $O(n + k)$  expected time, where  $k$  is the number of pairs reported.

Recall the definition of the close-pairs problem.

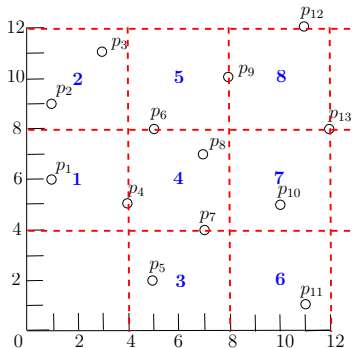
Let  $P$  be a set of distinct points  $\mathbb{R}^d$  and  $r$  a real value. The objective is to output all pairs of distinct points  $p, q \in P$  satisfying:

$$\text{dist}(p, q) \leq r.$$

We will again focus on 2D space.

## Close Pairs in 2D

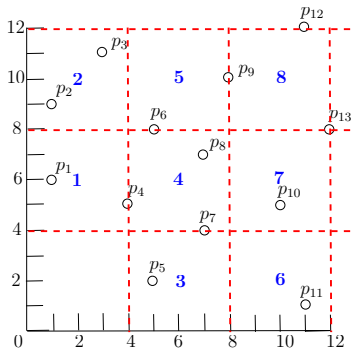
We will explain the algorithm using the same dataset and  $r = 4\sqrt{2}$ .



**Step 1:** Impose an arbitrary grid where each square cell has side length  $r/\sqrt{2} = 4$ . Identify all the non-empty cells.

## Close Pairs in 2D

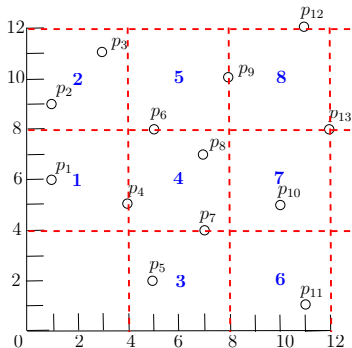
**Step 2:** For each cell  $c$ , let  $c(P)$  be the set of points covered by  $c$ . Simply report all pairs of distinct points in  $c(P)$  — notice that any two points in the same cell must have distance at most  $r$ .



For example, 1 pair is reported for Cell 1, and 3 pairs for Cell 8.

## Close Pairs in 2D

**Step 3:** For each cell  $c_1$ , identify all of its  $r$ -neighbor cells  $c_2$ . For every  $c_2$ , inspect all pairs of distinct points  $(p_1, p_2) \in c_1(P) \times c_2(P)$ , and report the ones within distance at most  $r$ .



For example, from Cells 2 and 4, inspect all the 8 pairs in  $\{p_2, p_3\} \times \{p_4, p_6, p_7, p_8\}$ , and report  $(p_2, p_4)$ ,  $(p_2, p_6)$ ,  $(p_3, p_6)$ .

## Close Pairs in 2D: Analysis

Next, we will prove that our algorithm runs in  $O(n + k)$  expected time. At first glance, this may look surprising. Recall that in Step 3, for each pair of  $r$ -neighbor cells  $(c_1, c_2)$ , we spend a quadratic amount of time  $O(|c_1(P)||c_2(P)|)$ , but risk finding no answer pairs at all. Indeed, the core of the analysis is to show that the total time of doing so is bounded by  $O(n + k)$ .

We will focus on Steps 2 and 3 because Step 1 obviously takes  $O(n)$  expected time (hashing).

## Close Pairs in 2D: Analysis (Step 2)

Let  $c_1, c_2, \dots, c_m$  be the non-empty cells, for some  $m \geq 1$ . Define  $n_i = |c_i(P)|$ , namely, the number of points covered by  $c_i$ , for each  $i \in [1, m]$ . Clearly  $\sum_{i=1}^m n_i \geq n$ .

The cost of Step 2 is

$$\sum_{i=1}^m O(n_i^2)$$

Notice that

$$k \geq \sum_{i=1}^m n_i(n_i - 1)/2 = \left( \frac{1}{2} \sum_{i=1}^m n_i^2 \right) - \left( \frac{1}{2} \sum_{i=1}^m n_i \right).$$

We thus have

$$\sum_{i=1}^m O(n_i^2) = O(n + k).$$



### Close Pairs in 2D: Analysis (Step 3)

We will prove that the cost of Step 3 is  $\sum_{i=1}^m O(n_i^2)$ , and therefore, bounded by  $O(n + k)$ .

Let  $c_i$  and  $c_j$  be a pair of  $r$ -neighbor cells. Step 3 spends  $O(n_i \cdot n_j)$  time to process  $c_i(P) \times c_j(P)$ . Clearly:

$$n_i \cdot n_j \leq (n_i^2 + n_j^2)/2.$$

### Close Pairs in 2D: Analysis (Step 3)

The total cost of Step 3 can be written as

$$O\left(\sum_{i=1}^m \sum_{j: c_j \text{ is an } r\text{-neighbor of } c_i} (n_i^2 + n_j^2)\right)$$

which is bounded by  $O(\sum_{i=1}^m n_i^2)$  because a cell has  $O(1)$   $r$ -neighbors.

We now conclude that the running time of our close-pairs algorithm is  $O(n + k)$  expected.