

9.3 Convergence

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- The convergence of the BA algorithm for computing $R(D_s) sD_s$ can be proved likewise.



9.3.1 A Sufficient Condition

$$\mathbf{u}^{(k+1)} = (\mathbf{u}_1^{(k+1)}, \mathbf{u}_2^{(k+1)}) = (c_1(\mathbf{u}_2^{(k)}), c_2(c_1(\mathbf{u}_2^{(k)})))$$

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for $k \ge 0$.

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= $\Delta f(\mathbf{u}^{(k)}).$

We first prove that if f is concave, then the algorithm cannot be trapped at \mathbf{u} if $f(\mathbf{u}) < f^*$.

Lemma 9.4 Let f be concave. If $f^{(k)} < f^*$, then $f^{(k+1)} > f^{(k)}$.

 \mathbf{Proof}

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It suffices to prove that $\Delta f(\mathbf{u}) > 0$ for any $\mathbf{u} \in A$ such that $f(\mathbf{u}) < f^*$. Then if $f^{(k)} = f(\mathbf{u}^{(k)}) < f^*$, we have $f^{(k+1)} - f^{(k)} = \Delta f(\mathbf{u}^{(k)}) > 0,$

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It suffices to prove that $\Delta f(\mathbf{u}) > 0$ for any $\mathbf{u} \in A$ such that $f(\mathbf{u}) < f^*$. Then if $f^{(k)} = f(\mathbf{u}^{(k)}) < f^*$, we have $f^{(k+1)} - f^{(k)} = \Delta f(\mathbf{u}^{(k)}) > 0,$

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$$f(c_1(\mathbf{u}_2), c_2(c_1(\mathbf{u}_2))) \stackrel{i)}{\geq} f(c_1(\mathbf{u}_2), \mathbf{u}_2) \stackrel{ii)}{\geq} f(\mathbf{u}_1, \mathbf{u}_2).$$

If $\Delta f(\mathbf{u}) = 0$, then both *i*) and *ii*) are tight.

b. Due to the uniqueness of $c_2(\cdot)$ and $c_1(\cdot)$,

ii) is tight
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\mathbf{Proof}

It suffices to prove that $\Delta f(\mathbf{u}) > 0$ for any $\mathbf{u} \in A$ such that $f(\mathbf{u}) < f^*$. Then if $f^{(k)} = f(\mathbf{u}^{(k)}) < f^*$, we have $f^{(k+1)} - f^{(k)} = \Delta f(\mathbf{u}^{(k)}) > 0,$

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It suffices to prove that $\Delta f(\mathbf{u}) > 0$ for any $\mathbf{u} \in A$ such that $f(\mathbf{u}) < f^*$. Then if $f^{(k)} = f(\mathbf{u}^{(k)}) < f^*$, we have $f^{(k+1)} - f^{(k)} = \Delta f(\mathbf{u}^{(k)}) > 0,$

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- d. Then $\tilde{\mathbf{z}} = \alpha_1 \mathbf{z}_1 + \alpha_2 \mathbf{z}_2$, where

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e. Since f is continuous and has continuous partial derivatives, the directional derivative of f at \mathbf{u} in the direction of \mathbf{z}_1 is given by $\nabla f \cdot \mathbf{z}_1$.



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f. f attains its maximum value at $\mathbf{u} = (\mathbf{u}_1, \mathbf{u}_2)$ when \mathbf{u}_2 is fixed.



Proof

It suffices to prove that $\Delta f(\mathbf{u}) > 0$ for any $\mathbf{u} \in A$ such that $f(\mathbf{u}) < f^*$. Then if $f^{(k)} = f(\mathbf{u}^{(k)}) < f^*$, we have

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f. f attains its maximum value at $\mathbf{u} = (\mathbf{u}_1, \mathbf{u}_2)$ when \mathbf{u}_2 is fixed.

g. In particular, f attains its maximum value at **u** along the line passing through $(\mathbf{u}_1, \mathbf{u}_2)$ and $(\mathbf{v}_1, \mathbf{u}_2)$.



Proof

It suffices to prove that $\Delta f(\mathbf{u}) > 0$ for any $\mathbf{u} \in A$ such that $f(\mathbf{u}) < f^*$. Then if $f^{(k)} = f(\mathbf{u}^{(k)}) < f^*$, we have

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Lemma 9.4 Let f be concave. If $f^{(k)} < f^*$, then $f^{(k+1)} > f^{(k)}.$

Proof

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j. Since f is concave along the line passing through **u** and \mathbf{v} , this implies $f(\mathbf{u}) > f(\mathbf{v})$, a contradiction.



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f. f attains its maximum value at $\mathbf{u} = (\mathbf{u}_1, \mathbf{u}_2)$ when \mathbf{u}_2 is fixed.

g. In particular, f attains its maximum value at **u** along the line passing through $(\mathbf{u}_1, \mathbf{u}_2)$ and $(\mathbf{v}_1, \mathbf{u}_2)$.

h. Therefore, by considering the line passing through $(\mathbf{u}_1, \mathbf{u}_2)$ and $(\mathbf{v}_1, \mathbf{u}_2)$, we see that $\nabla f \cdot \mathbf{z}_1 = 0$. Similarly, $\nabla f \cdot \mathbf{z}_2 = 0$.

i. Then
$$\underline{\nabla f \cdot \tilde{\mathbf{z}}} = \alpha_1 (\nabla f \cdot \mathbf{z}_1) + \alpha_2 (\nabla f \cdot \mathbf{z}_2) = 0.$$

j. Since f is concave along the line passing through **u** and **v**, this implies $f(\mathbf{u}) \ge f(\mathbf{v})$, a contradiction.



Lemma 9.4 Let f be concave. If $f^{(k)} < f^*$, then $f^{(k+1)} > f^{(k)}.$

Proof

It suffices to prove that $\Delta f(\mathbf{u}) > 0$ for any $\mathbf{u} \in A$ such that $f(\mathbf{u}) < f^*$. Then if $f^{(k)} = f(\mathbf{u}^{(k)}) < f^*$, we have $(h \mid 1)$ (\mathbf{l}_{a}) (h)0,

$$f^{(\kappa+1)} - f^{(\kappa)} = \Delta f(\mathbf{u}^{(\kappa)}) > 0$$

proving the lemma.

1. First, prove that if $\Delta f(\mathbf{u}) = 0$, then $\mathbf{u}_1 = c_1(\mathbf{u}_2)$ and $u_2 = c_2(u_1)$.

2. Second, consider any $\mathbf{u} \in A$ such that $f(\mathbf{u}) < f^*$. Prove by contradiction that $\Delta f(\mathbf{u}) > 0$.

a. Assume that $\Delta f(\mathbf{u}) = 0$. Then $\mathbf{u}_1 = c_1(\mathbf{u}_2)$ and $\mathbf{u}_2 = c_2(\mathbf{u}_1)$, i.e., \mathbf{u}_1 maximizes f for a fixed \mathbf{u}_2 , and \mathbf{u}_2 maximizes f for a fixed \mathbf{u}_1 .

b. Since $f(\mathbf{u}) < f^*$, there exists $\mathbf{v} \in A$ such that $f(\mathbf{u}) < f(\mathbf{v}).$

c. Let

- $\tilde{\mathbf{z}}$ unit vector in the direction of $\mathbf{v} \mathbf{u}$
- \mathbf{z}_1 unit vector in the direction of $(\mathbf{v}_1 - \mathbf{u}_1, 0)$
- unit vector in the direction of **Z**2 $(0, \mathbf{v}_2 - \mathbf{u}_2).$
- d. Then $\tilde{\mathbf{z}} = \alpha_1 \mathbf{z}_1 + \alpha_2 \mathbf{z}_2$, where

$$\alpha_i = \frac{\|\mathbf{v}_i - \mathbf{u}_i\|}{\|\mathbf{v} - \mathbf{u}\|}, \quad i = 1, 2.$$

e. Since f is continuous and has continuous partial derivatives, the directional derivative of f at \mathbf{u} in the direction of \mathbf{z}_1 is given by $\nabla f \cdot \mathbf{z}_1$.

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h. Therefore, by considering the line passing through $(\mathbf{u}_1, \mathbf{u}_2)$ and $(\mathbf{v}_1, \mathbf{u}_2)$, we see that $\nabla f \cdot \mathbf{z}_1 = 0$. Similarly, $\nabla f \cdot \mathbf{z}_2 = 0$.

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proving the lemma.

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2. Second, consider any $\mathbf{u} \in A$ such that $f(\mathbf{u}) < f^*$. Prove by contradiction that $\Delta f(\mathbf{u}) > 0$.

a. Assume that $\Delta f(\mathbf{u}) = 0$. Then $\mathbf{u}_1 = c_1(\mathbf{u}_2)$ and $\mathbf{u}_2 = c_2(\mathbf{u}_1)$, i.e., \mathbf{u}_1 maximizes f for a fixed \mathbf{u}_2 , and \mathbf{u}_2 maximizes f for a fixed \mathbf{u}_1 .

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k. Hence, $\Delta f(\mathbf{u}) > 0$.



Although $\Delta f(\mathbf{u}) > 0$ as long as $f(\mathbf{u}) < f^*$, $f^{(k)}$ does not necessarily converge to f^* because the increment in $f^{(k)}$ in each step may be arbitrarily small.

Theorem 9.5 If f is concave, then $f^{(k)} \to f^*$.

\mathbf{Proof}

1. $f^{(k)}$ necessarily converges, say to f', because $f^{(k)}$ is nondecreasing and bounded from above.

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5. A' is compact because it is the inverse image of a closed interval under a continuous function and A is bounded. Therefore γ exists.



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8. Thus for all sufficiently large k,

$$f^{(k+1)} - f^{(k)} = \Delta f(\mathbf{u}^{(k)}) \ge \gamma$$



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$$f^{(k+1)} - f^{(k)} = \Delta f(\mathbf{u}^{(k)}) \ge \gamma$$

9. No matter how small γ is, $f^{(k)}$ will eventually be greater than f', which is a contradiction to $f^{(k)} \to f'$.



 \mathbf{Proof}

1. $f^{(k)}$ necessarily converges, say to f', because $f^{(k)}$ is nondecreasing and bounded from above.

2. Hence, for any $\epsilon > 0$ and all sufficiently large k,

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9. No matter how small γ is, $f^{(k)}$ will eventually be greater than f', which is a contradiction to $f^{(k)} \to f'$. 10. Hence, $f^{(k)} \to f^*$.





9.3.2 Convergence to the Channel Capacity

Proposition

$$f(\mathbf{r}, \mathbf{q}) = \sum_{x} \sum_{y} r(x) p(y|x) \log \frac{q(x|y)}{r(x)}$$

is concave.

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1. Consider $(\mathbf{r}_1, \mathbf{q}_1)$ and $(\mathbf{r}_2, \mathbf{q}_2)$ in A.

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\mathbf{Proof}

1. Consider $(\mathbf{r}_1, \mathbf{q}_1)$ and $(\mathbf{r}_2, \mathbf{q}_2)$ in A.

2. Let $0 \leq \lambda \leq 1$ and $\overline{\lambda} = 1 - \lambda$. An application of the log-sum inequality gives

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- 2. Let $0 \leq \lambda \leq 1$ and $\overline{\lambda} = 1 \lambda$. An application of the log-sum inequality gives

$$(\lambda r_1(x) + \bar{\lambda} r_2(x)) \log \frac{\lambda r_1(x) + \bar{\lambda} r_2(x)}{\lambda q_1(x|y) + \bar{\lambda} q_2(x|y)} \leq \lambda r_1(x) \log \frac{\lambda r_1(x)}{\lambda q_1(x|y)} + \bar{\lambda} r_2(x) \log \frac{\bar{\lambda} r_2(x)}{\bar{\lambda} q_2(x|y)}.$$

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$$f(\mathbf{r}, \mathbf{q}) = \sum_{x} \sum_{y} r(x) p(y|x) \log \frac{q(x|y)}{r(x)}$$

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$$\frac{\lambda r_1(x) + \bar{\lambda} r_2(x)}{\lambda q_1(x|y) + \bar{\lambda} q_2(x|y)} \leq \lambda r_1(x) \log \frac{\lambda r_1(x)}{\lambda q_1(x|y)} + \bar{\lambda} r_2(x) \log \frac{\bar{\lambda} r_2(x)}{\bar{\lambda} q_2(x|y)}.$$

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