



香港中文大學
The Chinese University of Hong Kong

Chapter 7

Discrete Memoryless Channels

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In this chapter

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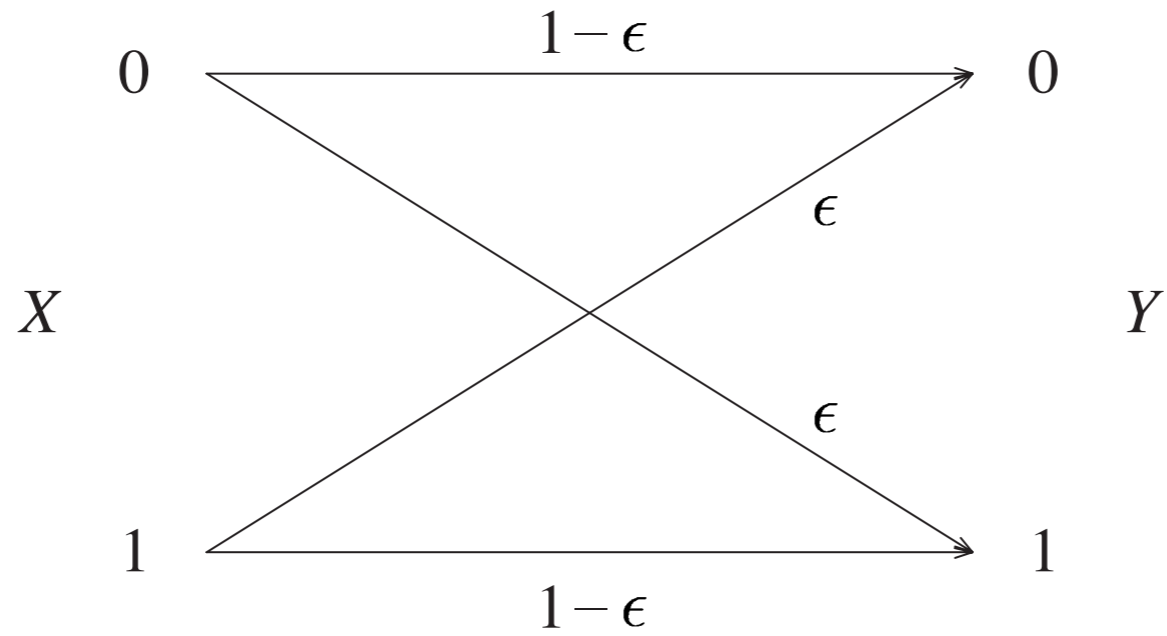
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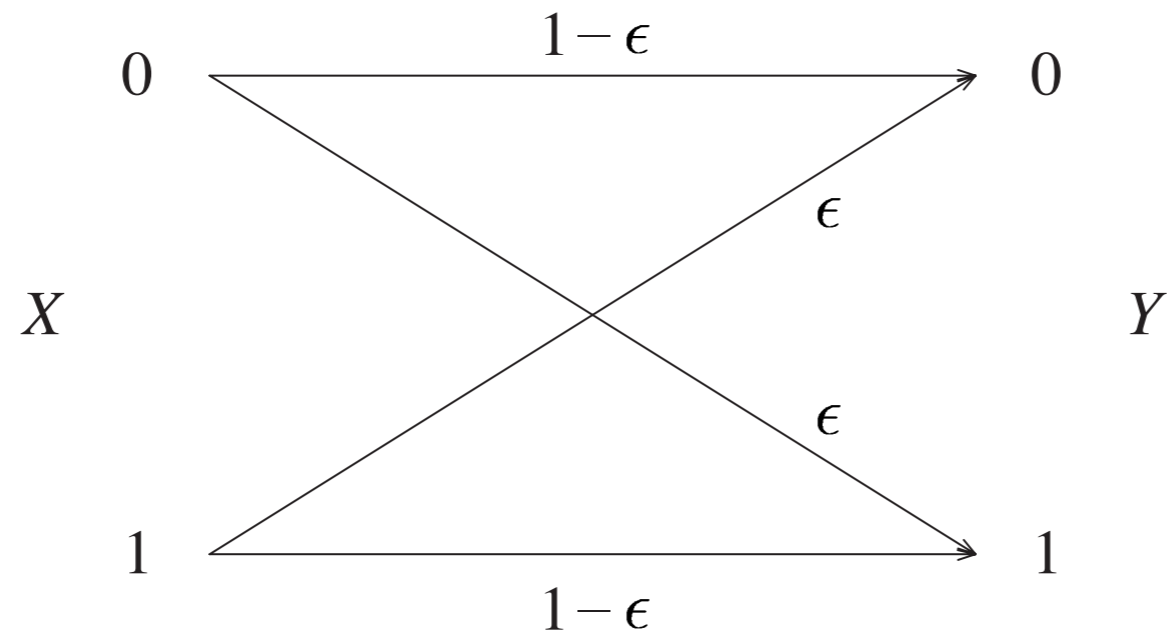
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- Separation theorem for source coding and channel coding

An Informal Discussion

Binary Symmetric Channel (BSC)

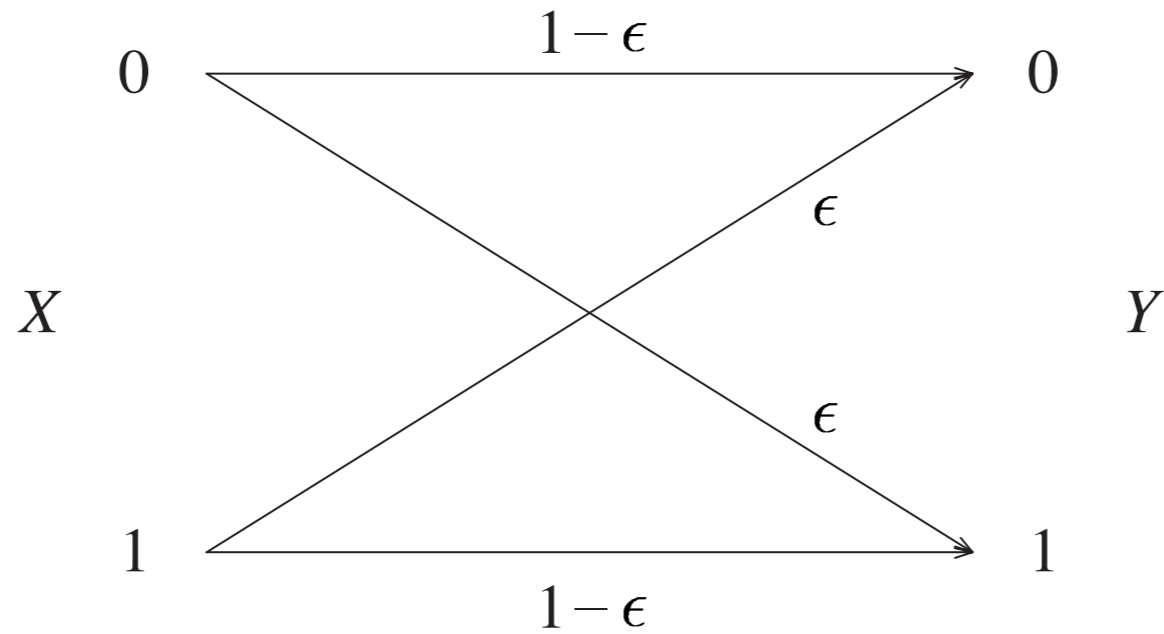


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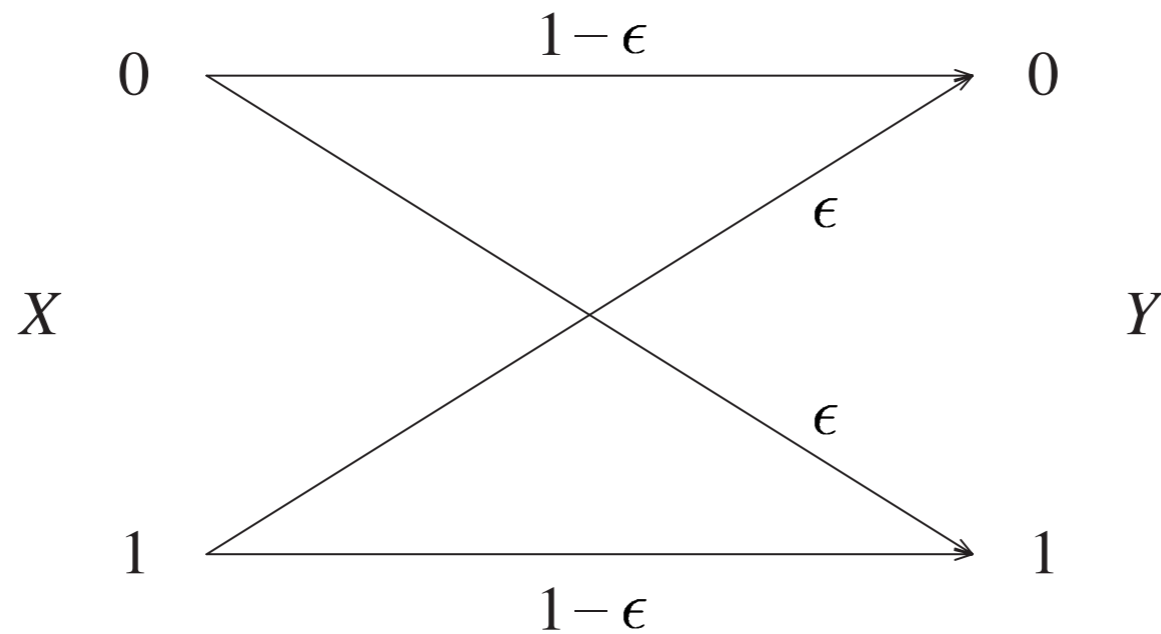
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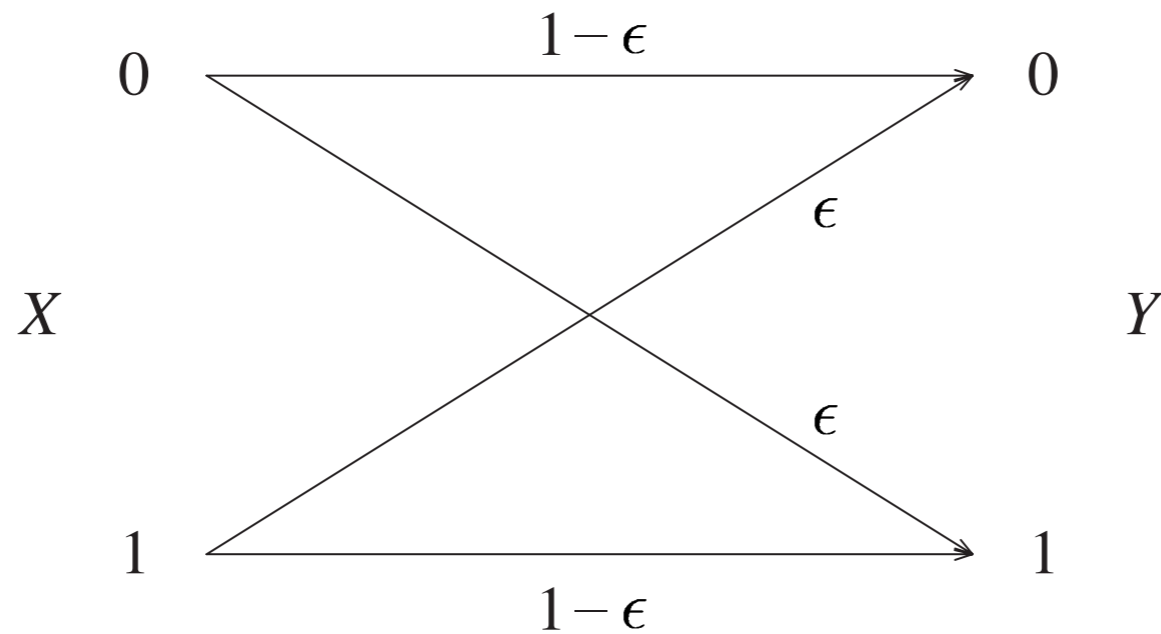
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- Crossover probability $= \epsilon, 0 \leq \epsilon \leq 1$

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- A decoding error if and only if a crossover occurs. Therefore, $P_e = \epsilon$.

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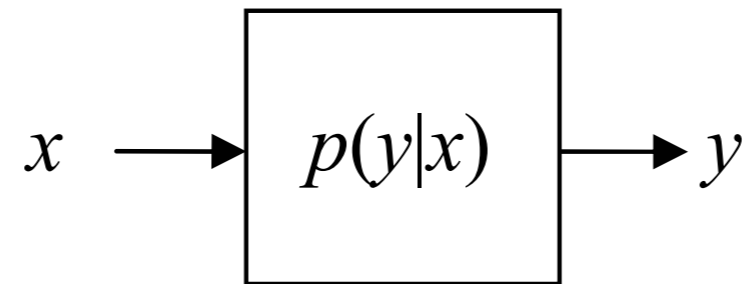
- However, $R = \frac{1}{n} \log 2 \rightarrow 0$ as $n \rightarrow \infty$. :(



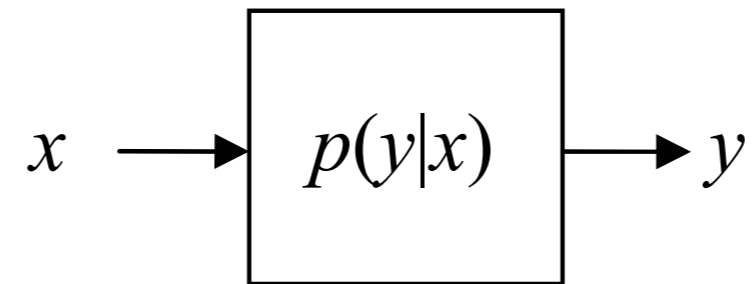
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7.1 Definition and Capacity

Definition 7.1 (Discrete Channel I)

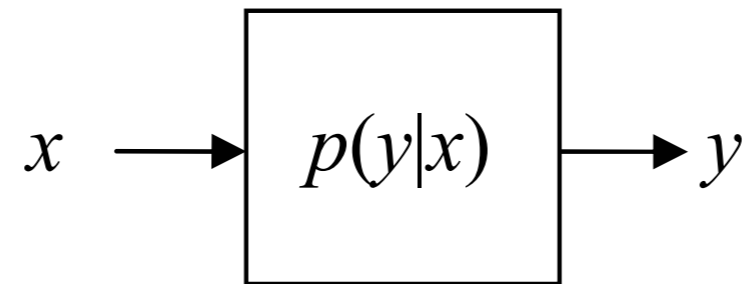


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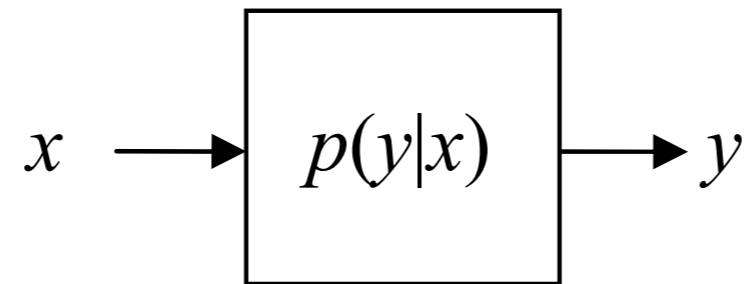
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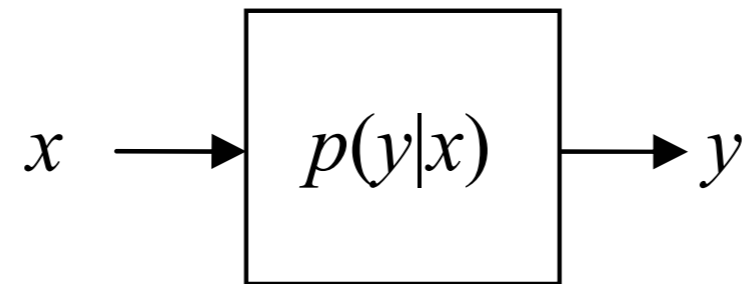
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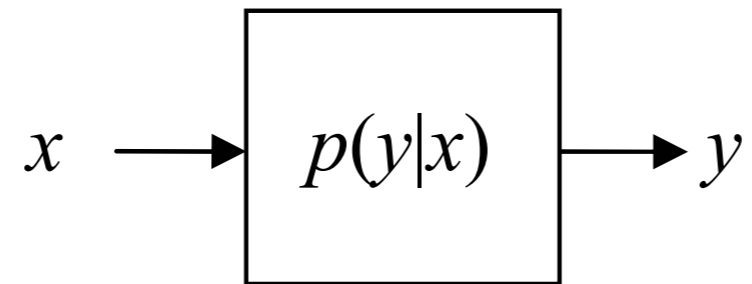
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- BSC with crossover probability ϵ :

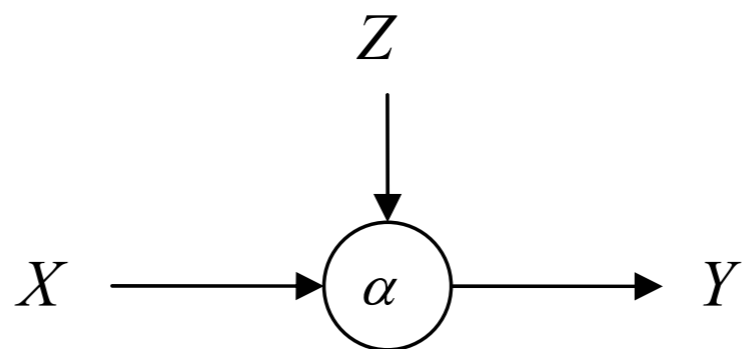
$$[p(y|x)] = \begin{bmatrix} 1 - \epsilon & \epsilon \\ \epsilon & 1 - \epsilon \end{bmatrix}$$

Definition 7.1 (Discrete Channel I) Let \mathcal{X} and \mathcal{Y} be discrete alphabets, and $p(y|x)$ be a transition matrix from \mathcal{X} to \mathcal{Y} . A discrete channel $p(y|x)$ is a single-input single-output system with input random variable X taking values in \mathcal{X} and output random variable Y taking values in \mathcal{Y} such that

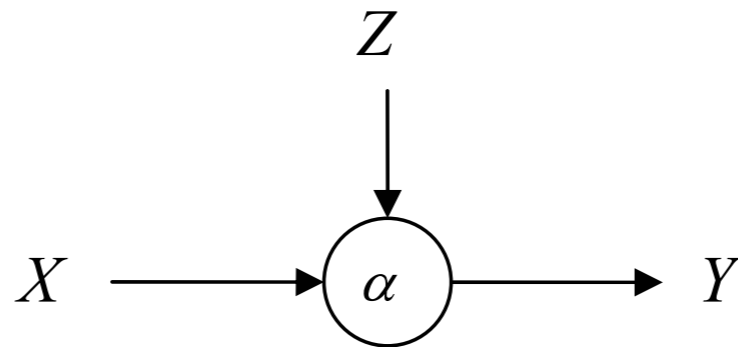
$$\Pr\{X = x, Y = y\} = \Pr\{X = x\} p(y|x)$$

for all $(x, y) \in \mathcal{X} \times \mathcal{Y}$.

Definition 7.2 (Discrete Channel II)

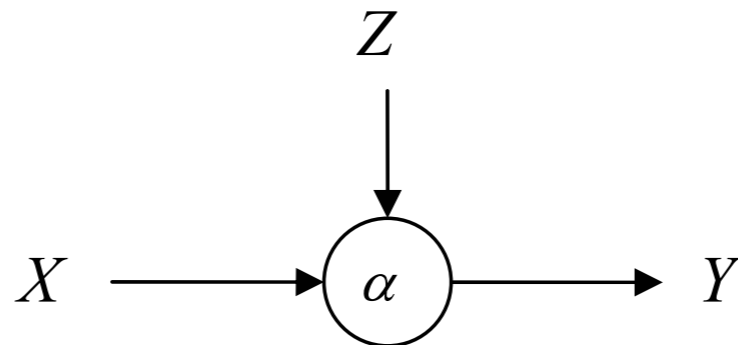


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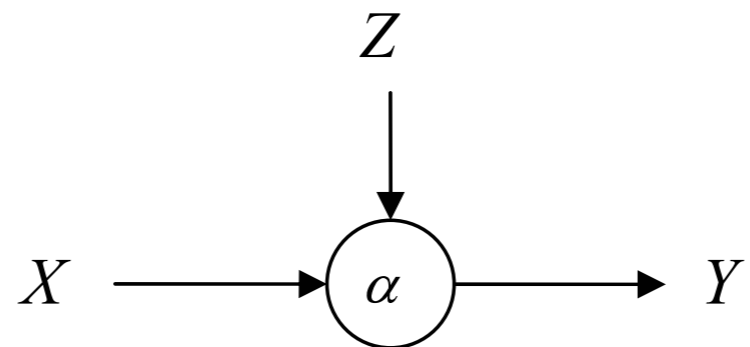
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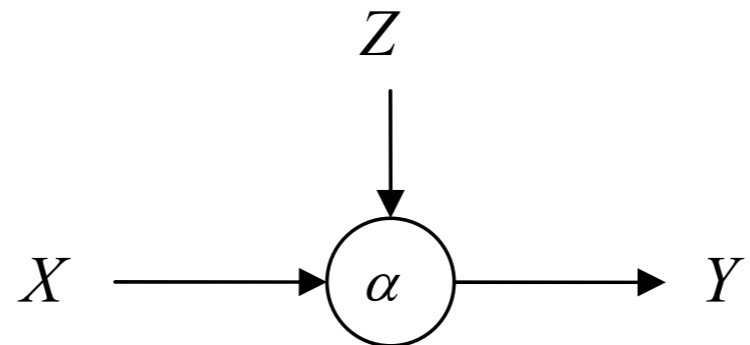
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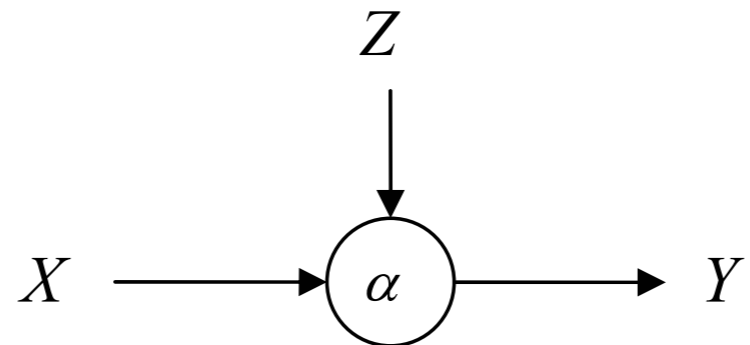
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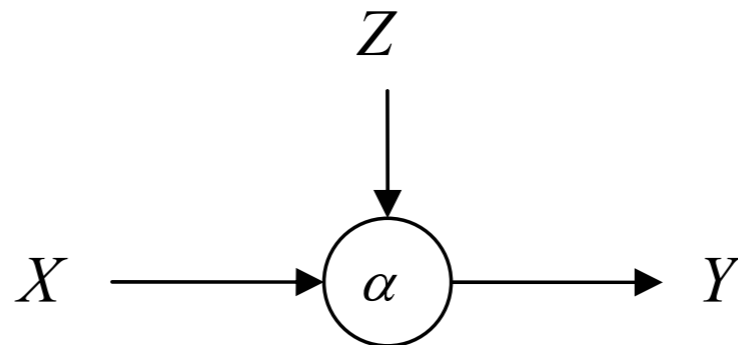
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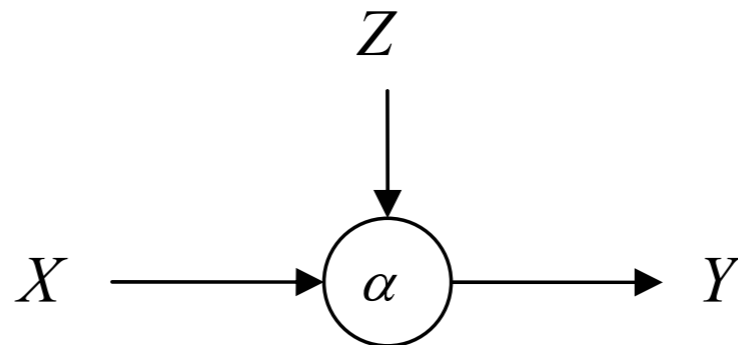
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- Input-output relation: $Y = \alpha(X, Z)$.

Definition 7.2 (Discrete Channel II) Let \mathcal{X} , \mathcal{Y} , and \mathcal{Z} be discrete alphabets. Let $\alpha : \mathcal{X} \times \mathcal{Z} \rightarrow \mathcal{Y}$, and Z be a random variable taking values in \mathcal{Z} , called the **noise variable**. A discrete channel (α, Z) is a single-input single-output system with input alphabet \mathcal{X} and output alphabet \mathcal{Y} . For any input random variable X , the noise variable Z is independent of X , and the output random variable Y is given by

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Equivalence of Discrete Channel I & Discrete Channel II

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Definition 7.3 Two discrete channels $p(y|x)$ and (α, Z) defined on the same input alphabet \mathcal{X} and output alphabet \mathcal{Y} are equivalent if

$$\Pr\{\alpha(x, Z) = y\} = p(y|x)$$

for all x and y .

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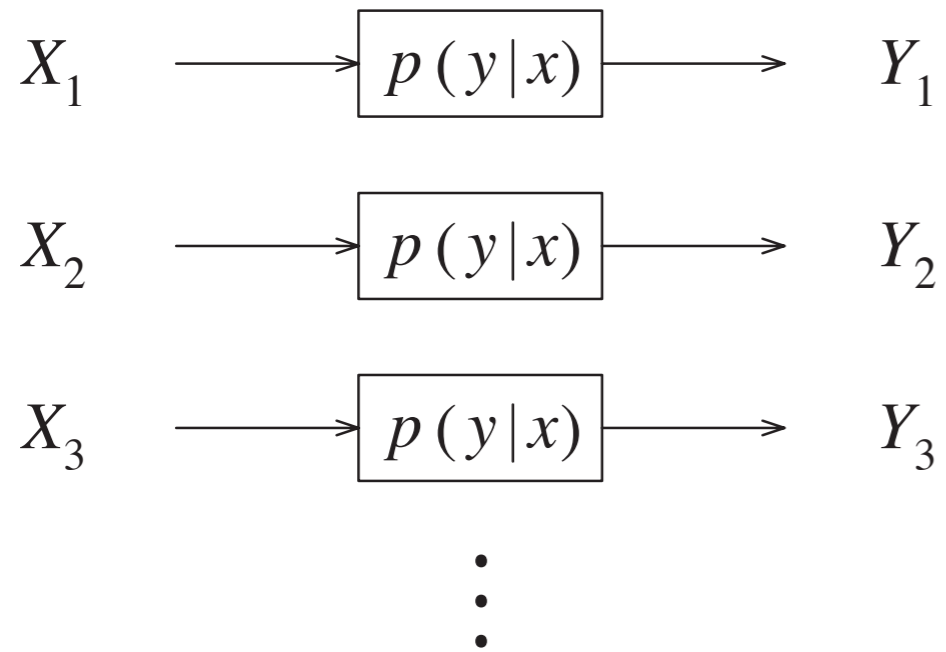
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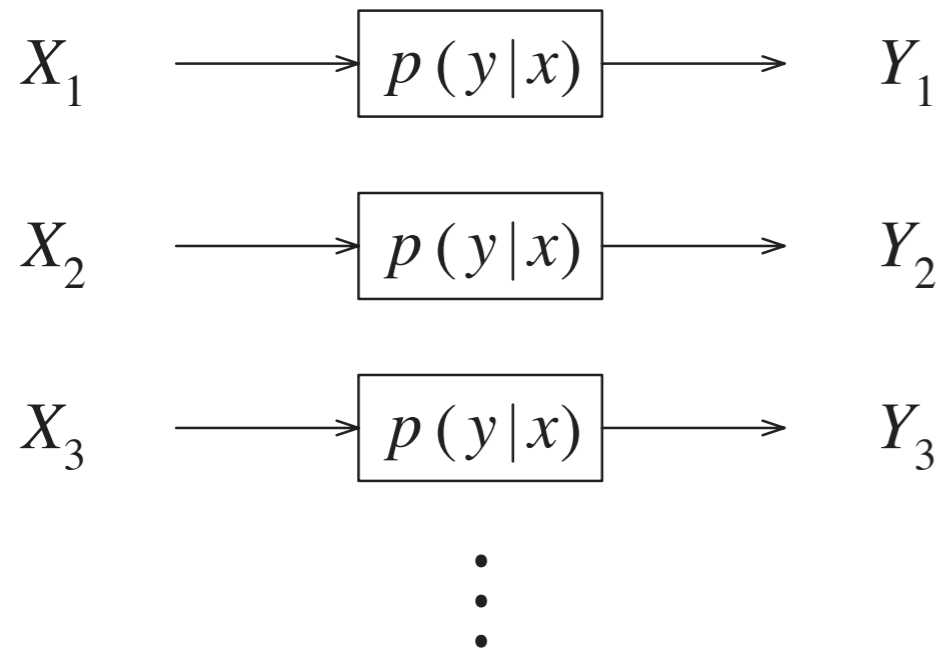
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- More than one random variable may be generated instantaneously but sequentially at a particular time index.

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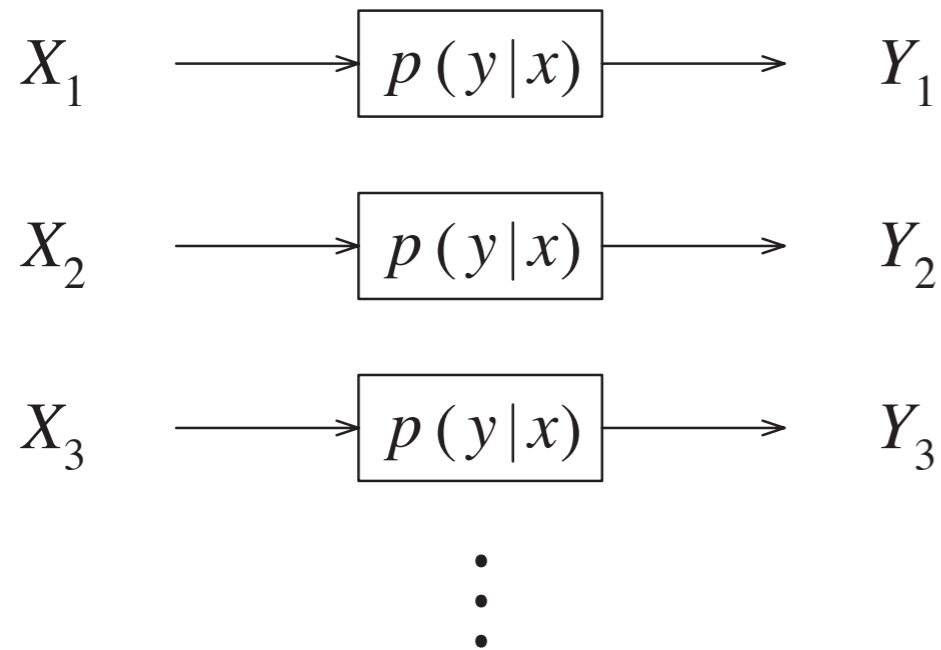


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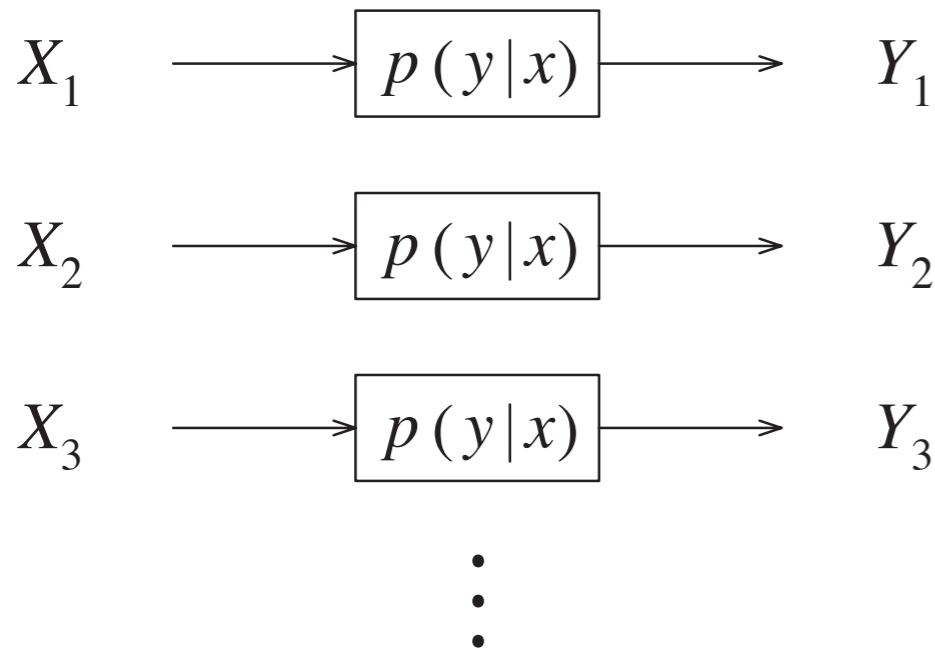
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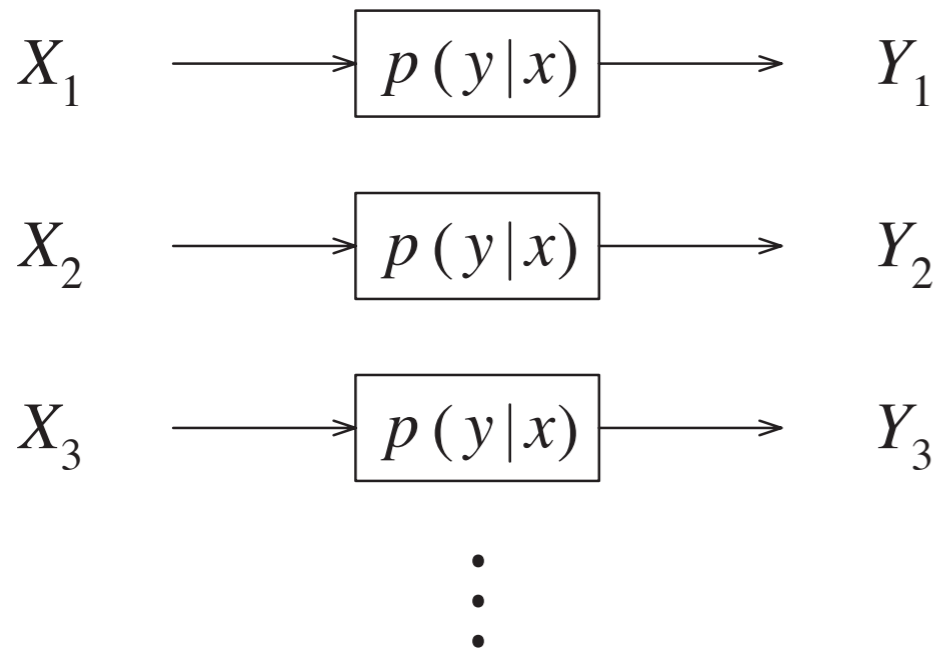
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- T_{i-} : all the random variables in the system generated before X_i .
- Memoryless Property (Independent noise):

$$\begin{aligned} \Pr\{Y_i = \mathbf{y}, X_i = \mathbf{x}, T_{i-} = t\} \\ = \Pr\{X_i = \mathbf{x}, T_{i-} = t\} p(\mathbf{y}|\mathbf{x}) \end{aligned}$$

Definition 7.4 (DMC I)

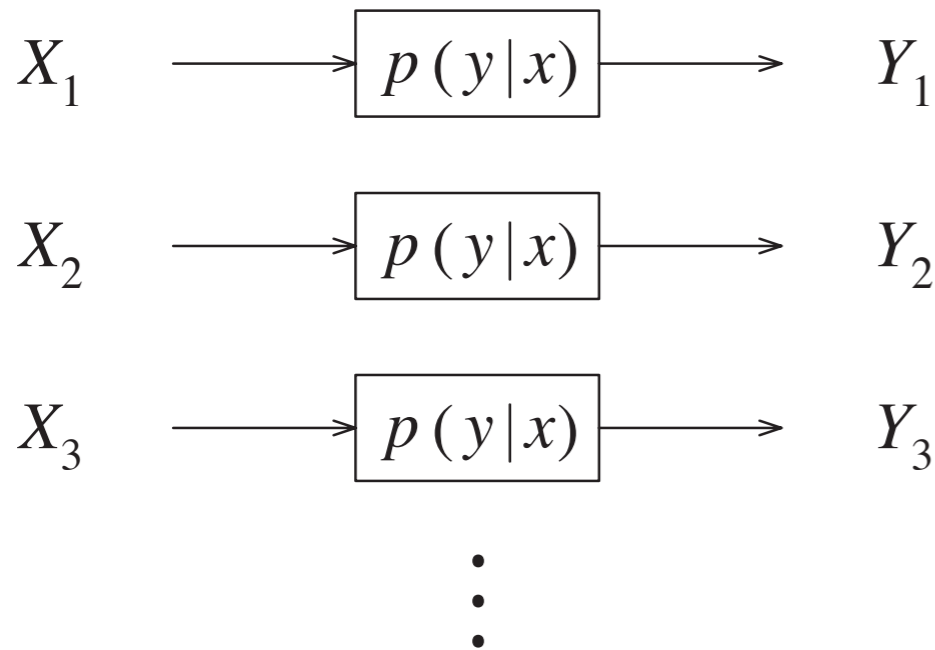


- A DMC specified by $p(y|x)$ is a sequence of replicates of a **generic discrete channel** $p(y|x)$.
- T_{i-} : all the random variables in the system generated before X_i .
- Memoryless Property (Independent noise):

$$\begin{aligned}\Pr\{Y_i = \mathbf{y}, X_i = \mathbf{x}, T_{i-} = t\} \\ = \Pr\{X_i = \mathbf{x}, T_{i-} = t\} p(\mathbf{y}|\mathbf{x})\end{aligned}$$

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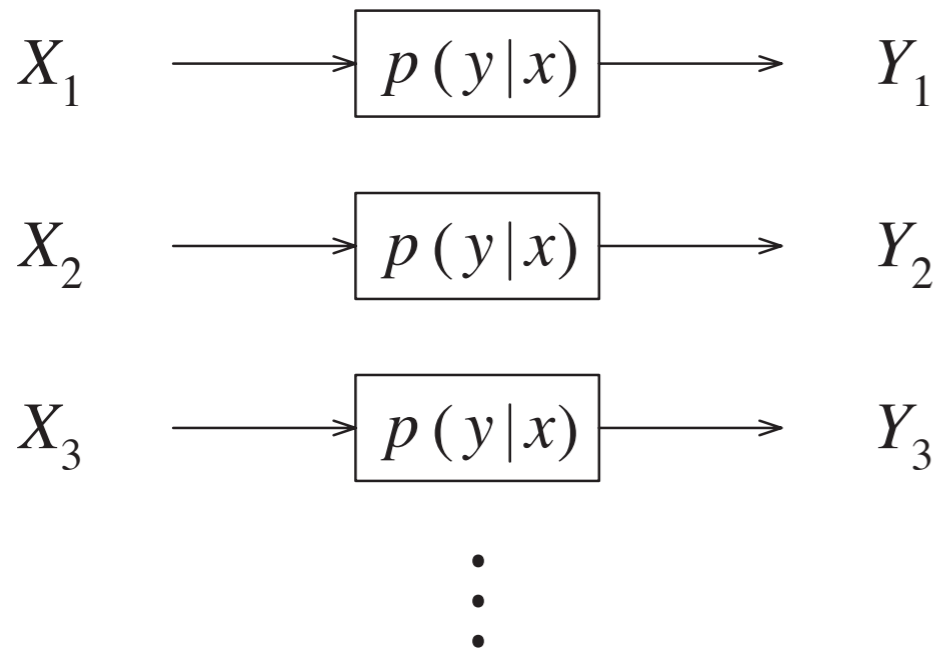
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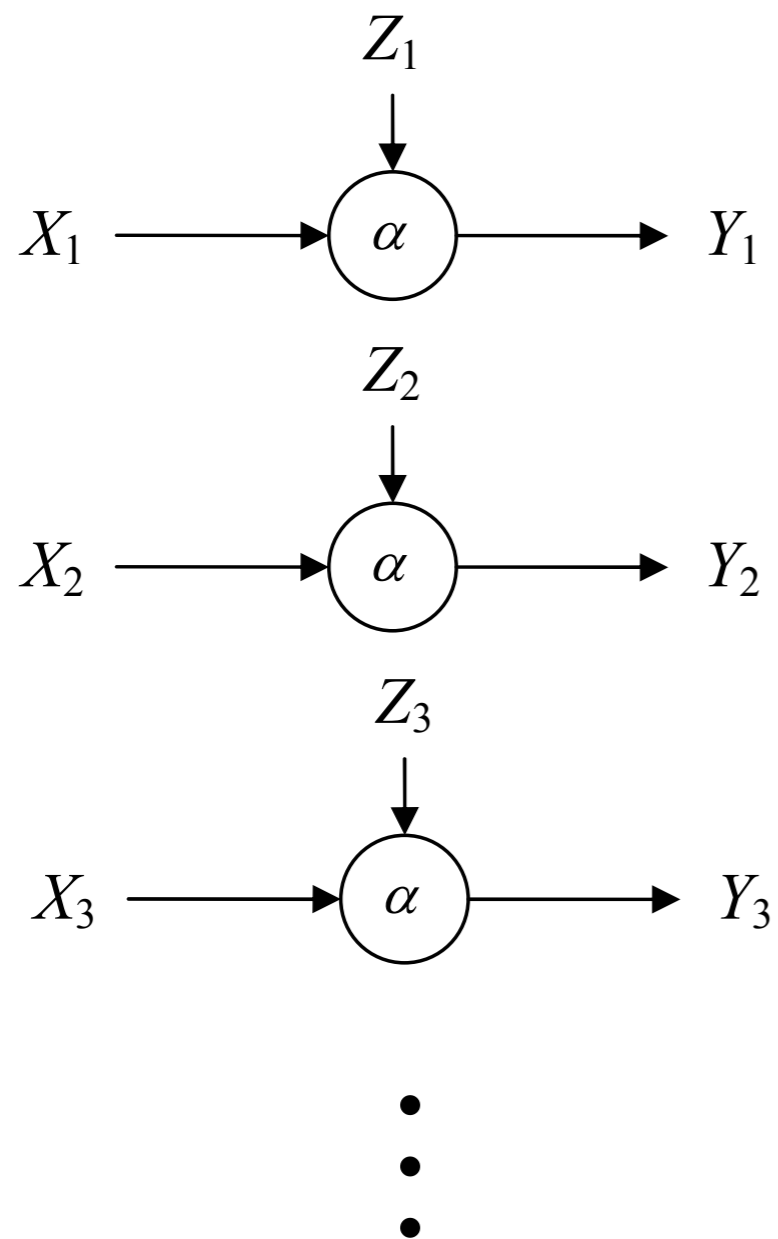
Given X_i , Y_i is independent of everything in the past.

Definition 7.4 (DMC I) A discrete memoryless channel (DMC) $p(y|x)$ is a sequence of replicates of a generic discrete channel $p(y|x)$. These discrete channels are indexed by a discrete-time index i , where $i \geq 1$, with the i th channel being available for transmission at time i . Transmission through a channel is assumed to be instantaneous. Let X_i and Y_i be respectively the input and the output of the DMC at time i , and let T_{i-} denote all the random variables that are generated in the system before X_i . The equality

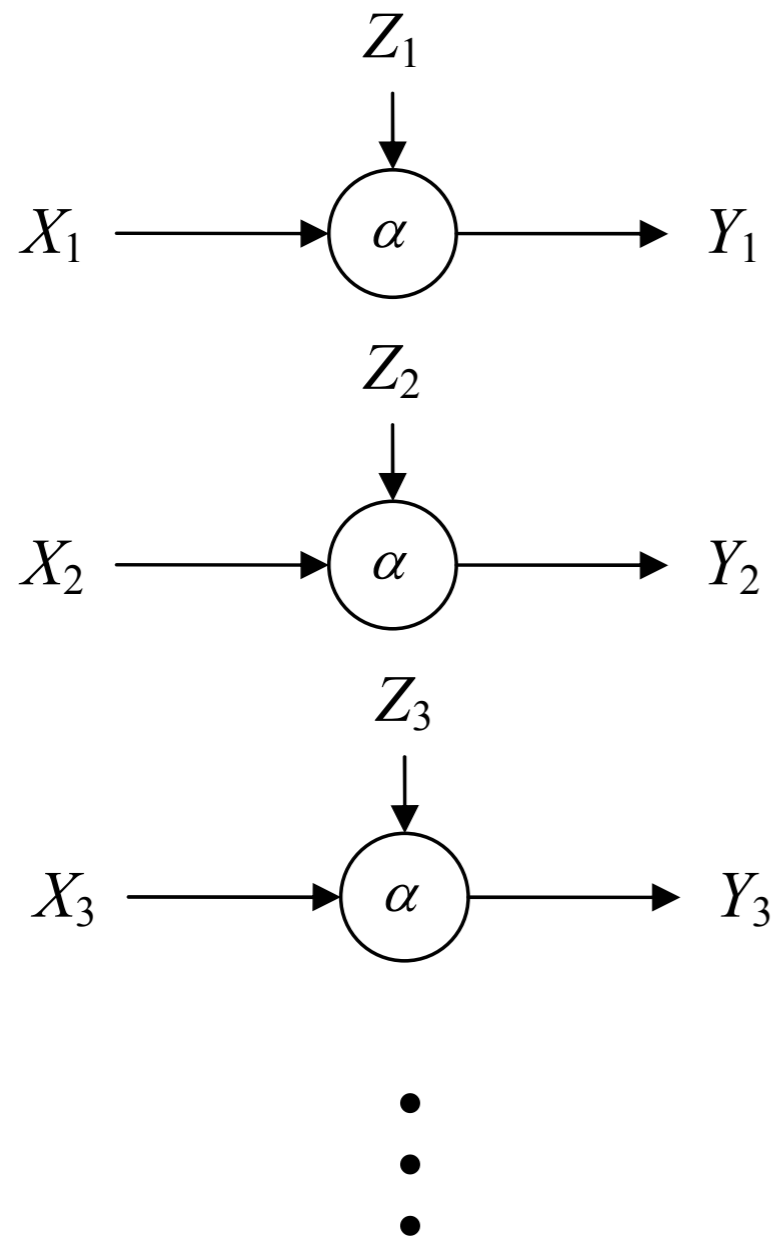
$$\Pr\{Y_i = y, X_i = x, T_{i-} = t\} = \Pr\{X_i = x, T_{i-} = t\}p(y|x)$$

holds for all $(x, y, t) \in \mathcal{X} \times \mathcal{Y} \times \mathcal{T}_{i-}$.

Definition 7.5 (DMC II)

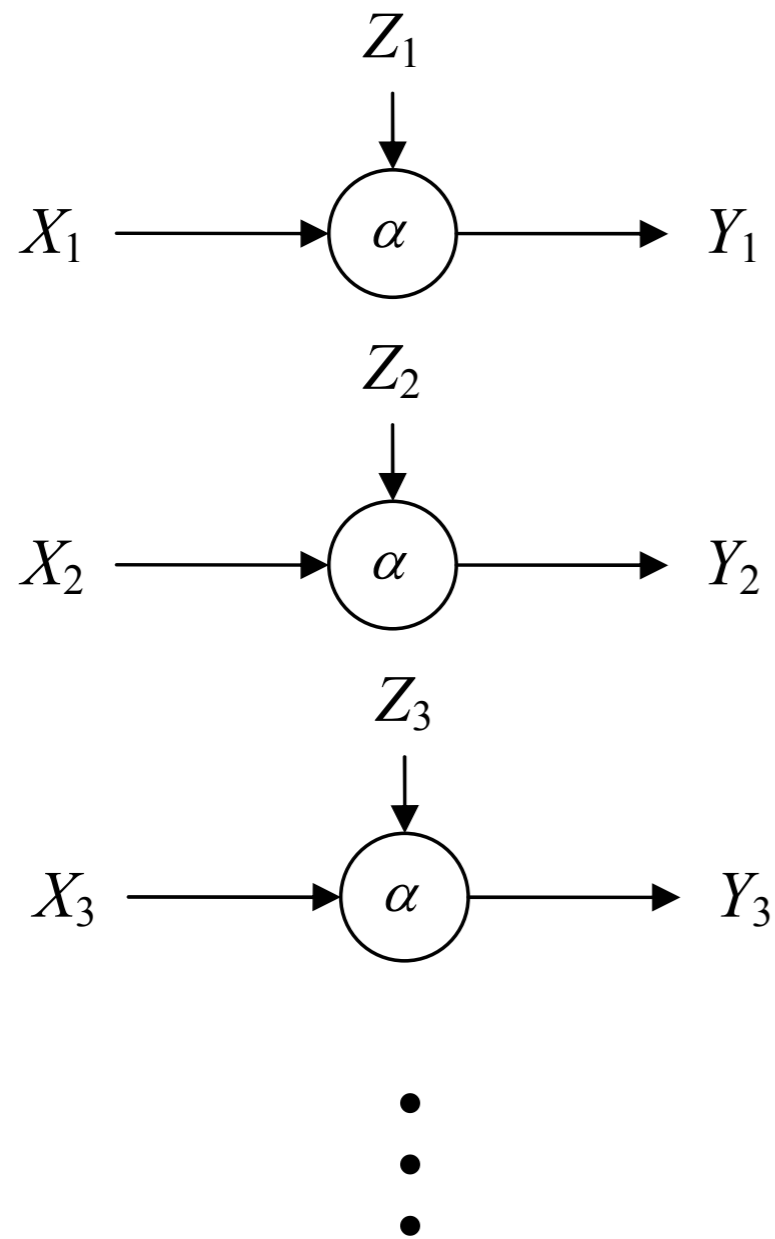


Definition 7.5 (DMC II)



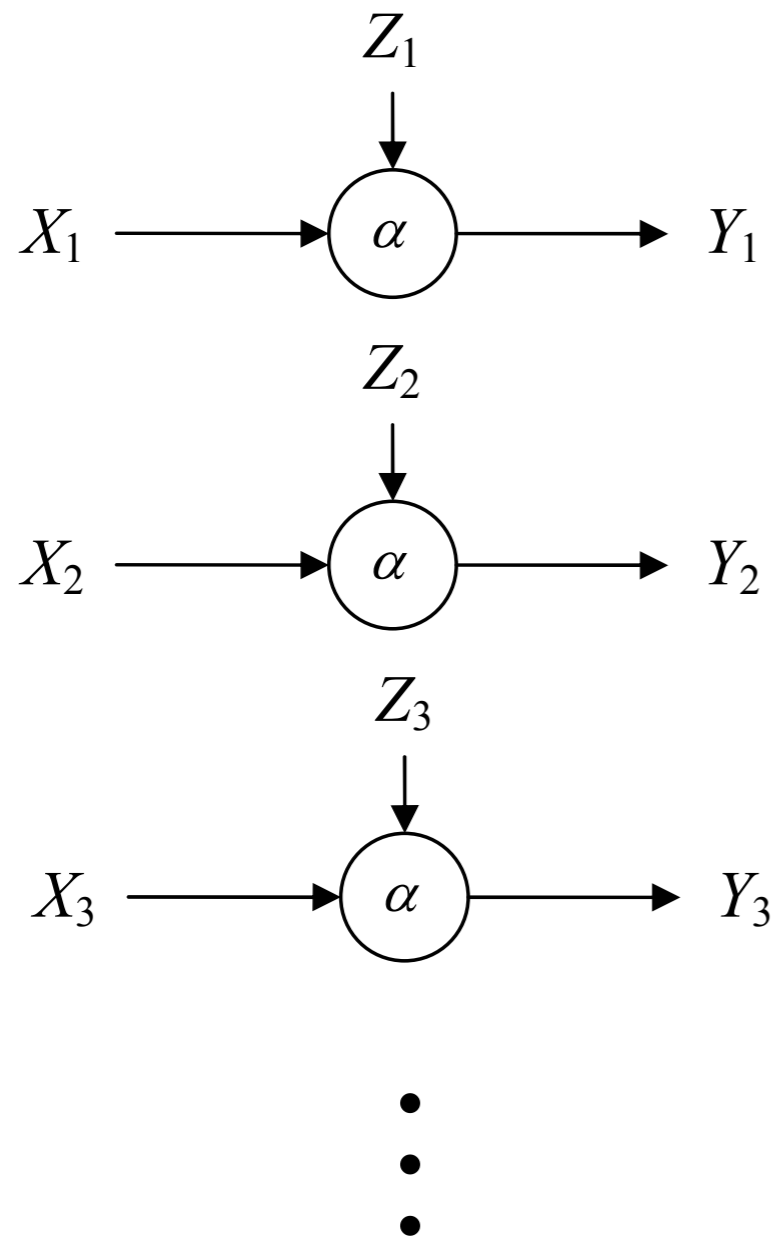
- A DMC specified by (α, Z) is a sequence of replicates of a **generic discrete channel** (α, Z) .

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- A DMC specified by (α, Z) is a sequence of replicates of a **generic discrete channel** (α, Z) .
- Z_i is the noise variable for transmission at time i , and has the same distribution as Z .

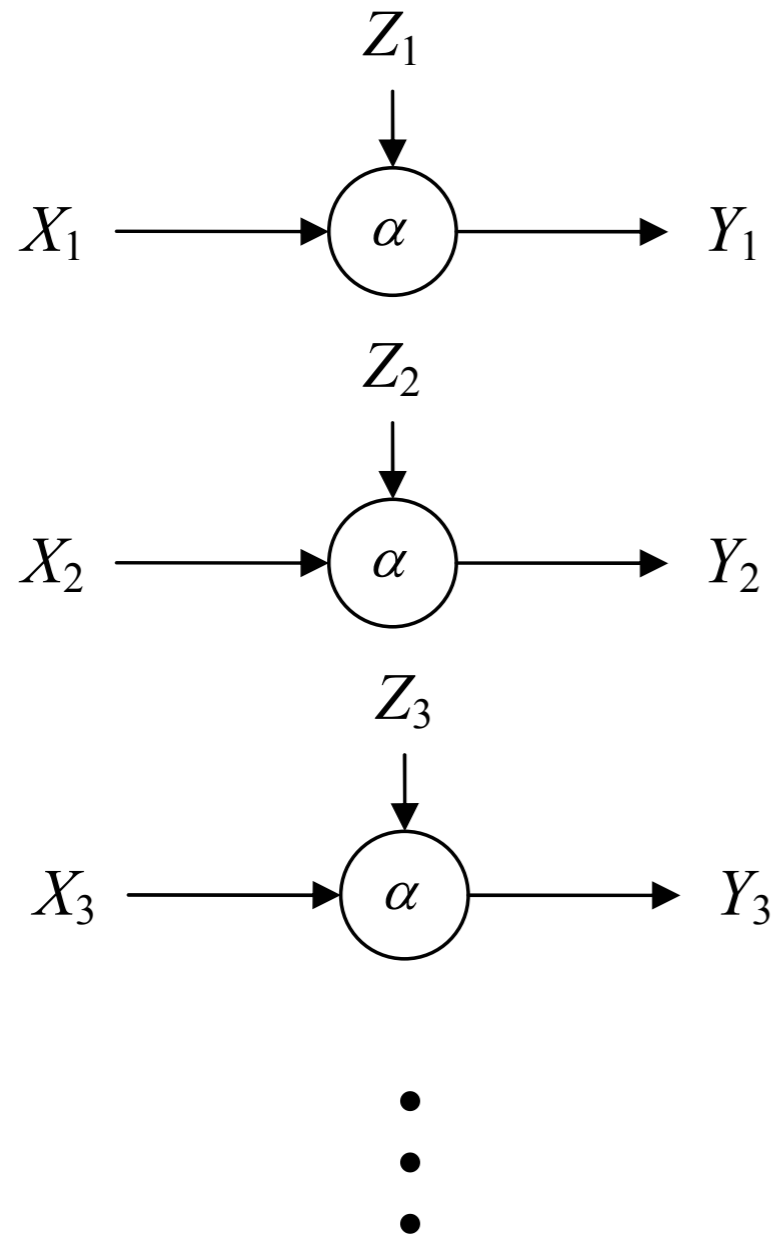
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The noise for transmission at time i is independent of both X_i and everything in the past.

Definition 7.5 (DMC II) A discrete memoryless channel (α, Z) is a sequence of replicates of a generic discrete channel (α, Z) . These discrete channels are indexed by a discrete-time index i , where $i \geq 1$, with the i th channel being available for transmission at time i . Transmission through a channel is assumed to be instantaneous. Let X_i and Y_i be respectively the input and the output of the DMC at time i , and let T_{i-} denote all the random variables that are generated in the system before X_i . The noise variable Z_i for the transmission at time i is a copy of the generic noise variable Z , and is independent of (X_i, T_{i-}) . The output of the DMC at time i is given by

$$Y_i = \alpha(X_i, Z_i).$$

Remark: The equivalence of Definitions 7.4 and 7.5 can be shown. See textbook.

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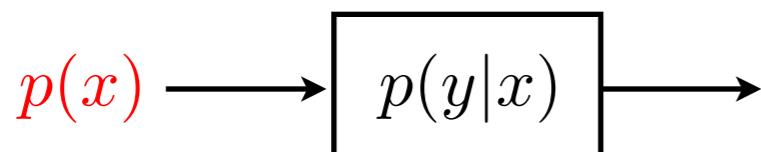
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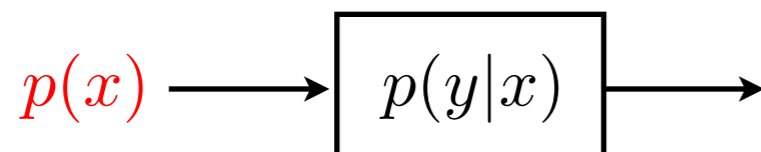


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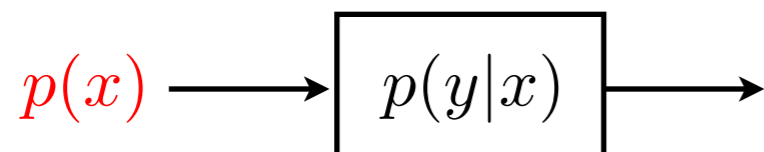
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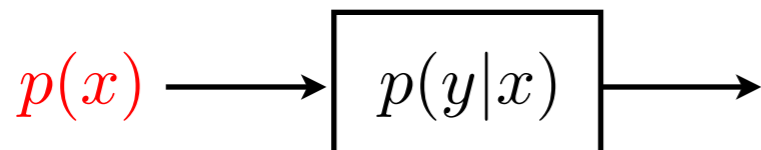
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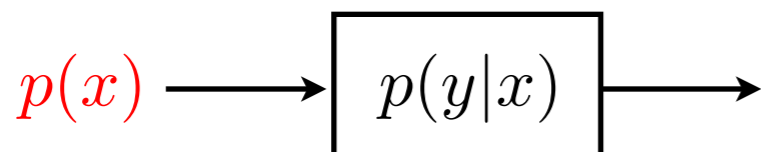


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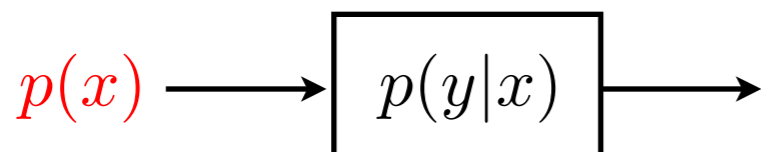
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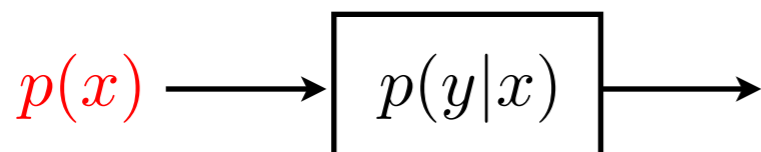
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- Since $I(X; Y)$ is a continuous functional of $p(x)$ and the set of all $p(x)$ is a compact set (i.e., closed and bounded) in $\mathfrak{R}^{|\mathcal{X}|}$, the maximum value of $I(X; Y)$ can be attained.

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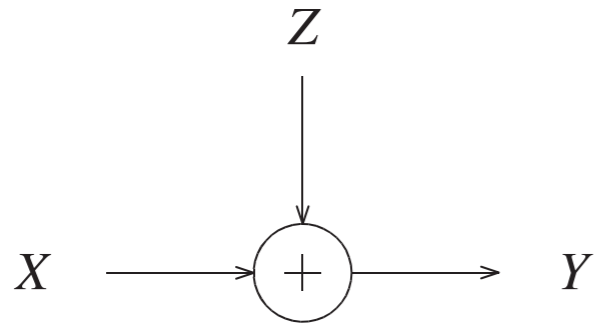
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- Will see that C is in fact the maximum rate at which information can be communicated reliably through a DMC.
- Can communicate through a channel at a positive rate while $P_e \rightarrow 0!$

Example 7.7 (BSC)



Alternative representation of a BSC with crossover probability ϵ :

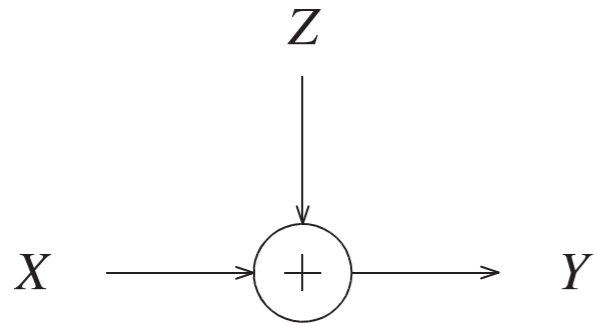
$$Y = X + Z \text{ mod } 2$$

with

$$\Pr\{Z = 0\} = 1 - \epsilon \quad \text{and} \quad \Pr\{Z = 1\} = \epsilon$$

and Z is independent of X .

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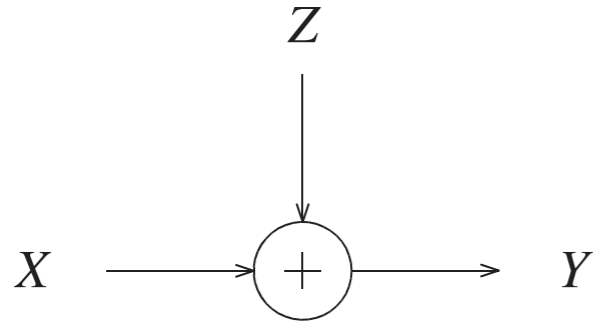
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Determination of C



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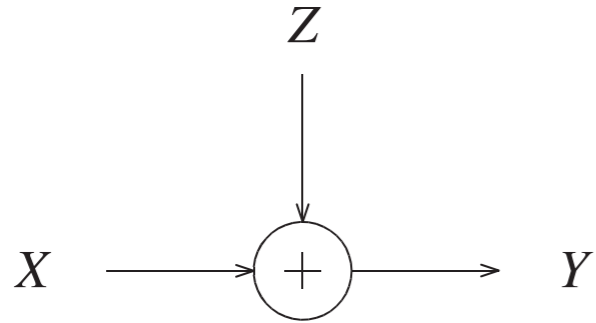
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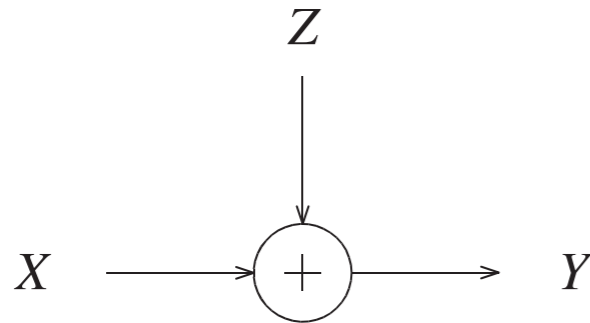
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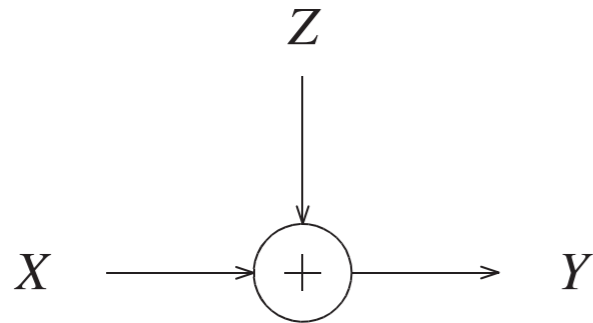
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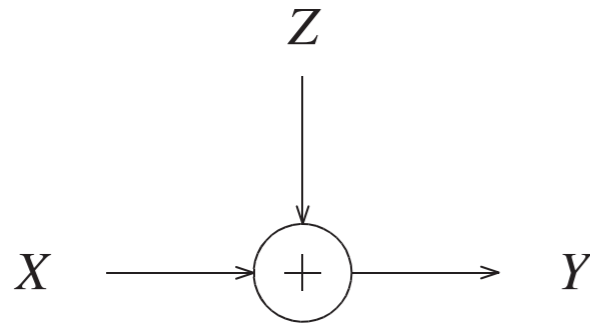
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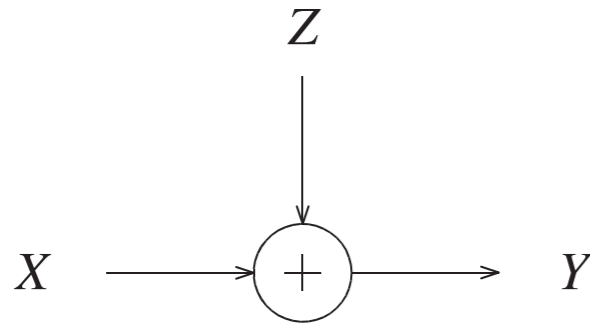
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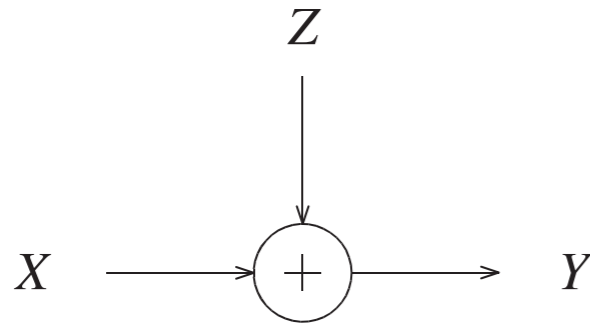
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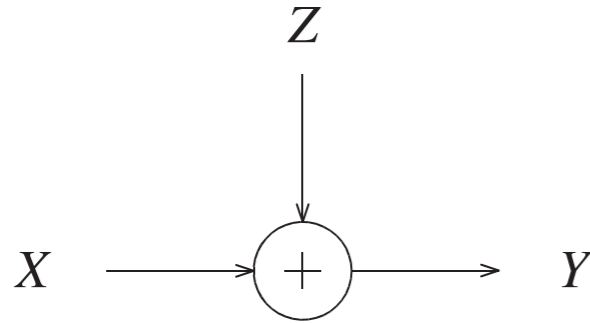
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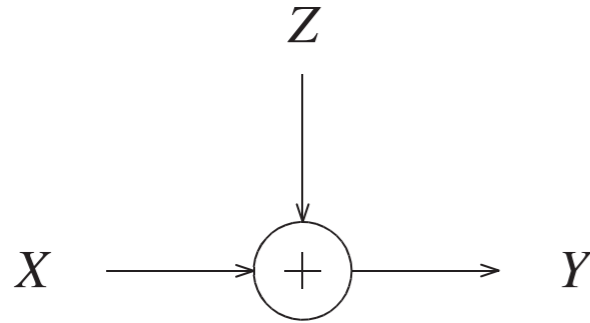
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2. So,

$$C = \max_{p(x)} I(X; Y) \leq 1 - h_b(\epsilon).$$

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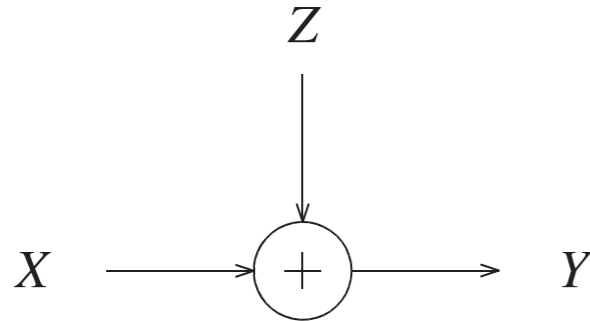
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3. The upper bound on $I(X; Y)$ is tight if

$$H(Y) = 1.$$

This can be achieved by taking the uniform input distribution.

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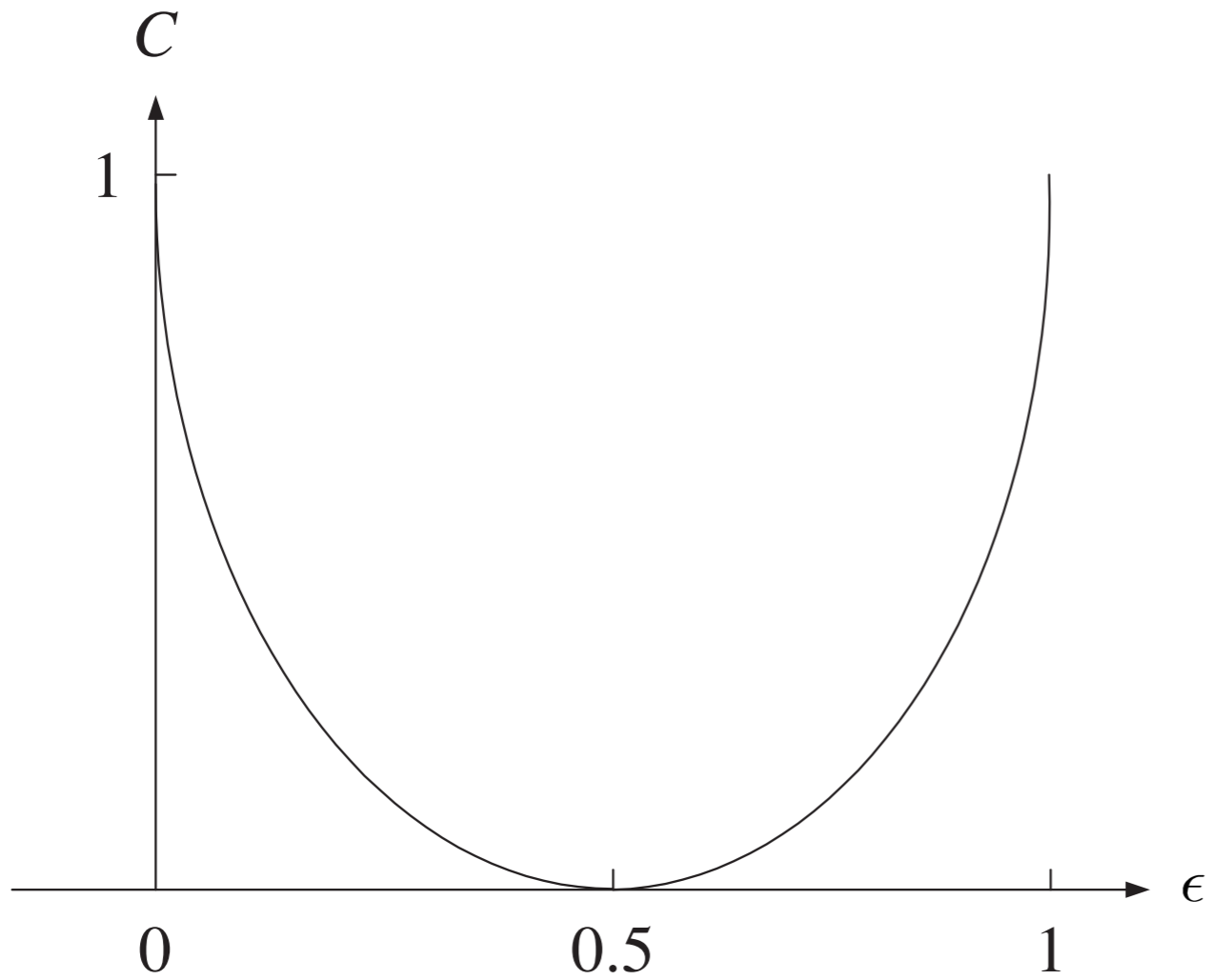
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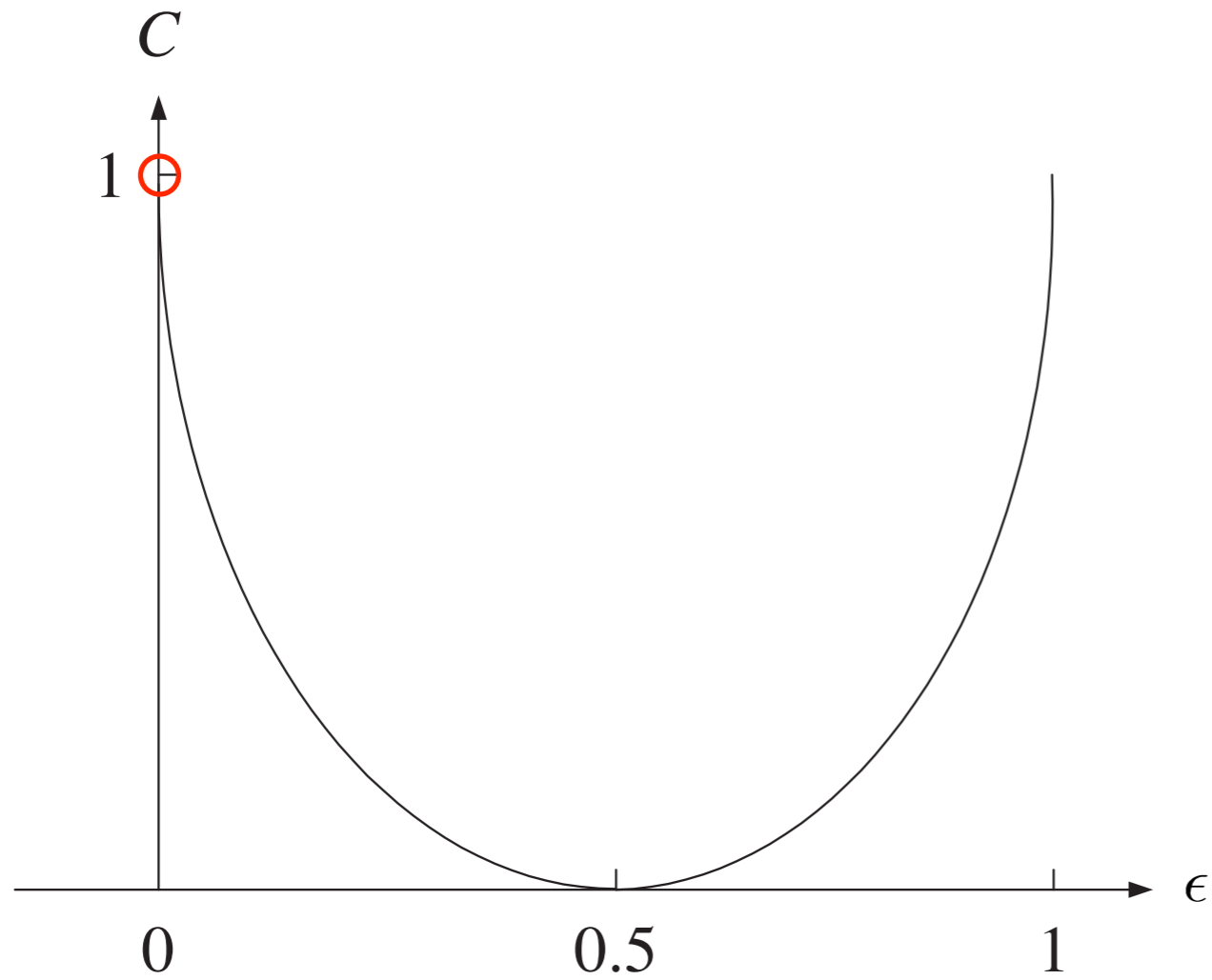
This can be achieved by taking the uniform input distribution.

4. Therefore, $C = 1 - h_b(\epsilon)$ bit per use.

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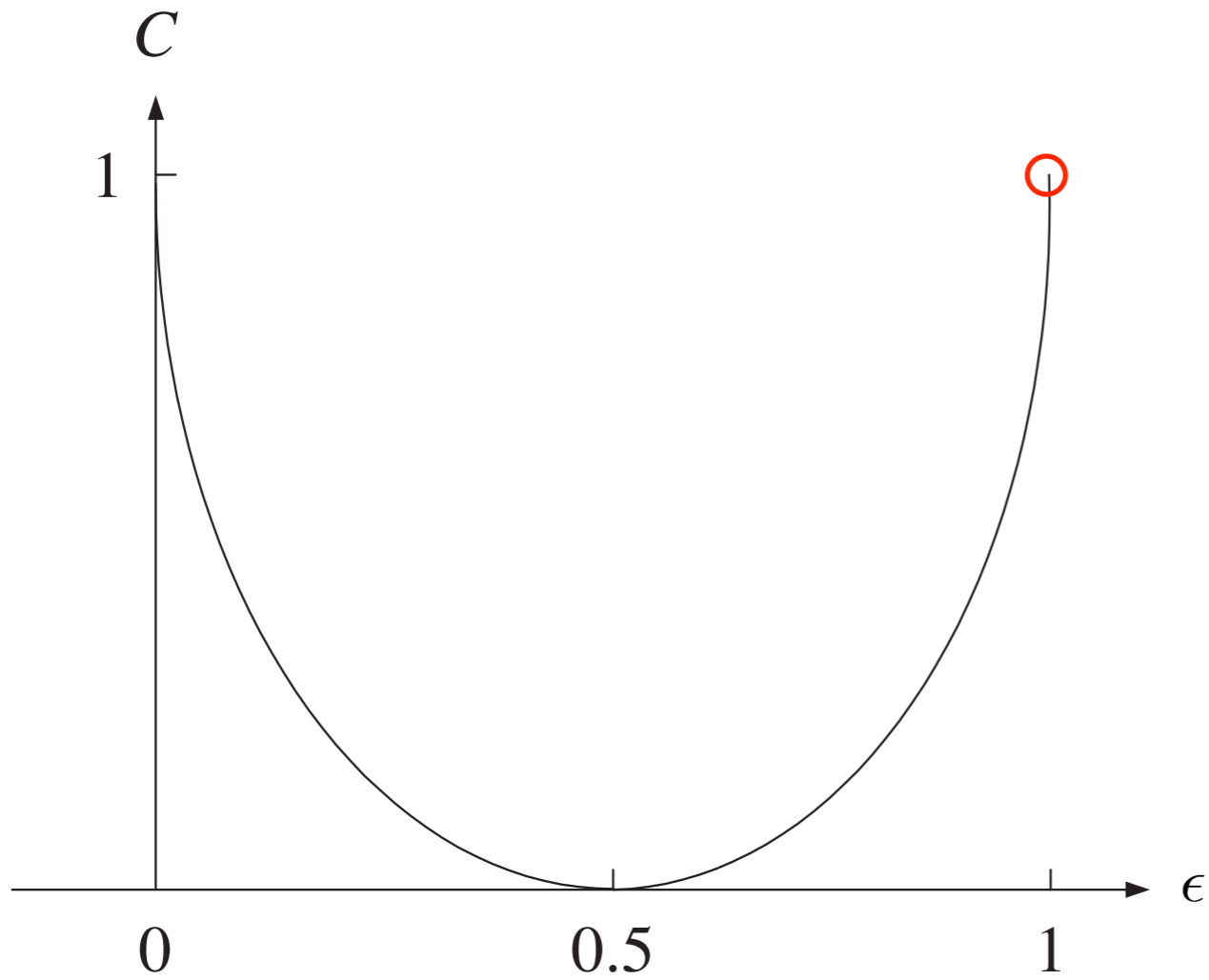


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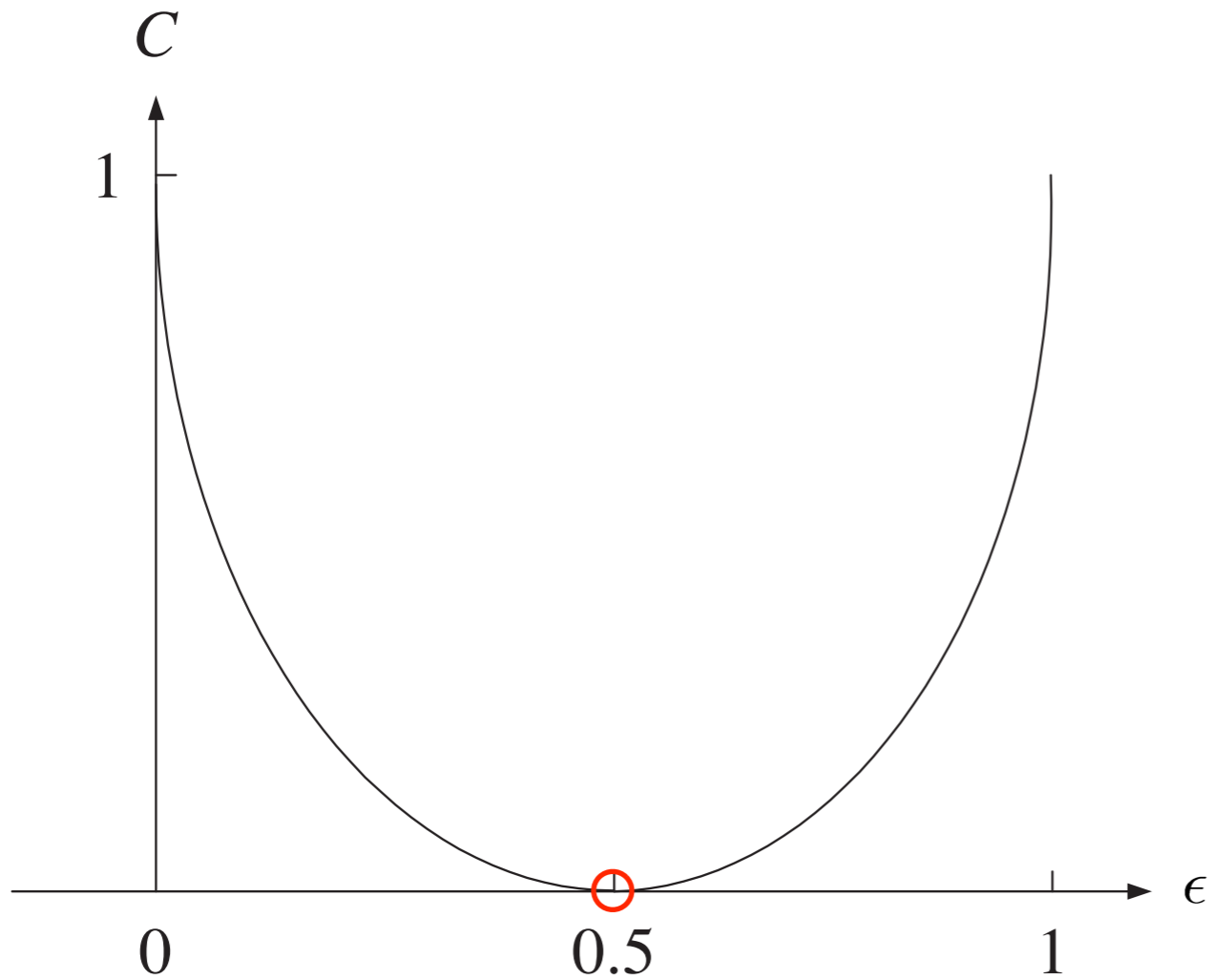
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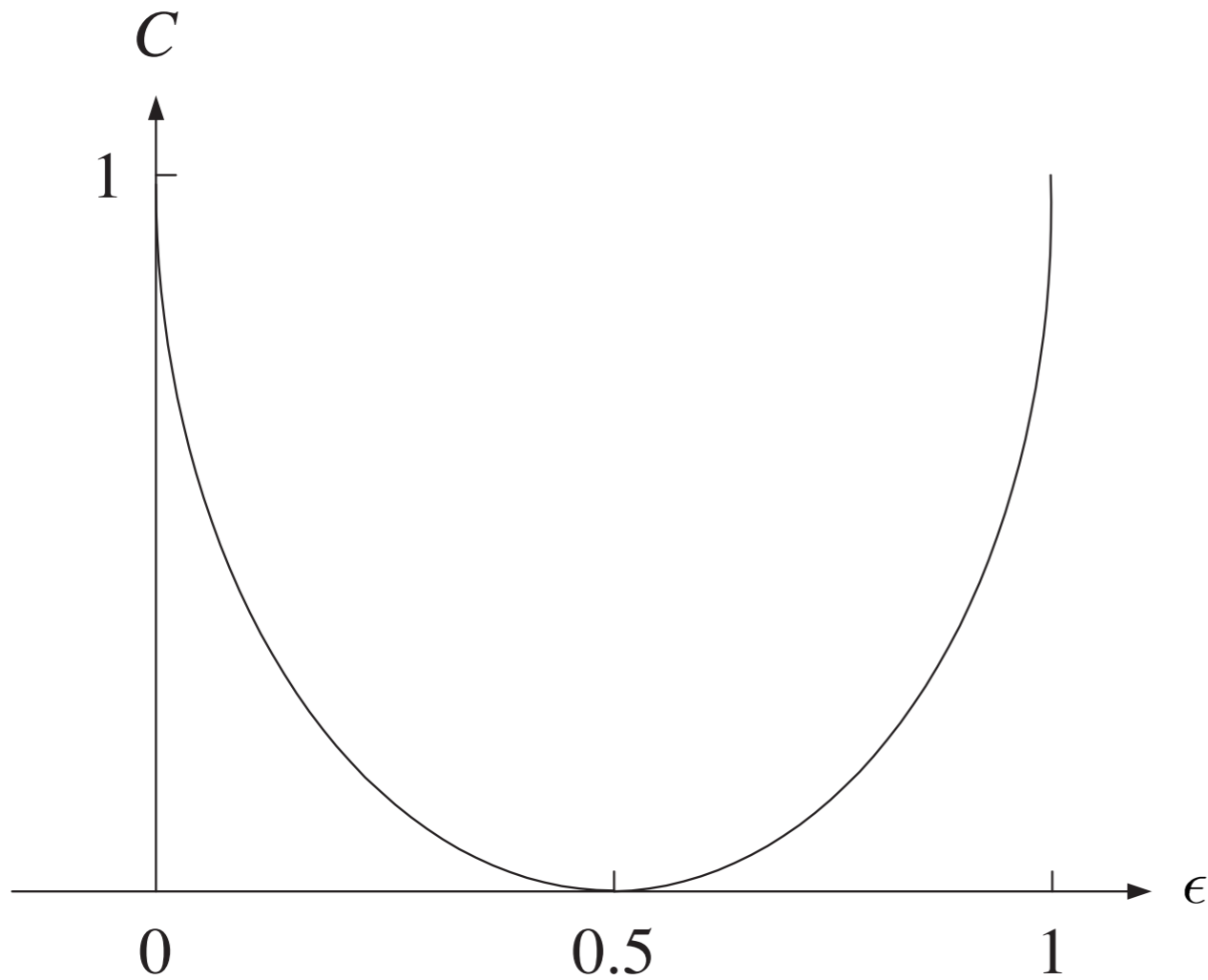
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- $C(0.5) = 0$

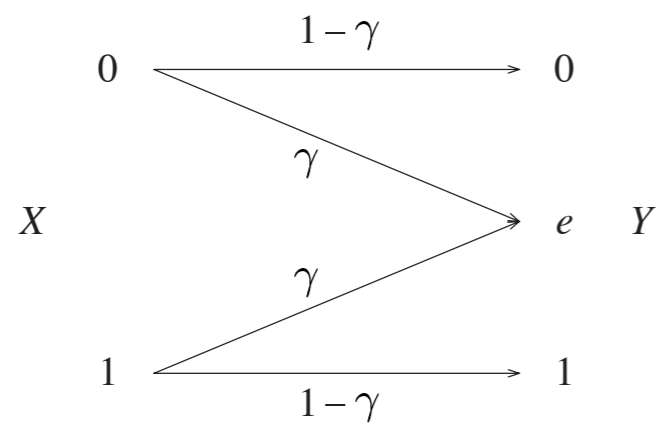
$$C(\epsilon) = 1 - h_b(\epsilon)$$



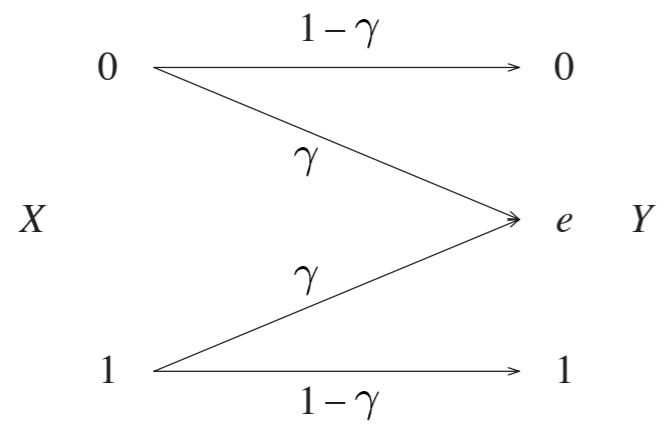
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Exercise: Show that X and Y are always independent for $\epsilon = 0.5$.

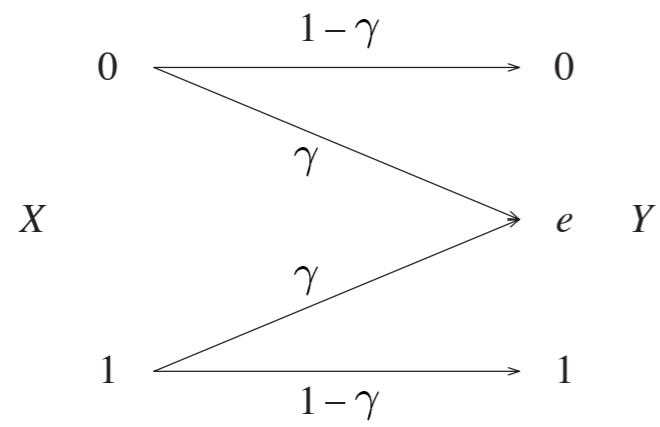
Example 7.8 (Binary Erasure Channel)



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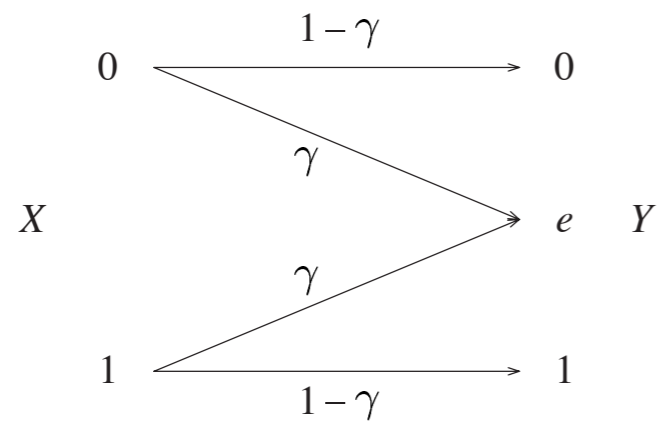


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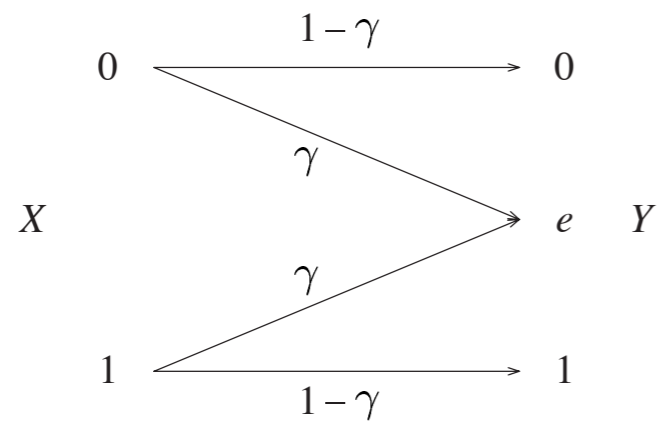
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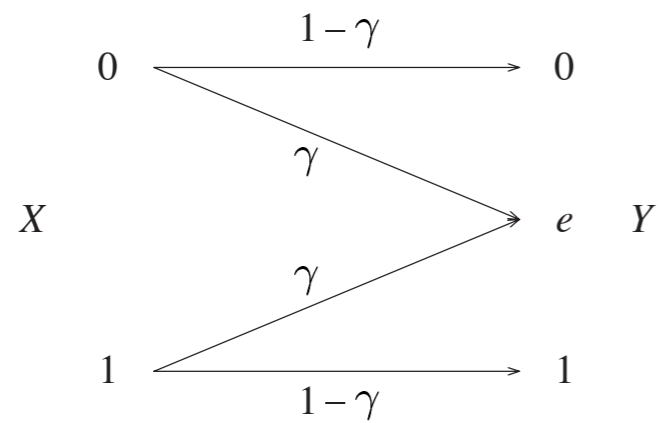
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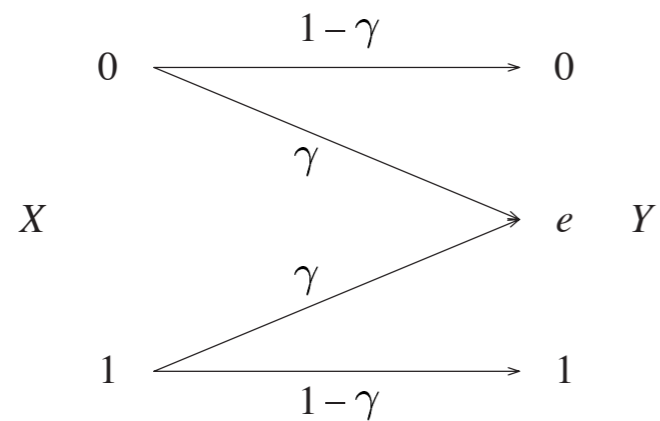
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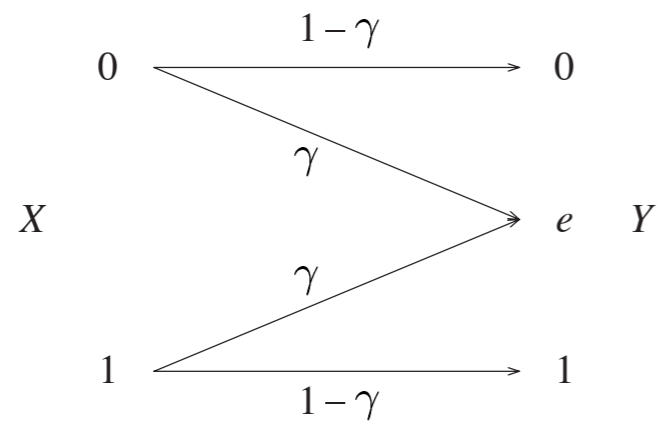
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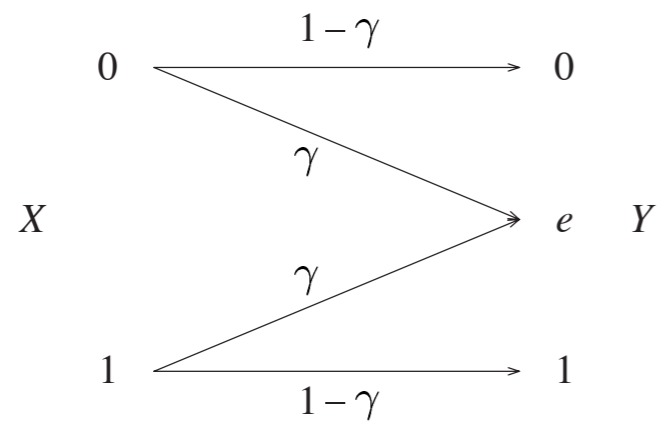
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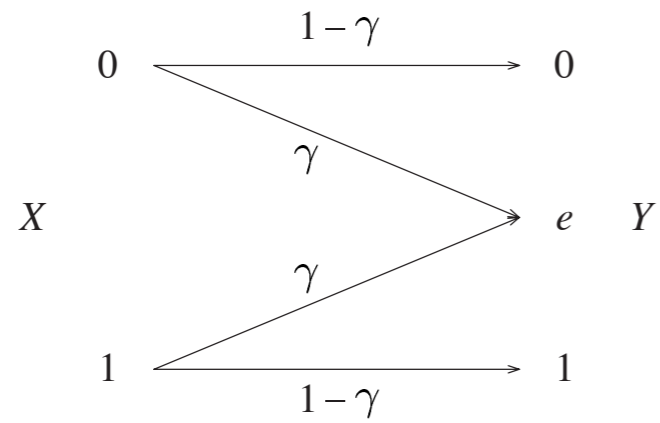
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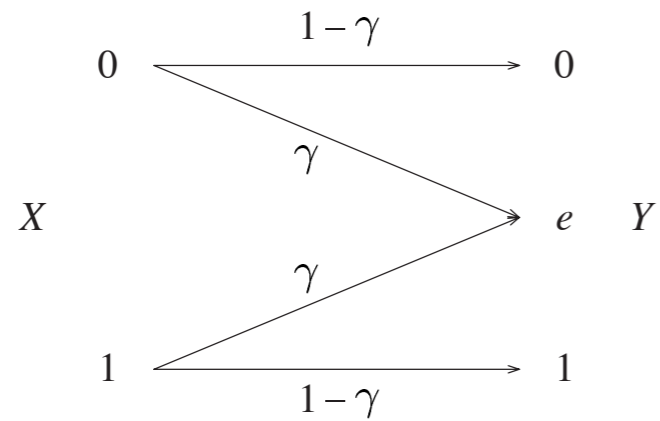


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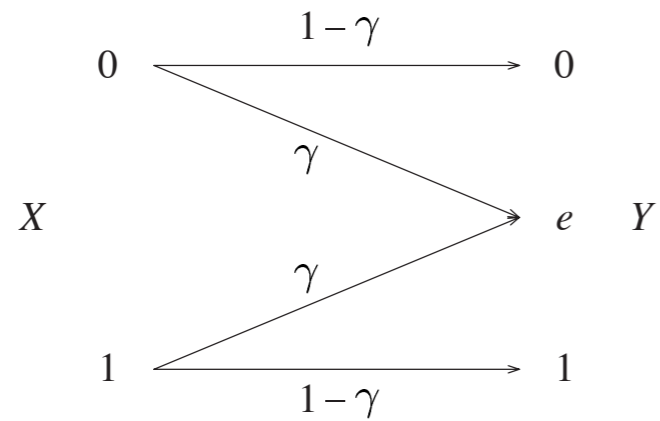
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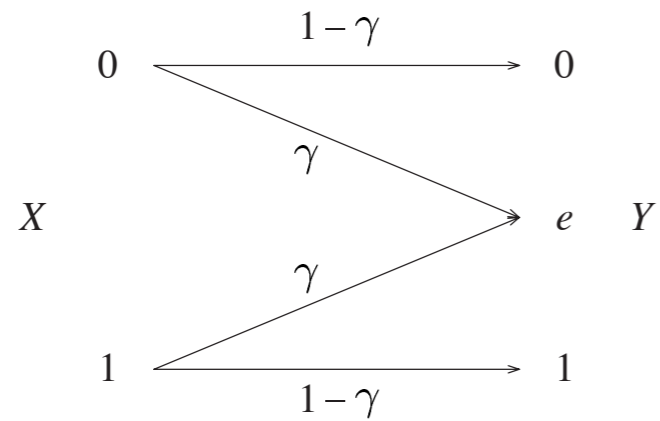
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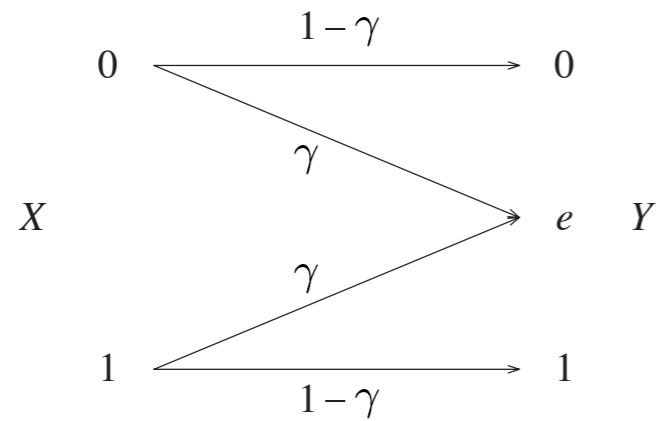
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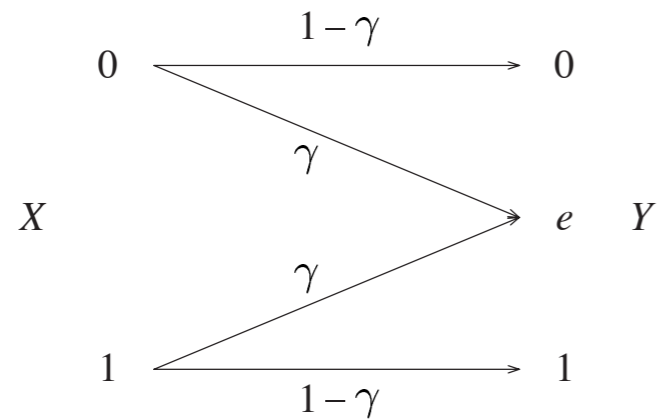
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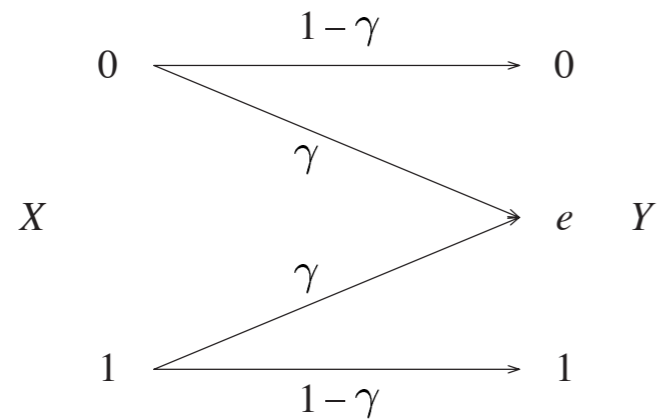
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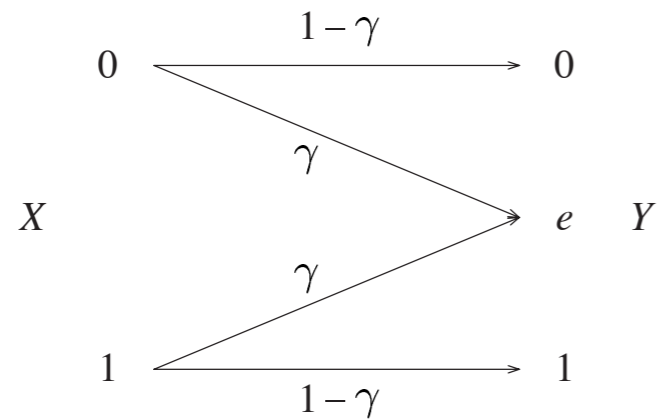
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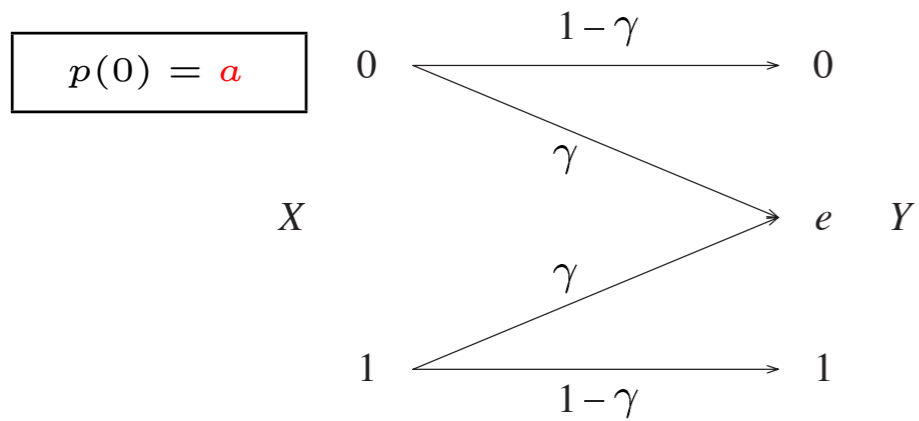
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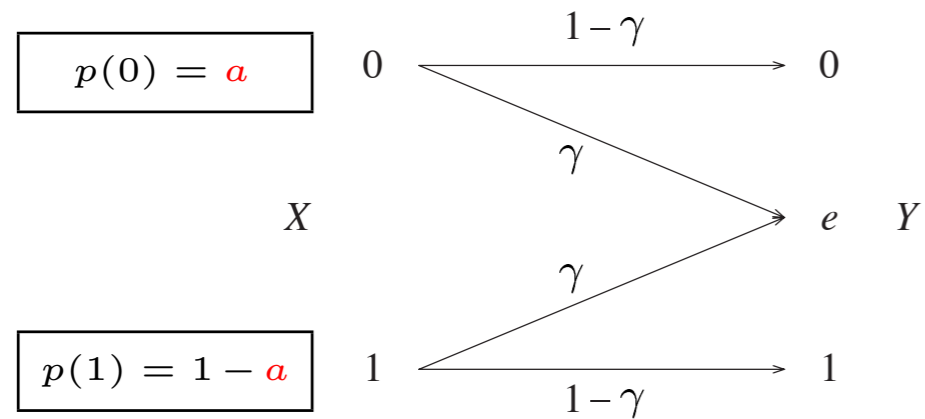
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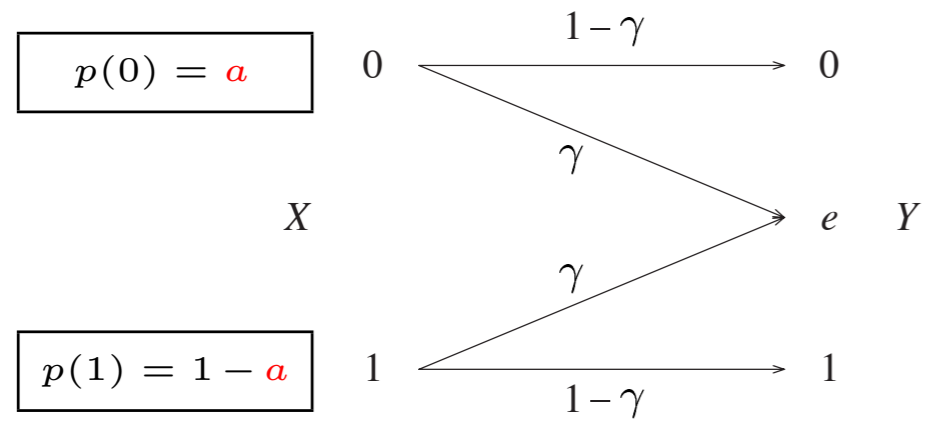
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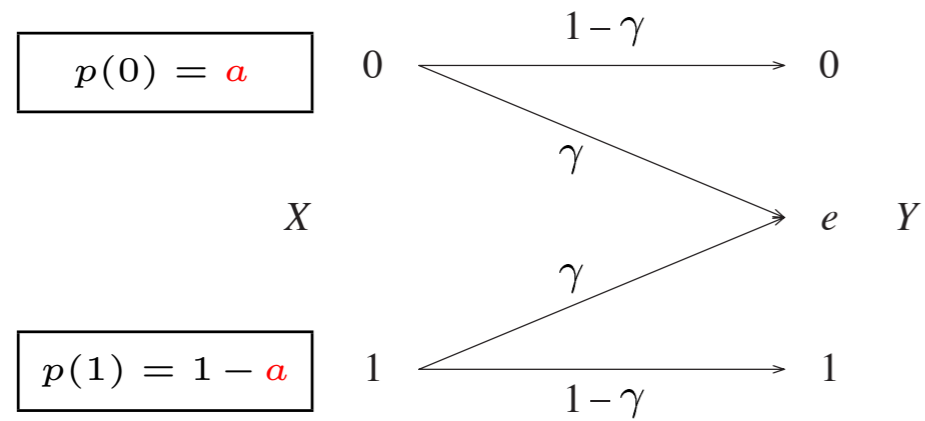
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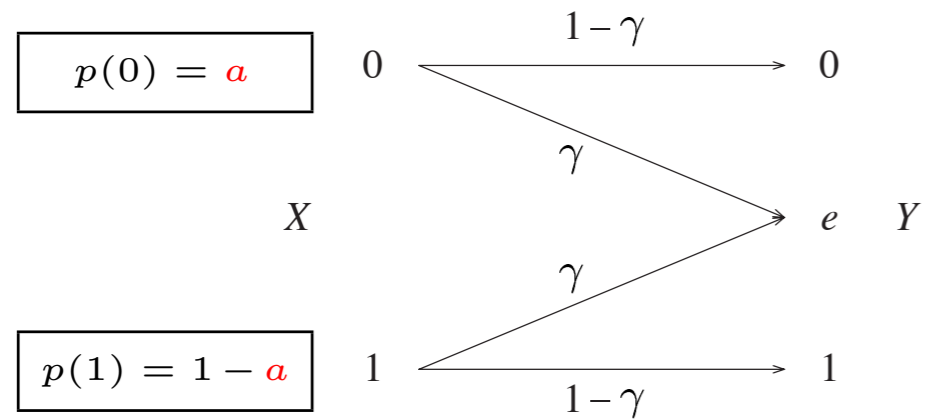
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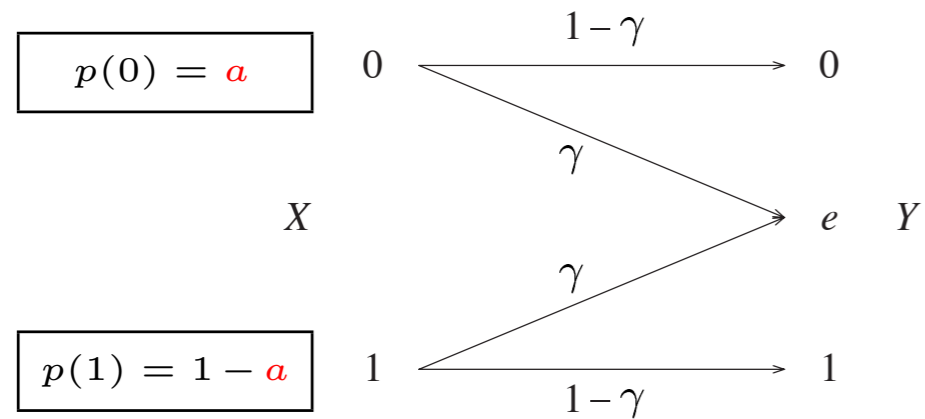
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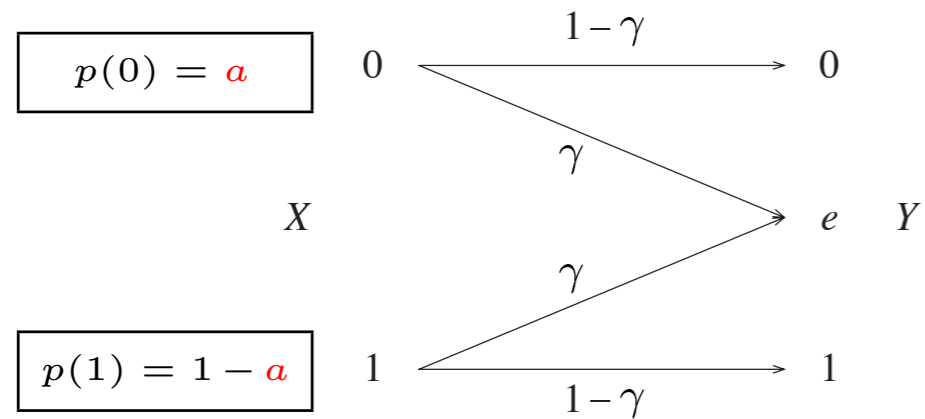
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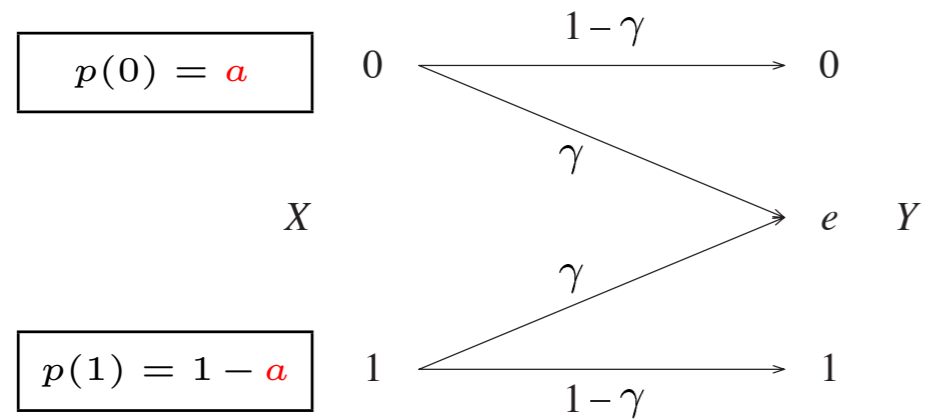
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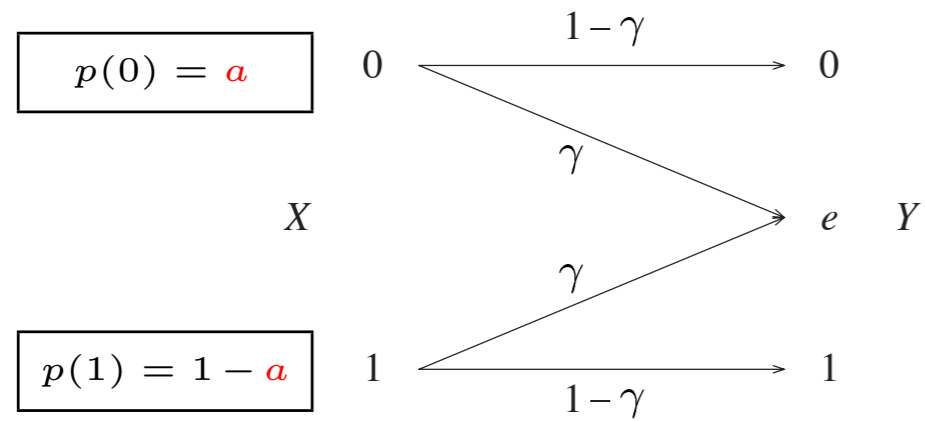
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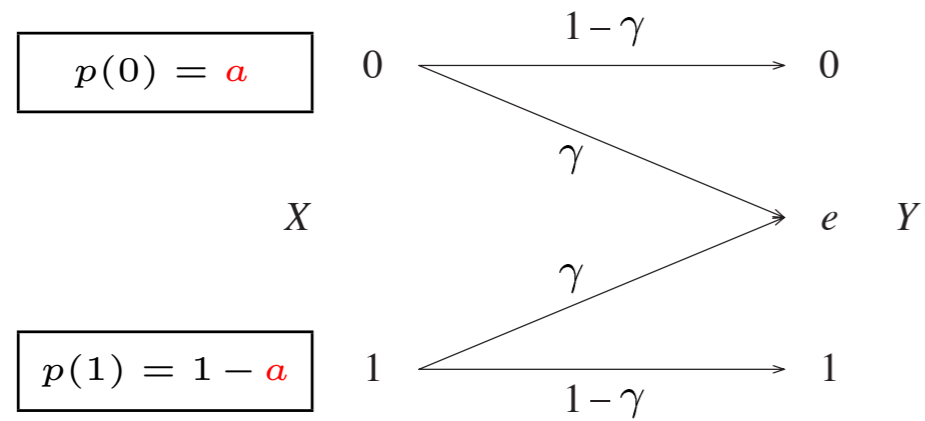
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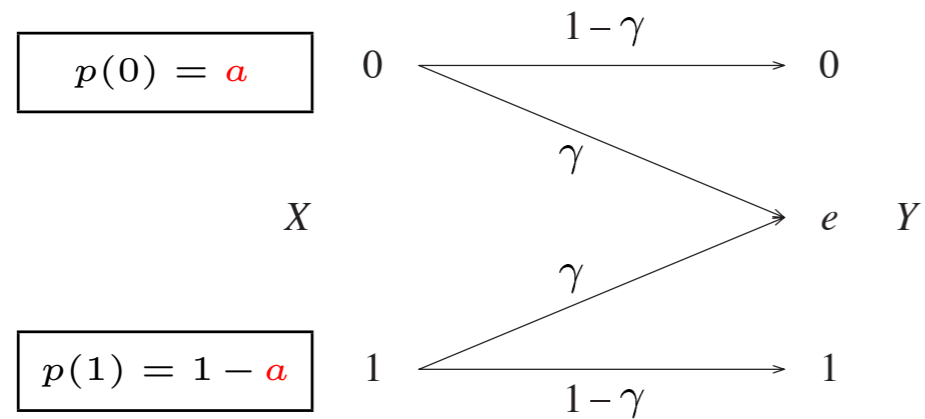
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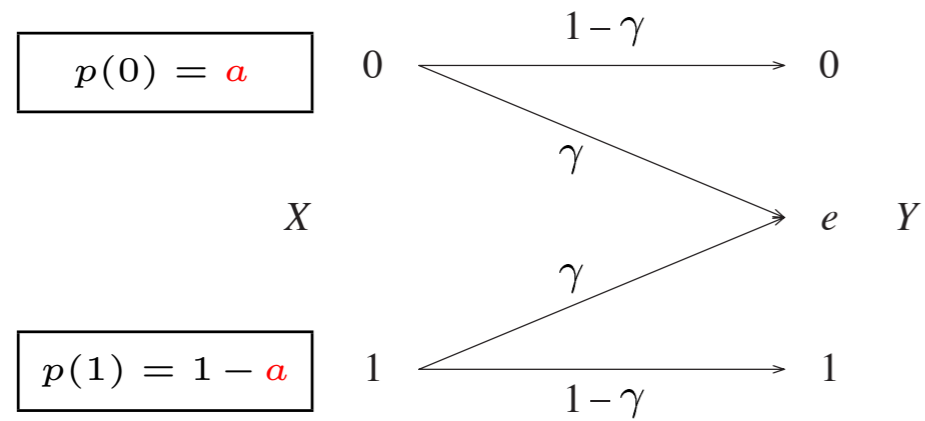
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- The output symbol e denotes “erasure”.
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 &= \max_{p(x)} H(Y) - h_b(\gamma).
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Thus we only have to maximize $H(Y)$ over all $p(x)$.

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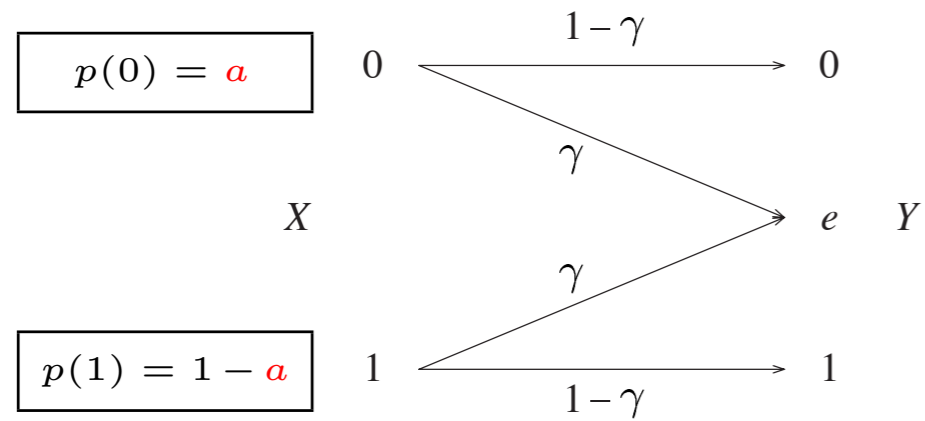
$$E = \begin{cases} 0 & \text{if } Y \neq e \\ 1 & \text{if } Y = e. \end{cases}$$

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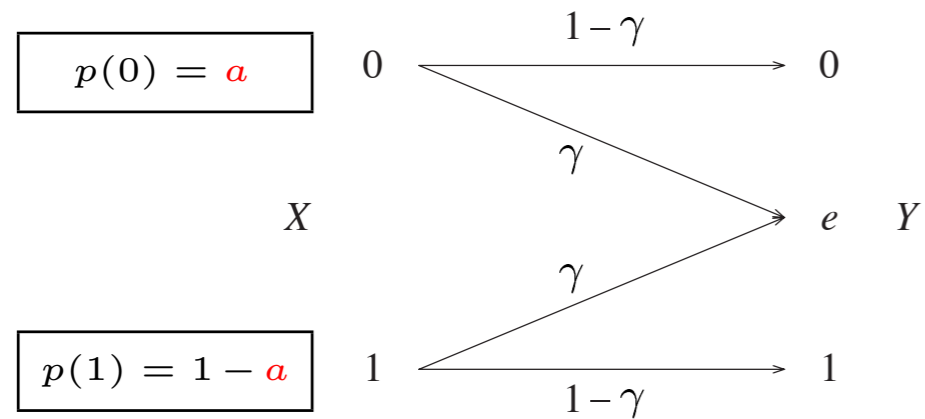
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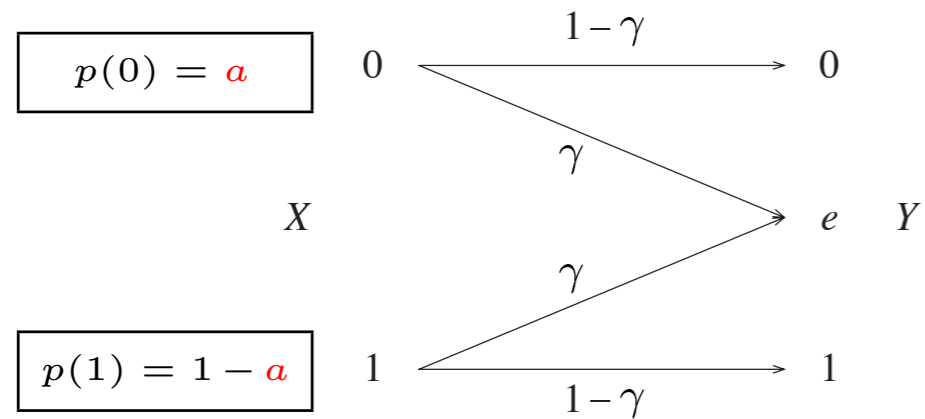
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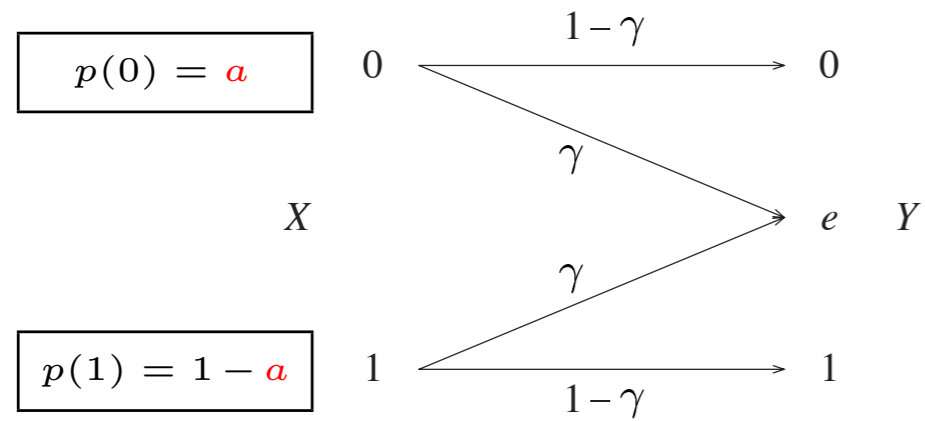
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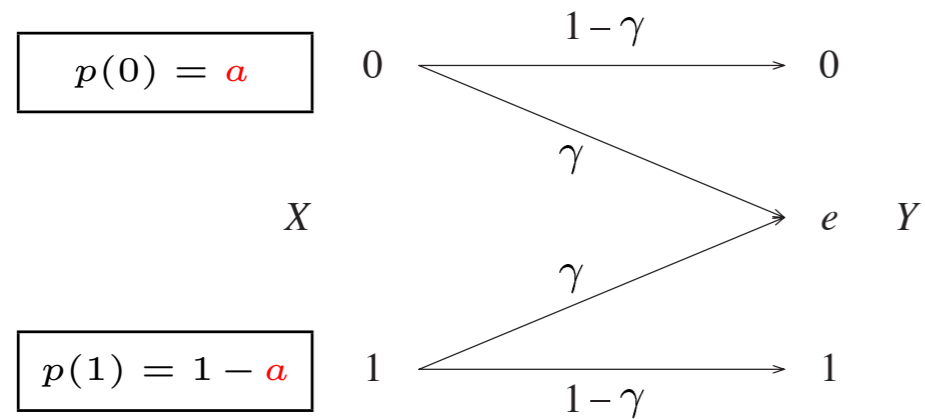
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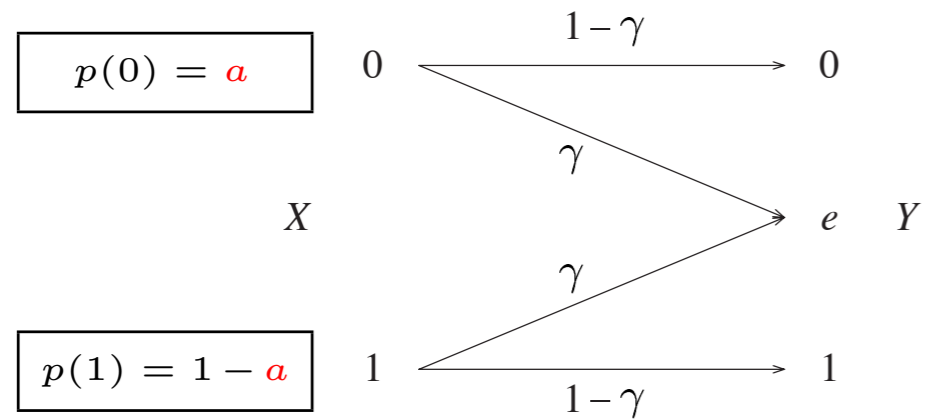
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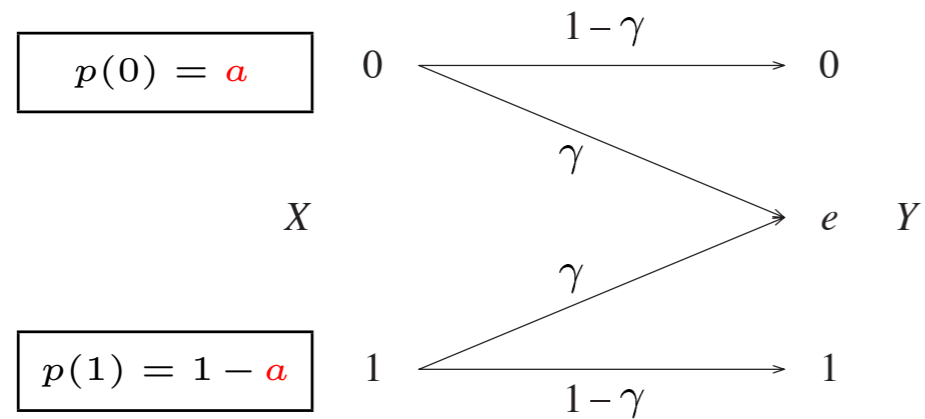
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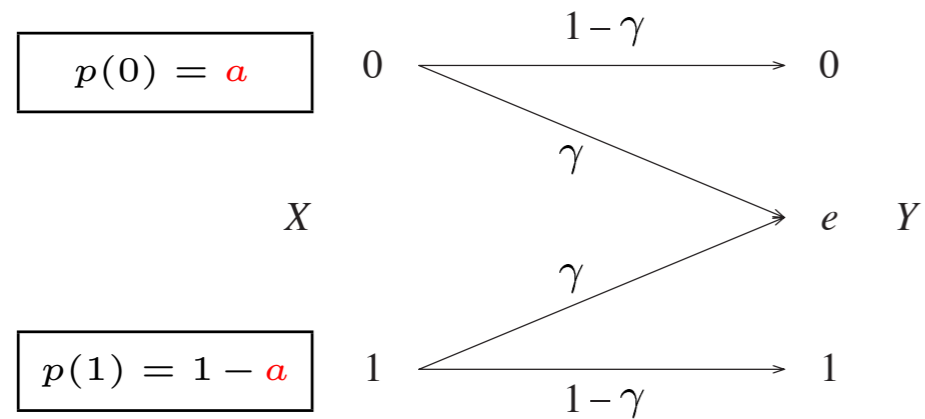
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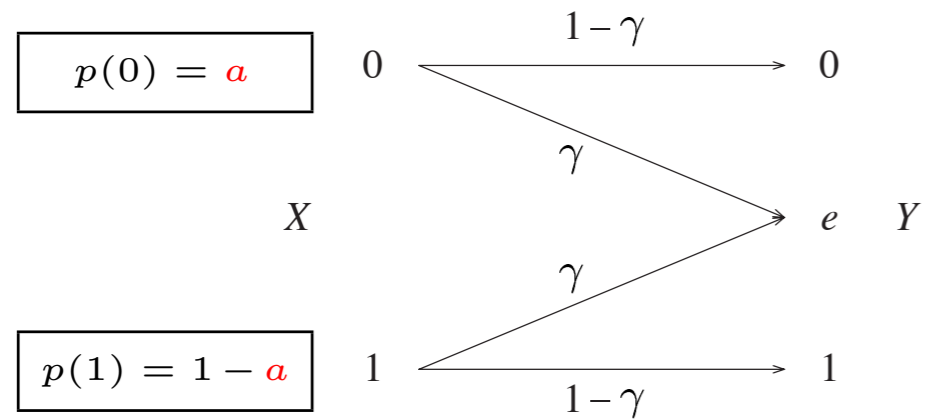
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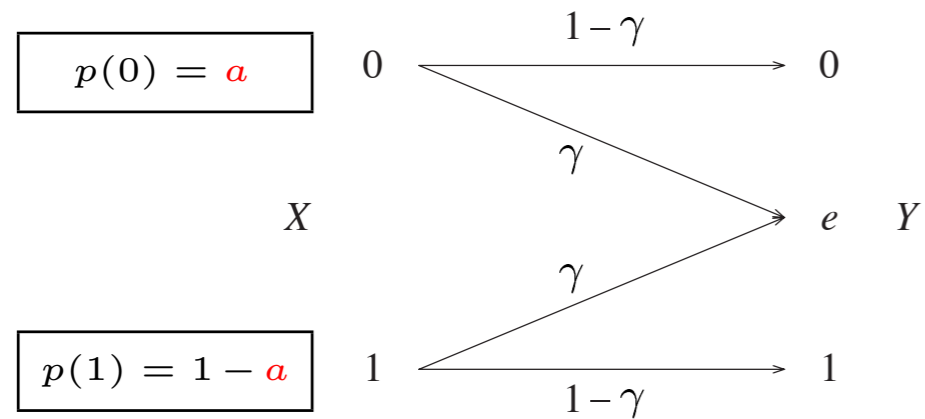
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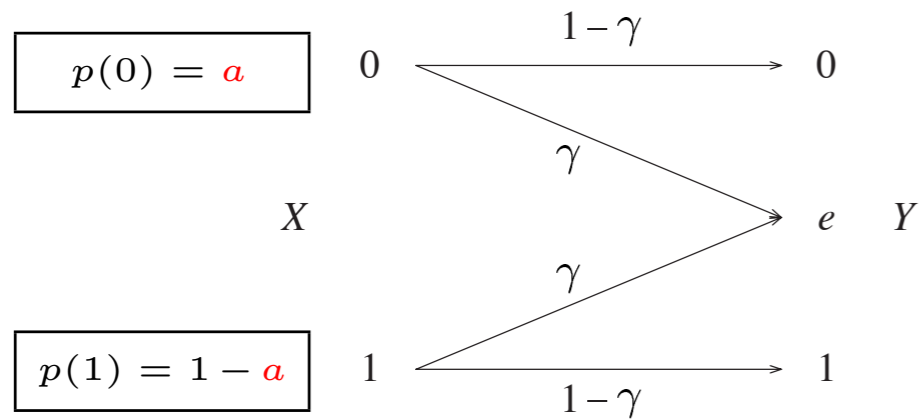
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