

Load Balancing between Computing Clusters

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Abstract

Increasing number of organizations have computing clusters located in different places. The distance between the computing clusters can be quite far apart. The load in one cluster may be very high while the other clusters may have nothing running on the system. A higher throughput can be achieved if load balancing is added between the clusters. In this paper, we proposed a simple and efficient load balancing method to balance loads between computing clusters that are far part from each other.

Keywords: Load balancing, Computing Clusters, Hypercube.

1 Introduction

In a computing cluster, time critical tasks can be executed quickly by splitting a task into sub-tasks. The sub-tasks are then executed in parallel in different processing nodes of a computing cluster. To maximize the benefit of computing cluster, the tasks assigned to each processing node should be roughly the same. Hence, load balancing is necessary to balance loads between the processing nodes within a computing cluster. However, if an organization has more than one computing cluster and they are located in different places, we also need to balance the load between the computing clusters to improve throughput.

An example of such organization is Sharcnet. Sharcnet is a partnership between a number of universities and

colleges in Canada. All the members of Sharcnet are located in southwestern Ontario. Currently, Sharcnet has five members with computing clusters. Two or more computing clusters are deployed at each of the following locations: the University of Guelph, McMaster University, and the University of Western Ontario. One computing cluster is deployed at the University of Windsor and one is deployed at Wilfrid Laurier University. Depending on funding from the government, more computing clusters will be added to current member sites and to other universities such as the University of Waterloo, Brock University, and Trent University in the region.

The computing clusters within Sharcnet are quite far away from each other and not all of them are connected through dedicated fibre optic lines. For example, the distance between Wilfrid Laurier University and University of Western Ontario is almost one hundred kilometers and there is no dedicated communication line between the two locations. Hence, the load balancing method to balance the load between computing clusters should have as few communications as possible.

In this paper, we address the problem of load imbalance in computing clusters. We assume that the job scheduler of each computing cluster is connected as a node of a hypercube. By assuming that the clusters are connected as a hypercube, we can group clusters that are connected directly through high-speed link in the same sub cube to take advantage of their connections. Furthermore, we can also make use of the topology of a hypercube to reduce the amount of communications during load balancing.

A n -dimensional hypercube is a network with $N = 2^n$

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nodes. Each node can be coded by a binary sequence of length n . Two nodes are connected if their binary sequences differ in exactly one position. Each node $v = v_1v_2\dots v_n$ is connected to n nodes. Node v is connected to node $u = u_1u_2\dots u_n$ if $v_i \neq u_i$ and $v_j = u_j$ for $j \in 1..n$ and $j \neq i$. The link between v and u is also called the link of dimension i .

2 Previously proposed load balancing schemes for hypercubes

If we can estimate the execution time of any task accurately and we also know the total number of tasks in advance, we can use a static load balancing method to assign balanced load to each of the processing nodes. Load balancing is not necessary. Unfortunately, there exists a large class of non-uniform problems with uneven and unpredictable computation and communication requirement. For these problems, we have to deal with the load imbalance dynamically.

Many load-balancing algorithms for hypercube have been proposed. They fall into two types: Synchronous load balancing and asynchronous load balancing. Synchronous load balancing [2, 3] is one in which the balancing is done on a global synchronous manner. Asynchronous load balancing [4, 5] is one in which each processing node can initiate the load balancing at any given time.

Two examples of asynchronous load balancing is Receiver initiated diffusion (RID) and Sender initiated diffusion (SID) [4, 5]. In RID, an under loaded node requests extra task from overloaded nodes. In SID, an overloaded node tries to find an under loaded node and transfers some of its tasks to the under loaded node.

Willebeek-Lamair and Reeves [2] showed that RID always outperforms SID. In RID, when the load of an under loaded node drops below a predetermined value, the under loaded node starts to send load balancing requests to its neighbors. Its neighbors then send their current load information to the under loaded node. Based on the load information of its neighbors, the under loaded node calculates the task that each of its neighbors has to send to it.

Cybenko [1] showed that the diffusion methods are inferior to the dimension exchange method in terms of their efficiencies and balance qualities. For the dimension exchange method (DEM) [7, 1, 2], all node pairs whose addresses differ only in the least significant bit balance their load between themselves. Next, all node pairs whose addresses differ in only the second least significant bit balance the load between themselves. The above process is repeated until each node has exchanged and balanced its

load with its neighbors in all the dimensions. After execution of the DEM, the load difference between any pair of nodes is at most n .

The number of communication steps in the DEM is $3n$. Let w_u be the number of tasks in node u and \oplus be the bitwise exclusive OR operator. Figure 1 shows the DEM algorithm for a hypercube.

DEM

for $k = 0$ to $n - 1$

node u exchange with node v the current value of w_u

and w_v , where $(u \oplus v) \oplus 2^k = 0$

if $(w_u - w_v) > 1$, send $\lfloor (w_u - w_v)/2 \rfloor$ tasks to node v

if $(w_v - w_u) > 1$, receive $\lfloor (w_v - w_u)/2 \rfloor$ tasks from node v

$w_u = \lceil (w_u + w_v)/2 \rceil$ if $w_u > w_v$

$w_u = \lfloor (w_u + w_v)/2 \rfloor$ otherwise

Figure 1: The DEM algorithm for hypercubes.

The cube walking algorithm (CWA)[3] can balance the load better than the DEM. After applying the CWA to a hypercube, the load difference between any nodes is at most one. The load difference is optimal because a load difference of zero can only happens if the total load is divisible by the total number of nodes N . The number of communication steps in the CWA is the same as DEM. However, CWA requires an additional $nN/2$ messages of size $O(n)$ to send the load information vectors where N is the number of nodes in an n -dimensional hypercube.

In order to reduce communications between computing clusters and get better load balancing quality that is comparable to CWA, we propose to use an improved version of the DEM instead of the CWA. In the next section, we describe the improved DEM for a hypercube.

3 Improved Dimension Exchange Algorithm for hypercubes

After the execution of the original DEM, the load difference between any two nodes is bounded by n . We can view the exchange of information and task migration in the least significant dimension of pairs of nodes as dividing the tasks among the two $(n - 1)$ -cubes roughly equally. However, the difference in the total number of task between the two $(n - 1)$ -cubes may be as high as $N/2$. This happens when the total number of tasks between every pair of nodes in the same dimension is an odd number and all the nodes

in one sub-cube have one more task than nodes in the other sub-cube.

Similarly, the exchange of load information and task migration in the second least significant dimension can be viewed as dividing tasks roughly equally between the two $(n-2)$ -cubes in each of the $(n-1)$ -cubes. The difference in the total number of tasks between two $(n-2)$ -cube in a $(n-1)$ -cube is bounded by $N/4$.

Using the above reasoning, after the load exchange in the first dimension, one $(n-1)$ -cube can have at most $T/2 + N/4$ tasks and the other one can have at least $T/2 - N/4$ task. After the load exchange in the second dimension, some $(n-2)$ -cubes have at most $(T/2 + N/4)/2 + N/8$ tasks and some $(n-2)$ -cubes have at least $(T/2 - N/4)/2 - N/8$ tasks. That is, some $(n-2)$ -cubes have at most $(T/2^2 + 2N/2^3)$ tasks and some have at least $(T/2^2 - 2N/2^3)$ tasks. Hence, after the execution of the DEM, some nodes have at most $T/2^n + n * N/2^{n+1}$ tasks and some have at least $T/2^n - n * N/2^{n+1}$ tasks. After applying the DEM, the maximum load difference between any two nodes is at most n .

The maximum difference can be reduced by $n/2$ if we divide the tasks more carefully between the sub-cubes in the load exchange of each dimension. Consider two neighboring nodes u and v with tasks w_u and w_v . Suppose $(w_u - w_v) > 0$. Instead of simply sending $\lfloor (w_u - w_v)/2 \rfloor$ tasks to node v , we may want to send $\lceil (w_u - w_v)/2 \rceil$ tasks to node v . By having a better scheme on which node should send $\lfloor (w_u - w_v)/2 \rfloor$ tasks or $\lceil (w_u - w_v)/2 \rceil$ tasks to its neighboring nodes, we could get a tighter bound on the maximum task difference. The improved DEM is shown in figure 2.

Improved DEM

Let node $u = u_1u_2\dots u_n$ and $v = v_1v_2\dots v_n$.

for $k = 0$ to $n - 1$

node u exchange with node v the current value of w_u and w_v , where $(u \oplus v) \oplus 2^k = 0$

if $k \neq n$

if $(w_u - w_v) > 0$ and $u_{k+1} = 0$,
send $\lfloor (w_u - w_v)/2 \rfloor$ tasks to node v
 $w_u = \lceil (w_u + w_v)/2 \rceil$

if $(w_u - w_v) > 0$ and $u_{k+1} = 1$,
send $\lceil (w_u - w_v)/2 \rceil$ tasks to node v
 $w_u = \lfloor (w_u + w_v)/2 \rfloor$

if $(w_v - w_u) > 0$ and $u_{k+1} = 0$,

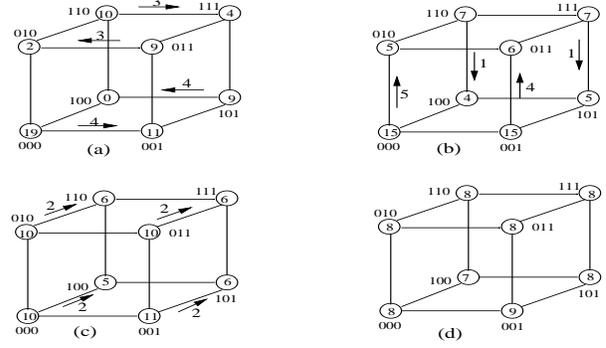


Figure 3. Example to show the execution of the DEM.

receive $\lceil (w_v - w_u)/2 \rceil$ tasks from node v

$w_u = \lceil (w_u + w_v)/2 \rceil$

if $(w_v - w_u) > 0$ and $u_{k+1} = 1$,

receive $\lfloor (w_v - w_u)/2 \rfloor$ tasks from node v

$w_u = \lfloor (w_u + w_v)/2 \rfloor$

else

if $(w_u - w_v) > 1$

send $\lfloor (w_u - w_v)/2 \rfloor$ tasks to node v

$w_u = \lceil (w_u + w_v)/2 \rceil$

if $(w_v - w_u) > 1$

receive $\lfloor (w_v - w_u)/2 \rfloor$ tasks from node v

$w_u = \lfloor (w_u + w_v)/2 \rfloor$

Figure 2: The improved DEM algorithm for hypercubes.

Figure 3 shows an example of the DEM algorithm in operation. A total of 33 task migrations took place. The maximum difference between any two nodes is 2. Figure 4 shows an example of the improved DEM algorithm in operation. A total of 25 task migrations took place. The maximum difference between any two nodes is 0. The examples show that the improved DEM should be able to provide better load balancing quality with less communication cost.

Theorem 1: After applying the improved DEM to an n -dimensional hypercube, the load difference between any two nodes u and v is at most $n/2$.

Proof: In the first step of the improved DEM, the load is divided roughly equally between the two $(n-1)$ -cubes within the n -cubes. Due to the new conditions imposed in the improved DEM, at most half of the nodes in one of the

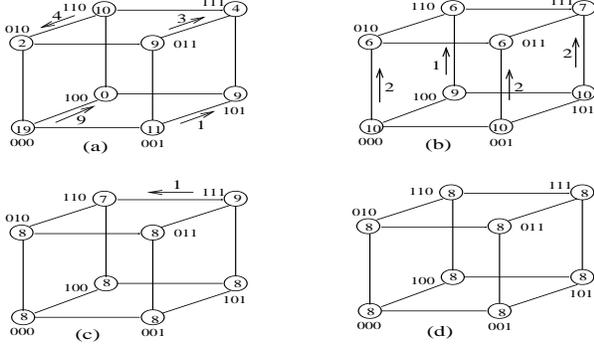


Figure 4. Example to show the execution of the improved DEM.

$(n - 1)$ -cube has one more task than the nodes in the other $(n - 1)$ -cube. Hence, a $(n - 1)$ -cube has at most $N/2^2$ tasks more than the other $(n - 1)$ -cube.

Let T be the total number of tasks in the n -cubes. After the first application of the dimension exchange, an $(n - 1)$ -cubes with the most tasks $T_{max,1}$ will have at most $N/4$ more than the other $(n - 1)$ -cubes with the least tasks $T_{min,1}$. Hence, $T_{max,1}$ will have at most $T/2 + N/2^3$ and $T_{min,1}$ has at least $T/2 - N/2^3$ tasks.

Similarly, after the load exchange in the second dimension, an $(n - 2)$ -cubes has at most $T_{max,2}$ and at least $T_{min,2}$ tasks.

$$T_{max,2} \leq (T/2 + N/2^3)/2 + N/2^3 * 1/2$$

$$\leq T/2^2 + 2N/2^4$$

$$T_{min,2} \geq (T/2 - N/2^3)/2 - N/2^3 * 1/2$$

$$\geq T/2^2 - 2N/2^4$$

After the load exchange in the i th application where $i \in \{1..n\}$, an $(n - l)$ -cubes has at most $T_{max,i}$ and at least $T_{min,i}$ tasks.

$$T_{max,l} \leq T/2^i + iN/2^{i+2}$$

$$T_{min,l} \geq T/2^i - iN/2^{i+2}$$

After applying the improved DEM, the maximum difference between any pairs of nodes in an n -dimensional hypercube is at most D tasks.

$$D = T_{max,n} - T_{min,n}$$

$$= T/2^n + nN/2^{n+2} - T/2^n + nN/2^{n+2}$$

$$= n/4 + n/4$$

$$= n/2$$

From theorem 1, the improved DEM has a better upper bound in load difference between any two nodes compared

n	Max load difference between any two nodes				
	0	1	2	3	4
3	780	49256	49170	793	0
4	0	12827	73855	13318	0
5	0	863	48776	49446	915
6	0	3	13053	73697	13237
7	0	0	864	48815	49461
8	0	0	9	14547	73490
9	0	0	0	859	48865
10	0	0	0	2	11820
11	0	0	0	0	905
12	0	0	0	0	4

Table 1a: The maximum load difference between any two nodes after applying DEM

n	Max load difference between any two nodes			Avg diff
	5	6	7	
3	0	0	0	1.50
4	0	0	0	2.00
5	0	0	0	2.50
6	10	0	0	3.00
7	860	0	0	3.50
8	11952	2	0	3.97
9	49393	883	0	4.50
10	73180	14991	7	5.03
11	49152	49024	919	5.50
12	13340	73414	13242	6.00

Table 1b: The maximum load difference between any two nodes after applying DEM

to the original DEM. Simulations were also done for both the DEM and the improved DEM for a hypercube from dimension 3 to dimension 12. Loads are randomly assigned to each node of a hypercube and DEM or the improved DEM are applied to balance the load. The simulation is repeated 100,000 times. The results are listed in table 1 and table 2.

From the data listed in table 1, after applying the original DEM to a hypercube, the expected load difference between any two nodes is roughly $n/2$. The difference is much lower than the upper bound of n . This can be explained by the fact that the upper bound can only happen for a special case.

From the data in table 2, after applying the improved

n	Max load difference between any two nodes							Avg	
	0	1	2	3	4	5	6	7	diff
3	9375	87483	3142	0	0	0	0	0	0.94
4	2030	87595	10375	0	0	0	0	0	1.08
5	104	79546	20350	0	0	0	0	0	1.20
6	0	69903	30097	0	0	0	0	0	1.30
7	0	60765	39235	0	0	0	0	0	1.39
8	0	52938	47062	0	0	0	0	0	1.47
9	0	47435	52565	0	0	0	0	0	1.53
10	0	43649	56351	0	0	0	0	0	1.56
11	0	39580	60420	0	0	0	0	0	1.60
12	0	34671	65329	0	0	0	0	0	1.65

Table 2: The maximum load difference between any two nodes after applying the improved DEM

DEM, the expected load difference between any two nodes is always less than 2. If the dimension of the hypercube is less than or equal to 12, the maximum load difference for any two nodes is at most 2. This happens because the load in each sub-cube of the hypercube would be roughly the same after one step of load balancing. The load balancing quality of the improved DEM compares favorably with the CWA where the maximum load difference is at most one.

The CWA requires $nN/2$ more messages of size $O(n)$ compared to the improved DEM. If we want to minimize the communications between the nodes, the improved DEM would be a very good alternative and the resulting load balancing quality is almost as good as the CWA.

4 Summary

An improved dimension exchange method (DEM) for synchronous load balancing for hypercube architecture is presented. The improved DEM requires the same number of communication steps and roughly the same task migrations comparing to the original dimension exchange method. However, the improved DEM provides much better load balancing quality than the original DEM. Although, theoretically the improved DEM cannot provide the same load balancing quality as the CWA, in practice, the improved DEM can provide comparable load balancing quality of the CWA. The improved DEM is quite suitable for load balancing for computing clusters that are quite far apart. In the near future, we will try to conduct load-balancing experiments between the computing clusters of Sharcnet and we will also try to address the problem of having computing clusters of various sizes.

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