

Figure 4.4. Infinitely many Optimal Solutions

Any $(x_1, x_2) = (1, k)$ for k being any positive number is a feasible solution.

Example 4.4. Consider

$$\begin{aligned} \max \quad & x_0 = 4x_1 + 14x_2 \\ \text{subject to} \quad & \begin{cases} 2x_1 + 7x_2 \leq 21 \\ 7x_1 + 2x_2 \leq 21 \\ x_1, x_2 \geq 0 \end{cases} \end{aligned}$$

| | x_1 | x_2 | x_3 | x_4 | b |
|-------|-------|-------|-------|-------|----------|
| x_3 | 2 | 7* | 1 | 0 | 21 |
| x_4 | 7 | 2 | 0 | 1 | 21 |
| x_0 | -4 | -14 | 0 | 0 | 0 |

nonbasic

| | x_1 | x_2 | x_3 | x_4 | b |
|-------|-------|-------|-------|-------|----------|
| x_2 | 2/7 | 1 | 1/7 | 0 | 3 |
| x_4 | 45/7* | 0 | -2/7 | 1 | 15 |
| x_0 | 0 | 0 | 2 | 0 | 42 |

Optimal ≥ 0
 0.00000001

optimal

$$\begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} 0 \\ 3 \\ 0 \\ 15 \end{pmatrix}$$

$$x_0 = 42$$

↓↑

| | x_1 | x_2 | x_3 | x_4 | b |
|-------|-------|-------|-------|-------|----------|
| x_2 | 0 | 1 | 7/45 | -2/45 | 7/3 |
| x_1 | 1 | 0 | -2/45 | 7/45* | 7/3 |
| x_0 | 0 | 0 | 2 | 0 | 42 |

$$\begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} 7/3 \\ 7/3 \\ 0 \\ 0 \end{pmatrix}$$

$x_0 = 42$

Thus all convex combinations of the points $[0, 3, 0, 15]$ and $[7/3, 7/3, 0, 0]$ are optimal feasible solutions.

4.4 Degeneracy and Cycling

Degenerate basic solutions are basic solutions with one or more basic variables at zero level. Degeneracy occurs when one or more of the constraints are redundant.

Example 4.5. Consider the following LLP

$$\begin{aligned} \max \quad & x_0 = 2x_1 + x_2 \\ \text{subject to} \quad & \begin{cases} 4x_1 + 3x_2 \leq 12 \\ 4x_1 + x_2 \leq 8 \\ 4x_1 - x_2 \leq 8 \\ x_1, x_2 \geq 0 \end{cases} \end{aligned}$$

$$\begin{aligned} 4x_1 + 3x_2 + x_3 &= 12 \\ 4x_1 + x_2 + x_4 &= 8 \\ 4x_1 - x_2 + x_5 &= 8 \end{aligned}$$

| | x_1 | x_2 | x_3 | x_4 | x_5 | b |
|-------|-------|-------|-------|-------|-------|----------|
| x_3 | 4 | 3 | 1 | 0 | 0 | 12 |
| x_4 | 4** | 1 | 0 | 1 | 0 | 8 |
| x_5 | 4* | -1 | 0 | 0 | 1 | 8 |
| x_0 | -2 | -1 | 0 | 0 | 0 | 0 |

3

3 non-zero basic variables
2 zero non-basic variables

(*) ✓

5

↘ (**)

| | x_1 | x_2 | x_3 | x_4 | x_5 | b |
|-------|-------|-------|-------|-------|-------|----------|
| x_3 | 0 | 4 | 1 | 0 | -1 | 4 |
| x_4 | 0 | 2* | 0 | 1 | -1 | 0 |
| x_1 | 1 | -1/4 | 0 | 0 | 1/4 | 2 |
| x_0 | 0 | -3/2 | 0 | 0 | 1/2 | 4 |

Degenerate Vertex $\{ x_4 = 0 \text{ and basic} \}$

↓

| | x_1 | x_2 | x_3 | x_4 | x_5 | b |
|-------|-------|-------|-------|-------|-------|----------|
| x_3 | 0 | 2** | 1 | -1 | 0 | 4 |
| x_1 | 1 | 1/4 | 0 | 1/4 | 0 | 2 |
| x_5 | 0 | -2 | 0 | -1 | 1 | 0 |
| x_0 | 0 | -1/2 | 0 | 1/2 | 0 | 4 |

Degenerate Vertex $\{ x_5 = 0 \text{ and basic} \}$

↓

$$\begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{pmatrix} = \begin{pmatrix} 2 \\ 0 \\ 4 \\ 0 \\ 0 \end{pmatrix}$$

0. - - - 01

B3

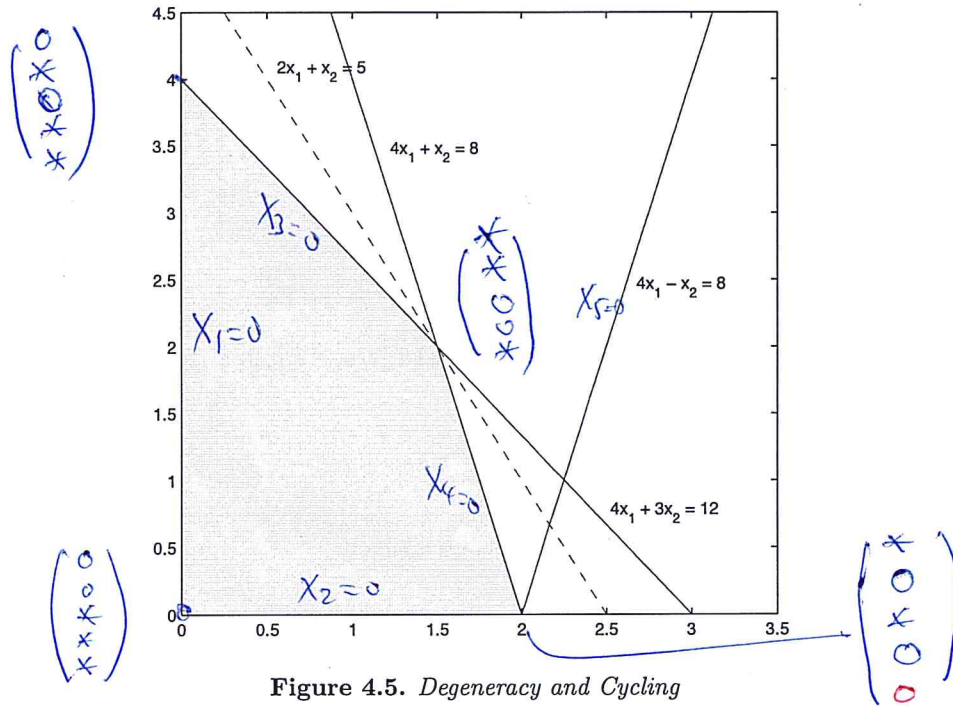


Figure 4.5. Degeneracy and Cycling

| | x_1 | x_2 | x_3 | x_4 | x_5 | b |
|-------|-------|-------|-------|-------|-------|----------|
| x_3 | 0 | 0 | 1 | -2 | 1* | 4 |
| x_2 | 0 | 1 | 0 | 1/2 | -1/2 | 0 |
| x_1 | 1 | 0 | 0 | 1/8 | 1/8 | 2 |
| x_0 | 0 | 0 | 0 | 3/4 | -1/4 | 4 |

| | x_1 | x_2 | x_3 | x_4 | x_5 | b |
|-------|-------|-------|-------|-------|-------|----------|
| x_2 | 0 | 1 | 1/2 | -1/2 | 0 | 2 |
| x_1 | 1 | 0 | -1/8 | 3/8 | 0 | 3/2 |
| x_5 | 0 | 0 | 1 | -2 | 1 | 4 |
| x_0 | 0 | 0 | 1/4 | 1/4 | 0 | 5 |

Degenerate Vertex $\{ x_2 = 0 \text{ and basic} \}$

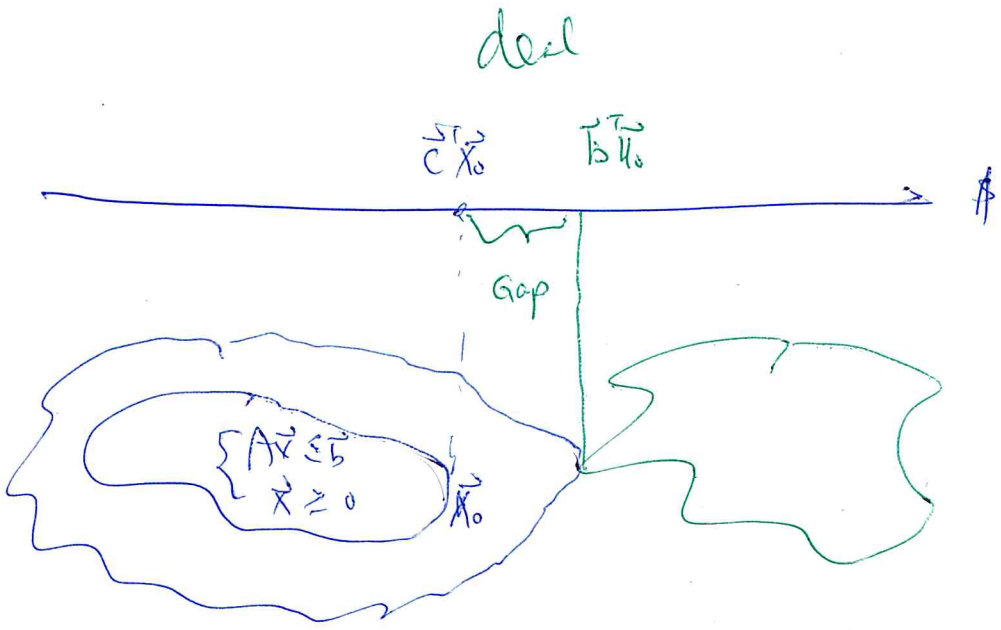
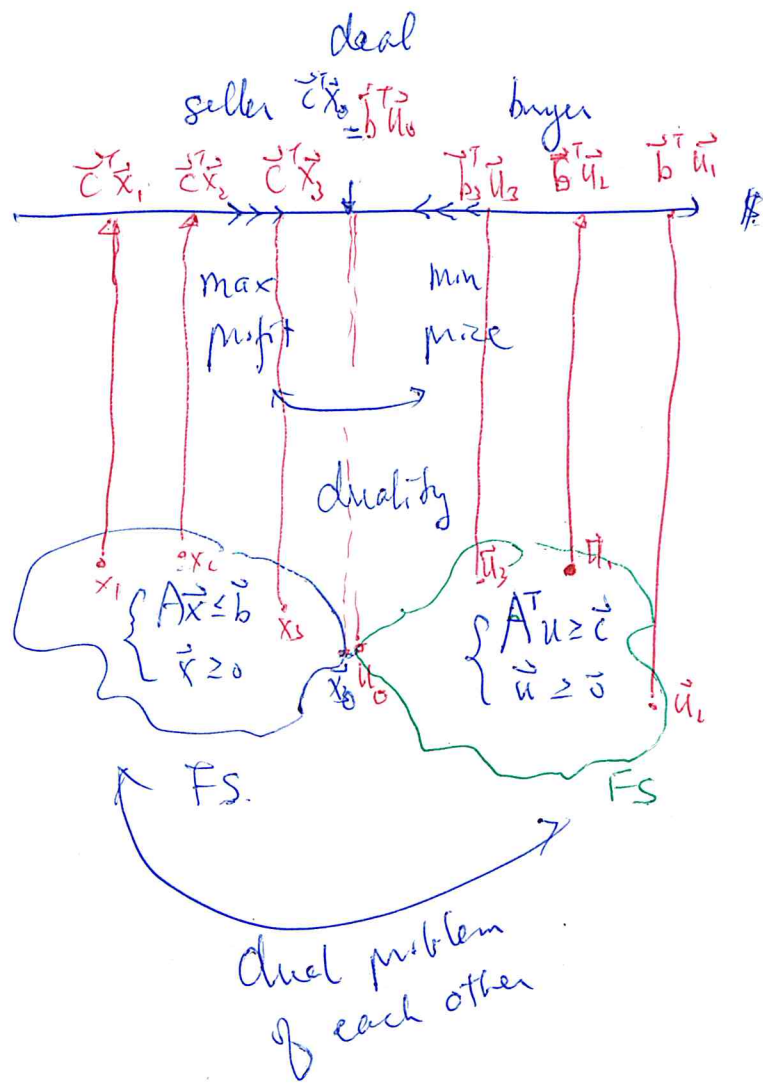
↓

| | x_1 | x_2 | x_3 | x_4 | x_5 | b |
|-------|-------|-------|-------|-------|-------|----------|
| x_5 | 0 | 0 | 1 | -2 | 1 | 4 |
| x_2 | 0 | 1 | 1/2 | -1/2 | 0 | 2 |
| x_1 | 1 | 0 | -1/8 | 3/8 | 0 | 3/2 |
| x_0 | 0 | 0 | 1/4 | 1/4 | 0 | 5 |

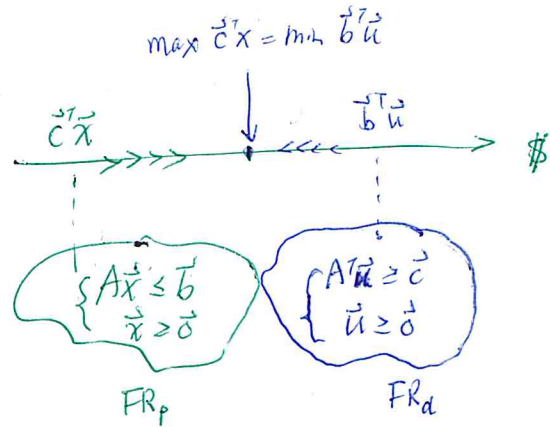
In figure 4.5, we see that the degenerate vertex V can be represented either by

$$\{x_2 = 0, x_4 = 0\}, \quad \{x_4 = 0, x_5 = 0\} \quad \text{or} \quad \{x_2 = 0, x_5 = 0\}.$$

We note that degeneracy guarantees the existence of more than one feasible pivot element, i.e. *tie-ratios* exist. For example, in the first tableau, the ratios for variables x_4 and x_5 are both equal to 2.



Chapter 5 DUALITY



Steve Smale for p.m.s

5.1 The Dual Problems

Every linear programming problem has associated with it another linear programming problem and that the two problems have such a close relationship that whenever one problem is solved, the other is solved as well. The original LPP is called the *primal* problem and the associated LPP is called the *dual* problem. Together they are called a "dual pair" (primal + dual) in the sense that the dual of the dual will again be the primal.

Example 5.1. (The Diet Problem) How can a dietician design the most economical diet that satisfies the basic daily nutritional requirements for a good health? For simplicity, we assume that there are only two foods F_1 and F_2 and the daily nutrition required are N_1, N_2 and N_3 . The unit cost of the foods and their nutrition values together with the daily requirement of each nutrition are given in the following table.

| | | Veg. F_1 | Meat F_2 | Daily Requirement | $\$u_1$ | $\$u_2$ | $\$u_3$ |
|------------------------------|------|------------|------------|-------------------|-------------------|-------------------|-------------------|
| $u_1 + 2u_2 + 3u_3 \leq 120$ | Cost | 120 | 180 | - | \textcircled{P} | \textcircled{V} | \textcircled{C} |
| Protein N_1 | | 1 | 1 | 10 | 1P | 1V | 1C |
| Vitamin N_2 | | 2 | 4 | 24 | 10 | 24 | 32 |
| Carbohydrate N_3 | | 3 | 6 | 32 | | | |

Let $x_j, j = 1, 2$ be the number of units of F_j that one should eat in order to minimize the cost and yet fulfill the daily nutrition requirement. Thus the problem is to select the x_j such that

$$\min \quad x_0 = 120x_1 + 180x_2$$

subject to the nutritional constraints:

$$\begin{cases} x_1 + x_2 \geq 10 \\ 2x_1 + 4x_2 \geq 24 \\ 3x_1 + 6x_2 \geq 32 \end{cases}$$

and the non-negativity constraints: $x_j \geq 0, j = 1, 2$. In matrix form, we have

$$\begin{aligned} \min \quad & x_0 = c^T x && (120, 180) \\ \text{subject to} \quad & \begin{cases} Ax \geq b \\ x \geq 0 \end{cases} && \begin{pmatrix} 1 & 1 \\ 2 & 4 \\ 3 & 6 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \geq \begin{pmatrix} 10 \\ 24 \\ 32 \end{pmatrix} \\ & && \vec{x} = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \geq \begin{pmatrix} 0 \\ 0 \end{pmatrix} \end{aligned}$$

PE

where

$$c = \begin{bmatrix} 120 \\ 180 \end{bmatrix}, \quad x = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}, \quad b = \begin{bmatrix} 10 \\ 24 \\ 32 \end{bmatrix}$$

and

$$A = \begin{bmatrix} 1 & 1 \\ 2 & 4 \\ 3 & 6 \end{bmatrix}$$

Now let us look at the same problem from a pharmaceutical company's point of view. How can a pharmaceutical company determine the price for each unit of nutrient pill so as to maximize revenue, if a synthetic diet made up of nutrient pills of various pure nutrients is adopted? Thus we have three types of nutrient pills P_1, P_2 and P_3 . We assume that each unit of P_i contains one unit of the N_i . Let u_i be the unit price of P_i , the problem is to maximize the total revenue u_0 from selling such a synthetic diet, i.e.

$$\max \quad u_0 = 10u_1 + 24u_2 + 32u_3$$

subject to the constraints that the cost of a unit of synthetic food j made up of P_i is no greater than the unit market price of F_j :

$$\begin{cases} u_1 + 2u_2 + 3u_3 \leq 120 \\ u_1 + 4u_2 + 6u_3 \leq 180 \\ u_1, u_2, u_3 \geq 0 \end{cases} \quad \begin{pmatrix} 1 & 2 & 3 \\ 1 & 4 & 6 \end{pmatrix} \begin{pmatrix} u_1 \\ u_2 \\ u_3 \end{pmatrix} \leq \begin{pmatrix} 120 \\ 180 \end{pmatrix}$$

In matrix form, the problem is:

$$\begin{aligned} \max \quad & u_0 = \mathbf{b}^T \mathbf{u} \quad (10, 24, 32) \quad \begin{pmatrix} u_1 \\ u_2 \\ u_3 \end{pmatrix} \geq \vec{0} \\ \text{subject to} \quad & \begin{cases} A^T \mathbf{u} \leq \mathbf{c} \rightarrow (120) \\ \mathbf{u} \geq \mathbf{0} \rightarrow (180) \end{cases} \end{aligned}$$

We said the two problems form a dual pair of linear programming problem, and we will see that the solution to one should lead to the solution of the other.

Definition 5.1. Let \mathbf{x} and \mathbf{c} be column n -vectors, \mathbf{b} and \mathbf{u} be column m -vectors and A be an m -by- n matrix. The *primal* and the *dual* problems can be defined as follows:

| Primal <i>CF</i> | Dual |
|--|---|
| $\max \mathbf{c}^T \mathbf{x}$ | $\min \mathbf{b}^T \mathbf{u}$ |
| subject to $A\mathbf{x} \leq \mathbf{b}$ | subject to $A^T \mathbf{u} \geq \mathbf{c}$ |
| $\mathbf{x} \geq \mathbf{0}$ | $\mathbf{u} \geq \mathbf{0}$ |

primal
 (i) cost coeff \vec{c}
 (ii) max
 (iii) r.h.s. \vec{b}
 (iv) \leq
 dual
 r.h.s.
 min
 cost coeff
 \geq

Calling one primal and the other one dual is completely arbitrary for we have the following theorem.

Theorem 5.1. *The dual of the dual is the primal.*

Proof. Transforming the dual into canonical form, we have

$$\begin{aligned} \max \quad & u'_0 = -\mathbf{b}^T \mathbf{u} \quad \text{FC} \\ \text{subject to} \quad & \begin{cases} -A^T \mathbf{u} \leq -\mathbf{c} \\ \mathbf{u} \geq \mathbf{0} \end{cases} \quad \text{Dual} \end{aligned}$$

$((\text{Primal})^{\text{dual}})^{\text{dual}} = \text{primal}$