

Lecture 11: More about invariant subspaces

Example 1: Let $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ by $T(a, b, c) = (2b + 3c, 3a + 3c, 8c)$

Let $W = \{ (s, t, 0) : s, t \in \mathbb{R} \}$. Let $\gamma = \{ \vec{e}_1, \vec{e}_2 \}$, $\beta = \{ \vec{e}_1, \vec{e}_2, \vec{e}_3 \}$

Then: $[T_W]_\gamma = \begin{pmatrix} 0 & 2 \\ 3 & 0 \end{pmatrix} \rightsquigarrow$ Char poly of $T_W = \lambda^2 - 6 = g(\lambda)$

Now, $[T]_\beta = \begin{pmatrix} 0 & 2 & 3 \\ 3 & 0 & 3 \\ 0 & 0 & 8 \end{pmatrix} \rightsquigarrow$ Char poly of $T = (t^2 - 6)(8 - t) = f(t)$

$\therefore g(t) \mid f(t)$.

Theorem 1: Let $T: V \rightarrow V$ (finite-dim). Let $W = T$ -cyclic subspace generated by $\vec{v} \neq 0 \in V$. Let $k = \dim(W)$. Then:

- $\{ \vec{v}, T(\vec{v}), \dots, T^{k-1}(\vec{v}) \}$ is a basis for W .
- Let $a_0 \vec{v} + a_1 T(\vec{v}) + \dots + a_{k-1} T^{k-1}(\vec{v}) + T^k(\vec{v}) = \vec{0}$.

Then, the char poly of T_W is: $(-1)^k (a_0 + a_1 t + \dots + a_{k-1} t^{k-1} + t^k)$

Proof: $\vec{v} \neq \vec{0}$. So, $\{ \vec{v} \}$ is lin. ind. Let $j =$ largest integer such that $\beta = \{ \vec{v}, T(\vec{v}), \dots, T^{j-1}(\vec{v}) \}$ is lin. ind.

(Must exist since V is finite-dim)

Let $X = \text{span}(\beta)$. Then, $\beta =$ basis of X . Also, $T^j(\vec{v}) \in X$ since $T^j(\vec{v})$ can be written as lin. comb. of β .

We show that X is T -invariant:

Let $\vec{w} \in X$. Then: $\vec{w} = a_0 \vec{v} + a_1 T(\vec{v}) + \dots + a_{j-1} T^{j-1}(\vec{v})$

$\Rightarrow T(\vec{w}) = a_0 \underbrace{T(\vec{v})}_X + a_1 \underbrace{T^2(\vec{v})}_X + \dots + a_{j-1} \underbrace{T^j(\vec{v})}_X \in X$

Now, $W = T$ -cyclic subspace = Smallest T -invariant subspace containing \vec{v} .

$\therefore W \subseteq X$. Clearly, $X \subseteq W$

Thus, $W = X$ and β = basis of W .

Also, $\dim(W) = k \Rightarrow j = k$.

$$\textcircled{2} \text{ Let } a_0 \vec{v} + a_1 T(\vec{v}) + \dots + a_{k-1} T^{k-1}(\vec{v}) + T^k(\vec{v}) = 0 \\ \Rightarrow T^k(\vec{v}) = -a_0 \vec{v} - a_1 T(\vec{v}) - \dots - a_{k-1} T^{k-1}(\vec{v})$$

$$\therefore [T_W]_{\beta} = \begin{pmatrix} 0 & 0 & \dots & 0 & -a_0 \\ 1 & 0 & \dots & 0 & -a_1 \\ 0 & 1 & \dots & 0 & \vdots \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \dots & 1 & -a_{k-1} \end{pmatrix}$$

By M.I. and cofactor expansion on the first row, we get,

$$\text{Char poly of } T_W \text{ is: } f(t) = (-1)^k (a_0 + a_1 t + \dots + a_{k-1} t^{k-1} + t^k) \\ \text{(Good exercise to check)}$$

Example 2: Consider $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ by $T(a, b, c) = (2b + 3c, 3a + 8c, 8c)$

$$T(\vec{e}_1) = 3\vec{e}_2, T^2(\vec{e}_1) = 6\vec{e}_1 \quad \therefore T\text{-cyclic subspace generated by } \vec{e}_1 \\ = \text{span}\{\vec{e}_1, \vec{e}_2\}$$

$$\text{Now, } -6\vec{e}_1 + T^2(\vec{e}_1) = 0.$$

$$\therefore \text{Char poly of } T_W \text{ is: } f(t) = (-1)^2 (-6 + t^2)$$

Check: $\beta = \{\vec{e}_1, \vec{e}_2\}$ = basis of W .

$$[T_W]_{\beta} = \begin{pmatrix} 0 & 2 \\ 3 & 0 \end{pmatrix}. \therefore \det([T_W]_{\beta} - tI) = \det \begin{pmatrix} t & 2 \\ 3 & -t \end{pmatrix} = t^2 - 6.$$

Theorem 2: (Cayley - Hamilton) Let $T: V \rightarrow V$ (fin-dim).

$f(t) = \text{char poly of } T$. Then: $f(T) = T_0 = \text{zero transformation}$

(That is, T "satisfies" $f(t)$)

Proof: Need to show, $f(T)(\vec{v}) = \vec{0}$ for $\forall \vec{v} \in V$.

If $\vec{v} = \vec{0}$, obvious.

Suppose $\vec{v} \neq \vec{0}$. Let $W = T$ -cyclic subspace generated by \vec{v} .

Suppose $\dim(W) = k$. So, $\exists a_0, a_1, \dots, a_{k-1}$ such that

$$a_0 \vec{v} + a_1 T(\vec{v}) + \dots + a_{k-1} T^{k-1}(\vec{v}) + T^k(\vec{v}) = \vec{0}.$$

Thus, char poly of $T|_W$ is $(-1)^k (a_0 + a_1 t + \dots + a_{k-1} t^{k-1} + t^k)$

$$\text{So, } g(T)(\vec{v}) = (-1)^k (a_0 I + a_1 T + \dots + a_{k-1} T^{k-1} + T^k)(\vec{v})$$

$$= (-1)^k (a_0 \vec{v} + a_1 T(\vec{v}) + \dots + a_{k-1} T^{k-1}(\vec{v}) + T^k(\vec{v})) = \vec{0}.$$

But $g(t)$ divides $f(t)$. Thus, $f(t) = g(t)q(t)$ for some $q(t)$.

$$\text{So, } f(T)(\vec{v}) = g(T)q(T)(\vec{v}) = q(T)(\vec{0}) = \vec{0}$$

Example 3: Let $T(a, b) = (3a+b, 2a+b)$. Let $\beta = \{\vec{e}_1, \vec{e}_2\} =$ ordered basis of \mathbb{R}^2 .

$$\text{Then: } A = [T]_{\beta} = \begin{pmatrix} 3 & 1 \\ 2 & 1 \end{pmatrix} \rightsquigarrow \text{char poly of } T = t^2 - 4t + 1$$

Easy to verify: $T^2 - 4T + I = \text{zero transformation}$.

$$\text{Also, } A^2 - 4A + I = \begin{pmatrix} 11 & 4 \\ 8 & 3 \end{pmatrix} - \begin{pmatrix} 12 & 4 \\ 8 & 4 \end{pmatrix} + \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}.$$

Remark: Cayley-Hamilton generally work for matrix.

Corollary 1: (Cayley-Hamilton for Matrices) Let $A \in M_{n \times n}(F)$.

Let $f(t) = \text{char-poly of } A$. Then: $f(A) = 0 = n \times n$ zero matrix.

Invariant subspaces and Direct Sum

Theorem 3: Let $T: V \rightarrow V$ (fin-dim). Suppose that $V = W_1 \oplus \dots \oplus W_k$

where $W_i = T$ -invariant subspace of V for each i .

Let $f_i(t) = \text{char. poly of } T|_{W_i}$

Then: $f_1(t) f_2(t) \dots f_k(t) = \text{char poly of } T$.

Proof: We prove by M.I. on k . Let $f(t) = \text{char poly of } T$.

When $k=2$, Let $\beta_1 = \text{ordered basis for } W_1$

$\beta_2 = \text{ordered basis for } W_2$.

Then: $\beta = \beta_1 \cup \beta_2 = \text{ordered basis for } V$. Let $B_1 = [T|_{W_1}]_{\beta_1}$,

$B_2 = [T|_{W_2}]_{\beta_2}$. Then: $A = [T]_{\beta} = \begin{pmatrix} B_1 & 0 \\ 0 & B_2 \end{pmatrix}$

$\therefore f(t) = \det(A - tI) = \det(B_1 - tI) \det(B_2 - tI) = f_1(t) f_2(t)$

\therefore true for $k=2$.

Assume thm is valid for $k-1$ summand ($k-1 \geq 2$)

Let $V = W_1 \oplus \dots \oplus W_k$. Let $W = W_1 + \dots + W_{k-1}$

Then, $W = T$ -invariant

Also, $V = W \oplus W_k$. So, $f(t) = g(t) f_k(t)$ where $g(t) = \text{char poly of } T|_W$.

Clearly, $W = W_1 \oplus W_2 \oplus \dots \oplus W_{k-1}$.

$\therefore g(t) = f_1(t) f_2(t) \dots f_{k-1}(t)$ by induction hypothesis.

$\therefore f(t) = g(t) f_k(t) = f_1(t) f_2(t) \dots f_{k-1}(t) f_k(t)$.

Remark: Simple example: $T =$ diagonalizable matrix.

$\lambda_1, \lambda_2, \dots, \lambda_k =$ distinct eigenvalues.

$V = E_{\lambda_1} \oplus \dots \oplus E_{\lambda_k}$. Then $f(t) = (\lambda_1 - t)^{m_1} \dots (\lambda_k - t)^{m_k}$

Also, char poly of $T_{E_{\lambda_i}} = f_i(t) = (\lambda_i - t)^{m_i}$

$\therefore f(t) = f_1(t) \dots f_k(t)$.

Example 4: Let $T(a, b, c, d) = (a+b, 2a-b, c+d, 3c+2d)$

Let $W_1 = \{(s, t, 0, 0) : s, t \in \mathbb{R}\}$; $W_2 = \{(0, 0, s, t) : s, t \in \mathbb{R}\}$

Then: $\mathbb{R}^4 = W_1 \oplus W_2$. Let $\beta_1 = \{e_1, e_2\}$, $\beta_2 = \{e_3, e_4\}$.

Then: $[T_{W_1}]_{\beta_1} = \begin{pmatrix} 1 & 1 \\ 2 & -1 \end{pmatrix}$; $[T_{W_2}]_{\beta_2} = \begin{pmatrix} 1 & 1 \\ 3 & 2 \end{pmatrix}$

$$A = [T]_{\beta = \beta_1 \cup \beta_2} = \begin{pmatrix} \boxed{\begin{matrix} 1 & 1 \\ 2 & -1 \end{matrix}} & \mathbf{0} \\ \mathbf{0} & \boxed{\begin{matrix} 1 & 1 \\ 3 & 2 \end{matrix}} \end{pmatrix} = \begin{pmatrix} B_1 & 0 \\ 0 & B_2 \end{pmatrix}$$

Then: $f(t) = \det(A - tI) = \det(B_1 - tI) \det(B_2 - tI)$

$$= \underset{\substack{\uparrow \\ \text{char poly of } T_{W_1}}}{f_1(t)} \cdot \underset{\substack{\uparrow \\ \text{char poly of } T_{W_2}}}{f_2(t)}$$

Definition 1: (Direct sum of Matrices)

Let $B_1 = M_{m \times m}(\mathbb{F})$, $B_2 = M_{n \times n}(\mathbb{F})$. We define the direct sum of B_1 and B_2 , denote by $B_1 \oplus B_2$ as the $(m+n) \times (m+n)$ matrix A such that:

$$A_{ij} = \begin{cases} (B_1)_{ij} & 1 \leq i, j \leq m \\ (B_2)_{(i-m) \times (j-m)} & m+1 \leq i, j \leq m+n \\ 0 & \text{otherwise} \end{cases} \quad A = \begin{pmatrix} B_1 & 0 \\ 0 & B_2 \end{pmatrix}$$

If B_1, B_2, \dots, B_k are square matrices, we define the direct sum of B_1, B_2, \dots, B_k recursively by:

$$B_1 \oplus B_2 \oplus \dots \oplus B_k = (B_1 \oplus \dots \oplus B_{k-1}) \oplus B_k.$$

$$A = \begin{pmatrix} \boxed{B_1} & & & \\ & \boxed{B_2} & & \\ & & \dots & \\ & & & \boxed{B_k} \end{pmatrix}$$

Example 4: Let $B_1 = \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix}$; $B_2 = \begin{pmatrix} 2 & 3 \\ 4 & 5 \end{pmatrix}$; $B_3 = (1)$

$$\text{Then: } B_1 \oplus B_2 \oplus B_3 = \begin{pmatrix} \boxed{1} & \boxed{2} & 0 & 0 & 0 \\ \boxed{3} & \boxed{4} & 0 & 0 & 0 \\ 0 & 0 & \boxed{2} & \boxed{3} & 0 \\ 0 & 0 & \boxed{4} & \boxed{5} & 0 \\ 0 & 0 & 0 & 0 & \boxed{1} \end{pmatrix}$$

Theorem 4: Let $T: V \rightarrow V$ (fin-dim). Let $W_1, \dots, W_k =$

T -invariant subspaces of V such that $V = W_1 \oplus \dots \oplus W_k$.
Let $\beta_i =$ ordered basis for W_i . Let $\beta = \beta_1 \cup \beta_2 \cup \dots \cup \beta_k$.

Let $A = [T]_{\beta}$ and $B_i = [T]_{\beta_i}$

Then: $A = B_1 \oplus B_2 \oplus \dots \oplus B_k$