

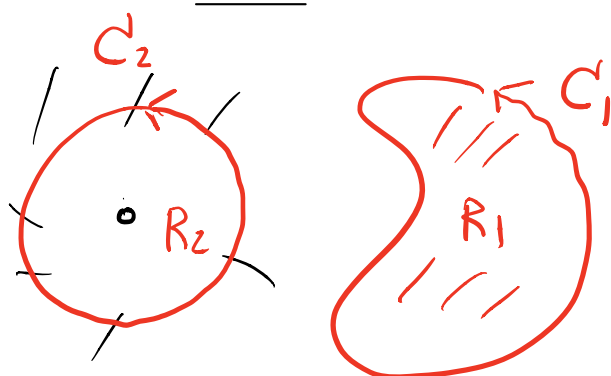
Note:  $\Omega_1 = \mathbb{R}^2 \setminus \{x \leq 0\}$



Green's Thm applies

as  $R \subset \Omega_1$

$\Omega_2 = \mathbb{R}^2 \setminus \{(0,0)\}$



Let  $C_2 = x^2 + y^2 = 1$ ,

then

$R_2 =$  region

enclosed by  $C_2$

$= \{x^2 + y^2 < 1\} \not\subset \Omega_2$

since  $(0,0) \in R_2$  but

$(0,0) \notin \Omega_2$

$\therefore$  Green's Thm doesn't apply  
to  $C_2$  &  $R_2$

$R_1 \subset \Omega_2$   
Green's Thm  
applies

eg 4.8: Verify both forms of Green's Thm for

$\vec{F}(x,y) = (x-y)\hat{i} + x\hat{j}$  on  $\Omega = \mathbb{R}^2$  (is  $C^\infty$ )

$C =$  unit circle:  $\vec{r}(t) = \cos t \hat{i} + \sin t \hat{j}$ ,  
 $0 \leq t \leq 2\pi$

Then  $R =$  enclosed by  $C = \{x^2 + y^2 < 1\}$  the unit disc.

Solu:  $M = x - y$ ,  $N = x$  (in this case)

$$\frac{\partial M}{\partial x} = 1, \quad \frac{\partial M}{\partial y} = -1, \quad \frac{\partial N}{\partial x} = 1, \quad \frac{\partial N}{\partial y} = 0.$$

On  $C$ ,  $x = \cos t$ ,  $y = \sin t$  for  $0 \leq t \leq 2\pi$

Normal Form

$$\text{L.H.S.} = \oint_C M dy - N dx$$

$$= \int_0^{2\pi} [(\cos t - \sin t) \cos t - \cos t (-\sin t)] dt$$

$$= \pi$$

$$\text{R.H.S.} = \iint_R \left( \frac{\partial M}{\partial x} + \frac{\partial N}{\partial y} \right) dA = \iint_R 1 dA = \pi$$

Tangential form

$$\text{L.H.S.} = \oint_C M dx + N dy$$

$$= \int_0^{2\pi} [(\cos t - \sin t)(-\sin t) + \cos t \cos t] dt$$

$$= 2\pi$$

$$\text{R.H.S.} = \iint_R \left( \frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) dA = \iint_R [1 - (-1)] dA = 2\pi$$

#

# Pf of Green's Thm (tangential form)

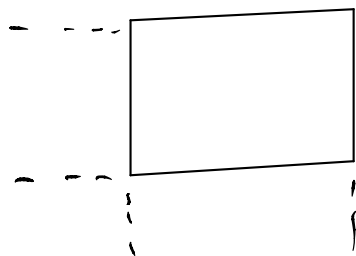
Recall: A region  $R$  is of special type:

type (1) = If  $R = \{(x,y) : a \leq x \leq b, g_1(x) \leq y \leq g_2(x)\}$   
for some continuous functions  $g_1(x)$  &  $g_2(x)$ .

type (2) = If  $R = \{(x,y) : h_1(y) \leq x \leq h_2(y), c \leq y \leq d\}$   
for some continuous functions  $h_1(x)$  &  $h_2(x)$ .

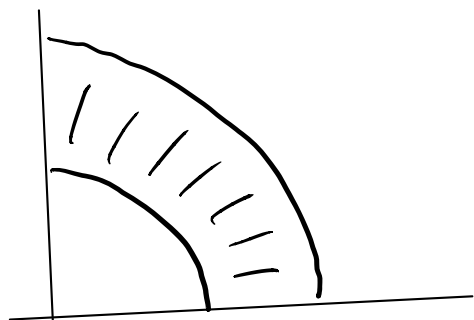
Now: If  $R$  is both type (1) and type (2), it  
said to be simple.

eg 49 (i)

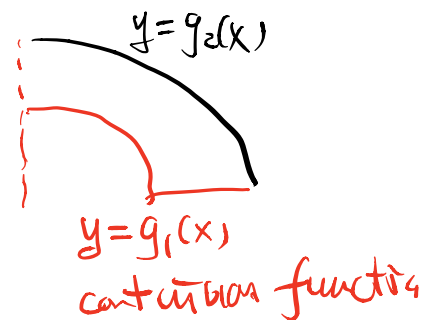


rectangle is simple.

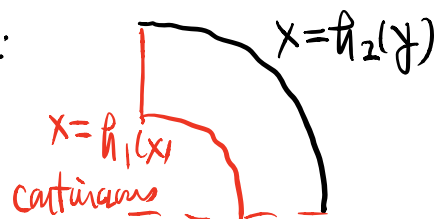
(ii)



type (1):  
yes

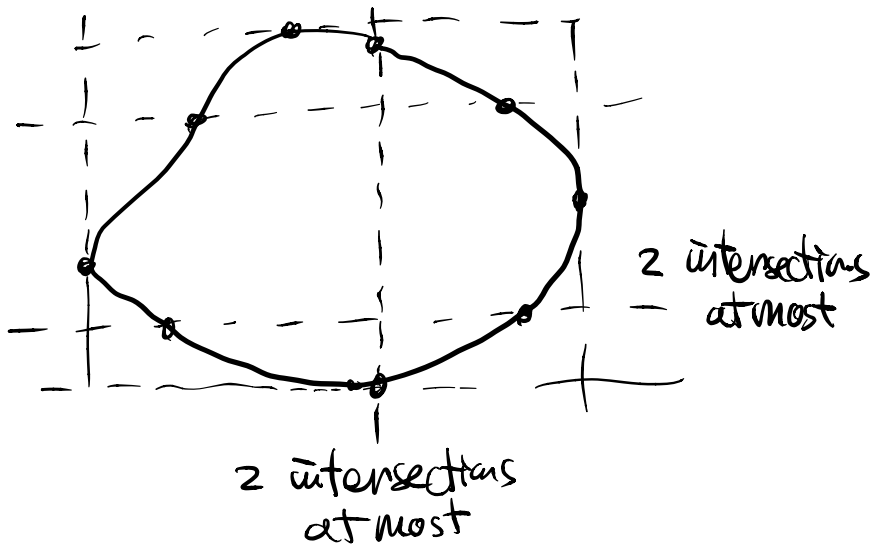


type (2):  
yes



is simple :

(iii)



$$\left. \begin{array}{l} \forall a \in \mathbb{R}, \# \{ \partial R \cap \{x=a\} \} \leq 2 \\ \text{and } \# \{ \partial R \cap \{y=a\} \} \leq 2 \end{array} \right\} \Rightarrow \text{simple}$$

(provided  $\partial R$  is piecewise smooth)

Pf of Green Thm for simple region

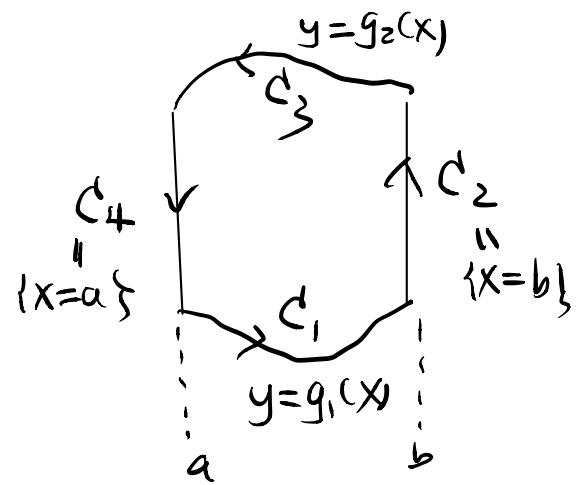
By definition,  $R$  is of type (I) and can be written as

$$R = \{ (x,y) = a \leq x \leq b, g_1(x) \leq y \leq g_2(x) \}$$

Let denote the components of the boundary of  $R$  by

$C_1, C_2, C_3, C_4$  as in the

figure (note that  $C_2$  and/or  $C_4$  can degenerated to a point.)





Then  $\partial R = C_1 + C_2 + C_3 + C_4$  as oriented curve

(using "+" instead of "U" to denote the orientation)

Now  $C_1 = \{y = g_1(x)\}$  can be parametrized by

$$\vec{r}(t) = x=t, y=g_1(t), a \leq t \leq b$$

with the correct orientation

$$\therefore \int_{C_1} M dx = \int_a^b M(t, g_1(t)) dt.$$

Similarly " $-C_3$ " can be parametrized by

$$\vec{r}(t) = x=t, y=g_2(t), a \leq t \leq b$$

with the correct orientation

$$\therefore \int_{-C_3} M dx = \int_a^b M(t, g_2(t)) dt$$

$$\Rightarrow \int_{C_3} M dx = - \int_a^b M(t, g_2(t)) dt$$

(oriented)

For  $C_2 = \{x=b\}$ , it can be parametrized by

$$\vec{r}(t) = x=b, y=t, g_1(b) \leq t \leq g_2(b)$$

with correct orientation

$$\therefore \int_{C_2} M dx = 0$$

$$\text{Similarly } \int_{C_4} M dx = - \int_{-C_4} M dx = 0$$

$$\begin{aligned} \text{Hence } \oint_{\partial R} M dx &= \sum_{i=1}^4 \int_{C_i} M dx \\ &= \int_a^b [M(x, g_1(x)) - M(x, g_2(x))] dx \\ &\left( = \int_a^b [M(x, g_1(x)) - M(x, g_2(x))] dx \quad (x=t) \right) \end{aligned}$$

On the other hand, Fubini's Thm  $\Rightarrow$

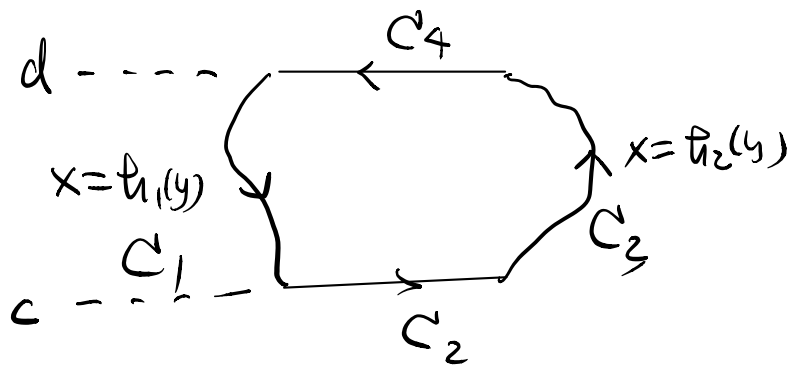
$$\begin{aligned} \iint_R -\frac{\partial M}{\partial y} dA &= \int_a^b \left[ \int_{g_1(x)}^{g_2(x)} -\frac{\partial M}{\partial y} dy \right] dx \\ &= \int_a^b -[M(x, g_2(x)) - M(x, g_1(x))] dx \end{aligned}$$

$$\therefore \iint_R -\frac{\partial M}{\partial y} dA = \oint_{\partial R} M dx$$

Since  $R$  is also type (2),  $R$  can be written as

$$R = \{(x, y) = h_1(y) \leq x \leq h_2(y), c \leq y \leq d\}$$

One can show  
similarly



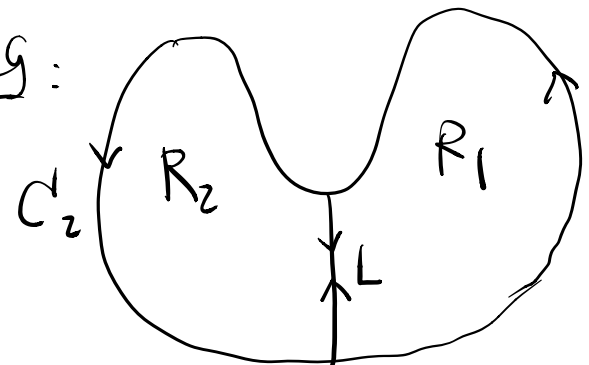
$$\begin{aligned}
 \oint_{\partial R} N dy &= - \int_c^d N(h_1(t), t) dt + 0 \\
 &\quad + \int_c^d N(h_2(t), t) dt + 0 \\
 &= \int_c^d [N(h_2(t), t) - N(h_1(t), t)] dt \\
 &= \int_c^d [N(h_2(y), y) - N(h_1(y), y)] dy \quad (y=t) \\
 &= \int_c^d \left[ \int_{h_1(y)}^{h_2(y)} \frac{\partial N}{\partial x} dx \right] dy \\
 &= \iint_R \frac{\partial N}{\partial x} dA
 \end{aligned}$$

All together

$$\begin{aligned}
 \oint_R (M dx + N dy) &= \iint_R \left( -\frac{\partial M}{\partial y} \right) dA \\
 &\quad + \iint_R \frac{\partial N}{\partial x} dA \\
 &= \iint_R \left( \frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) dA
 \end{aligned}$$

# Proof of Green's Thm for

$R =$  finite union of simple regions with intersections only along some boundary line segments, and these line segments touch only at the end points at most.

eg: 

$R_1, R_2 = \text{simple}$   
 but  $R = R_1 \cup R_2 \neq \text{simple}$

$\partial R_1 = C_1 + L$  ( $L: \downarrow$ )  
 $\partial R_2 = C_2 - L$  ( $L: \downarrow$ )

with anti-clockwise orientations  
 $\partial R = C_1 -$

By assumption  $R = \cup R_i$  finite union s.t.  
 $R_i$  are simple and

$R_i \cap R_j =$  line segment of a common boundary portion, denote by  $L_{ij}$  ( $i \neq j$ )

Then

$$\iint_R \left( \frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) dA = \sum_i \iint_{R_i} \left( \frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) dA$$

$$\left( \begin{array}{l} \text{by Green's theorem} \\ \text{for simple region} \end{array} \right) = \sum_i \oint_{\partial R_i} (M dx + N dy)$$

Denote  $C_i =$  the part of  $\partial R_i$  with no intersection with any other  $R_j$  (except at end point)

$$\text{Then } \partial R_i = C_i + \sum_{j \neq i} L_{ij}$$

$L_{ij}$  is oriented according to the anti-clockwise orientation of  $\partial R_i$ .

Hence

$$\iint_R \left( \frac{\partial M}{\partial x} - \frac{\partial N}{\partial y} \right) dA = \sum_i \int_{C_i + \sum_{j \neq i} L_{ij}} (M dx + N dy)$$

$$= \sum_i \int_{C_i} M dx + N dy$$

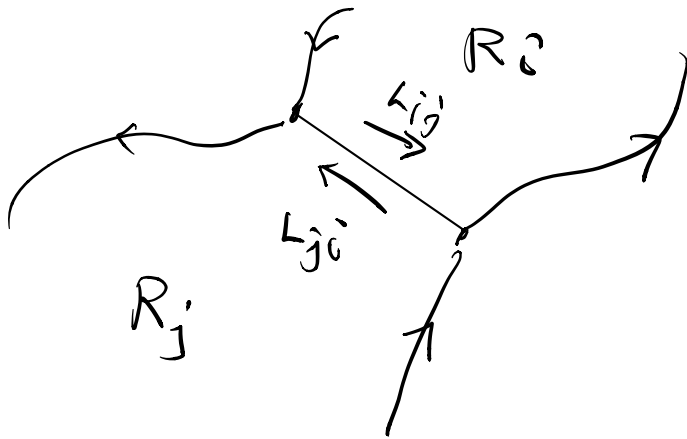
$$+ \sum_i \sum_{j \neq i} \int_{L_{ij}} (M dx + N dy)$$

Note that  $\sum_i C_i = \partial R$  (as  $C_i$  is not common boundary of any other  $R_j$ )

$$\therefore \sum_i \int_{C_i} M dx + N dy = \oint_{\partial R} M dx + N dy.$$

Finally, we have

$L_{ji} = -L_{ij}$  as  $R_i \triangleleft R_j$  are located on the two different sides of the common boundary



$$\therefore \sum_{\bar{i}} \sum_{\substack{\bar{j} \\ (j \neq i)}} \int_{L_{ij}} Mdx + Ndy = \sum_{\substack{\bar{i}, \bar{j} \\ \bar{i} < \bar{j}}} \int_{L_{ij}} Mdx + Ndy \\ + \sum_{\substack{\bar{i}, \bar{j} \\ \bar{i} > \bar{j}}} \int_{L_{ij}} Mdx + Ndy$$

$$= \sum_{\substack{\bar{i}, \bar{j} \\ \bar{i} < \bar{j}}} \int_{L_{ij}} Mdx + Ndy \\ + \sum_{\substack{\bar{j}, \bar{i} \\ \bar{j} > \bar{i}}} \int_{L_{ji}} Mdx + Ndy$$

$$= \sum_{\substack{\bar{i}, \bar{j} \\ \bar{i} < \bar{j}}} \left[ \left( \int_{L_{ij}} Mdx + Ndy \right) + \left( \int_{L_{ji}} Mdx + Ndy \right) \right]$$

$$= \sum_{\substack{i, j \\ i < j}} \left( \int_{L_{ij}} M dx + N dy - \int_{L_{ji}} M dx + N dy \right)$$

$$\text{Since } L_{ji} = -L_{ij}$$

$$= 0$$

This 2<sup>nd</sup> case basically include almost all situations in the level of Advanced Calculus.

The proof of general case needs "analysis" and will be omitted here. ~~##~~

Def 12: The divergence of  $\vec{F} = M\hat{i} + N\hat{j}$  is

defined to be

$$\text{div } \vec{F} = \frac{\partial M}{\partial x} + \frac{\partial N}{\partial y}$$

Note:

$$\text{div } \vec{F} = \lim_{\epsilon \rightarrow 0} \frac{1}{\text{Area}(D_{\epsilon}^{(x,y)})} \iint_{D_{\epsilon}^{(x,y)}} \left( \frac{\partial M}{\partial x} + \frac{\partial N}{\partial y} \right) dA$$

$$= \lim_{\epsilon \rightarrow 0} \frac{1}{\text{Area}(\bar{D}_\epsilon(x,y))} \oint_{\partial \bar{D}_\epsilon(x,y)} \vec{F} \cdot \vec{n} \, ds$$

= "flux density".

Notation = For  $f(x,y)$ ,  $\vec{\nabla} f = \frac{\partial f}{\partial x} \hat{i} + \frac{\partial f}{\partial y} \hat{j}$  (gradient)

$$= \left( \hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} \right) f$$

It is convenient to denote

$$\boxed{\vec{\nabla} = \hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y}}$$

Then

$$\vec{\nabla} \cdot \vec{F} = \left( \hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} \right) \cdot \left( M \hat{i} + N \hat{j} \right)$$

$$= \frac{\partial M}{\partial x} + \frac{\partial N}{\partial y} = \text{div} \vec{F}.$$

Hence we also write

$$\boxed{\text{div} \vec{F} = \vec{\nabla} \cdot \vec{F}}$$

$$\boxed{\text{Def 13} = \text{Define } \text{rot} \vec{F} \text{ to be } \text{rot} \vec{F} = \frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \text{ (} \vec{F} = M \hat{i} + N \hat{j} \text{)}}$$



Note :

$$\text{rot } \vec{F} = \lim_{\varepsilon \rightarrow 0} \frac{1}{\text{Area}(\bar{D}_\varepsilon)} \iint_{\bar{D}_\varepsilon} \left( \frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) dA$$

$$= \lim_{\varepsilon \rightarrow 0} \frac{1}{\text{Area}(\bar{D}_\varepsilon)} \oint_{\partial \bar{D}_\varepsilon} \vec{F} \cdot \vec{T} ds$$

= circulation density

Using  $\vec{\nabla} = \hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y}$ , we can write

$$\boxed{\text{rot } \vec{F} = (\vec{\nabla} \times \vec{F}) \cdot \hat{k}}$$

since  $\vec{F} = M \hat{i} + N \hat{j} + \text{zero} \cdot \hat{k}$  (in  $\mathbb{R}^3$ )

$$\vec{\nabla} = \hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} + \hat{k} \frac{\partial}{\partial z} \quad (\text{"gradient" in } \mathbb{R}^3)$$

$$\Rightarrow \vec{\nabla} \times \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ M & N & 0 \end{vmatrix}$$

$$\& \frac{\partial M}{\partial z} = \frac{\partial N}{\partial z} = 0$$

$$= \left( \frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) \hat{k}$$

$$\Rightarrow \text{rot } \vec{F} = (\vec{\nabla} \times \vec{F}) \cdot \hat{k}$$

$\hat{k}$ -component of "curl  $\vec{F}$ ".

where  $\boxed{\text{curl } \vec{F} = \vec{\nabla} \times \vec{F}}$ .