



Summary:

$\Omega_1$

$\Omega_2$

$$f(x,y) = \theta$$

smooth function on  $\Omega_1$

$$f(x,y) = \theta$$

is not a smooth function on  $\Omega_2$   
( $\theta$  cannot be well-defined)

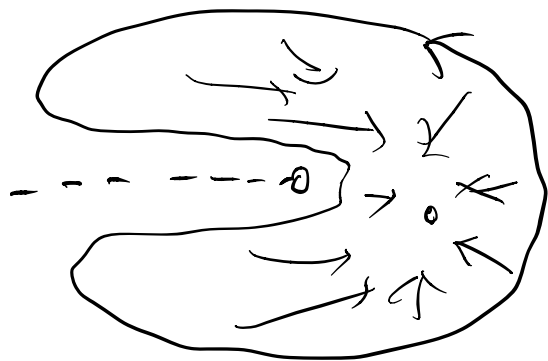
$$C: x^2 + y^2 = 1$$

is not even a curve in  $\Omega_1$

$$C: x^2 + y^2 = 1$$

is a closed curve in  $\Omega_2$

because  $(-1,0) \in C$   
 $(-1,0) \notin \Omega_1$



closed curves cannot surround the origin  $\Rightarrow$

closed curves can be deformed continuously (with in  $\Omega_1$ ) to a point.



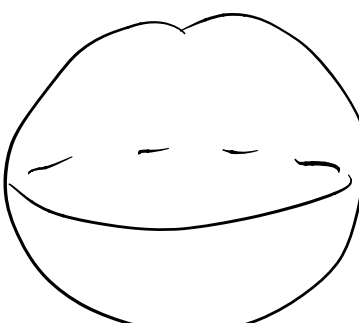
$C$  enclosed the "hole"  
 $\Rightarrow C$  cannot be deformed continuously (with in  $\Omega_2$ ) to a point.

Defn 15 A subset  $D \subseteq \mathbb{R}^n$ ,  $n=2$  or  $3$ , is called simply-connected if every closed curve in  $D$  can be contracted to a point in  $D$  without ever leaving  $D$ .

(contracted: deformed continuously)

eg 44:  $\Omega_1$  in eg 43 is simply-connected, but  $\Omega_2$  is not simply-connected.

eg 45:  $S^2 \subset \mathbb{R}^3$   $S^2: x^2 + y^2 + z^2 = 1$



is simply-connected.

eg 46: torus  $\mathbb{T}^2 \cong S^1 \times S^1 \subset \mathbb{R}^3$  is not simply-connected.



Remark: Simply connectedness is a global condition to guarantee "egts in Cor to Thm 9"  $\Rightarrow$  "conservative".

Thm 10: Suppose  $\Omega \subseteq \mathbb{R}^n$ ,  $n=2$  or  $3$ , is connected and simply-connected. Let  $\vec{F}$  be  $C^1$  vector field on  $\Omega$ . Then

$\vec{F}$  is conservative on  $\Omega$

$\Leftrightarrow$  components of  $\vec{F}$  satisfy the system of equations in the Cor to the Thm 9.

eg 47 let  $\Omega = \mathbb{R}^3$  (connected and simply connected)

$$\text{let } \vec{F} = M\hat{i} + N\hat{j} + L\hat{k}$$

$$= (y + e^z)\hat{i} + (x + 1)\hat{j} + (1 + xe^z)\hat{k}.$$

Find the potential function  $f$  of  $\vec{F}$ , i.e.

$$\vec{\nabla} f = \vec{F}.$$

Solu: This is, we want to find  $f$  s.t.

$$\frac{\partial f}{\partial x} = M, \quad \frac{\partial f}{\partial y} = N, \quad \frac{\partial f}{\partial z} = L.$$

Checking  $M, N, L$  satisfy the system of eqts in Cor to Thm 9:

$$\begin{array}{ccc}
 \frac{\partial M}{\partial x} = 0 & \frac{\partial M}{\partial y} = 1 & \frac{\partial M}{\partial z} = e^z \\
 \frac{\partial N}{\partial x} = 1 & \frac{\partial N}{\partial y} = 0 & \frac{\partial N}{\partial z} = 0 \\
 \frac{\partial L}{\partial x} = e^z & \frac{\partial L}{\partial y} = 0 & \frac{\partial L}{\partial z} = xe^z
 \end{array}$$

Thm 10  $\Rightarrow$  existence of potential function  $f$ .

To find  $f$  explicitly:

$$\frac{\partial f}{\partial x} = y + e^z$$

$$\begin{aligned}
 \Rightarrow f &= \int (y + e^z) dx = xy + xe^z + \text{"const in } x\text{"} \\
 &= xy + xe^z + g(y, z) \quad \text{for some function in } y, z
 \end{aligned}$$

$$\begin{aligned}
 x+1 &= \frac{\partial f}{\partial y} = \frac{\partial}{\partial y} (xy + xe^z + g(y, z)) \\
 &= x + \frac{\partial g}{\partial y}
 \end{aligned}$$

$$\Rightarrow \frac{\partial g}{\partial y} = 1$$

$$\begin{aligned}
 \Rightarrow g &= y + \text{"const in } y\text{"} = y + h(z) \\
 &\quad \text{for some function } h(z).
 \end{aligned}$$

$$\therefore f = yx + xe^z + y + h(z)$$

$$(1 + xe^z) = \frac{\partial f}{\partial z} = \frac{\partial}{\partial z}(yx + xe^z + y + h(z))$$

$$= xe^z + h'(z)$$

$$\Rightarrow h'(z) = 1$$

$$\Rightarrow h(z) = z + \text{const}$$

Hence

$$f(x, y, z) = yx + xe^z + y + z + C$$

where  $C$  is a constant.

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(Note: This is equivalent to find  $f$  s.t.  
total differential  $df = M dx + N dy + L dz$ )

Remark:

To prove Thm 10 in  $\mathbb{R}^2$ , we need the Green's Thm  
(in  $\mathbb{R}^3$ , we need Stokes' Thm)

## Thm 11 (Green's Theorem)

Let  $\Omega \subseteq \mathbb{R}^2$  be open;  $\vec{F} = M\hat{i} + N\hat{j}$  be  $C^1$  vector field on  $\Omega$ ;  $C$  is a piecewise smooth simple closed anti-clockwise oriented curve enclosing a region  $R$  which lies entirely in  $\Omega$ .

Then

### • Normal Form

$$\oint_C \vec{F} \cdot \vec{n} \, ds = \oint_C Mdy - Ndx = \iint_R \left( \frac{\partial M}{\partial x} + \frac{\partial N}{\partial y} \right) dx dy$$

### • Tangential Form

$$\oint_C \vec{F} \cdot \vec{T} \, ds = \oint_C Mdx + Ndy = \iint_R \left( \frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) dx dy$$

(Remark: The two forms are equivalent.)