

eg 27 let  $f(x,y,z) = \frac{1}{x^2+y^2+z^2} = \frac{1}{\rho^2}$  (unbounded at  $\rho=0$ )  
 $g(x,y,z) = \frac{1}{(\sqrt{x^2+y^2+z^2})^3} = \frac{1}{\rho^3}$

over unit ball  $B = \{(\rho, \phi, \theta) : 0 \leq \rho \leq 1\}$

"Improper Integral"

$\lim_{\epsilon \rightarrow 0} \iiint_{B \setminus B_\epsilon} f(x,y,z) dx dy dz = \text{exists?}$

where  $B_\epsilon = \{(\rho, \phi, \theta) : 0 \leq \rho \leq \epsilon\}$

$\lim_{\epsilon \rightarrow 0} \iiint_{B \setminus B_\epsilon} f(x,y,z) dx dy dz$

$= \lim_{\epsilon \rightarrow 0} \int_0^{2\pi} \int_0^\pi \int_\epsilon^1 \frac{1}{\rho^2} \cdot (\rho^2 \sin \phi d\rho d\phi d\theta)$

$= \lim_{\epsilon \rightarrow 0} \left( \int_0^{2\pi} d\theta \right) \left( \int_0^\pi \sin \phi d\phi \right) \left( \int_\epsilon^1 d\rho \right)$

$= \lim_{\epsilon \rightarrow 0} 4\pi (1-\epsilon) = 4\pi$

Hence we said that  $f = \frac{1}{x^2+y^2+z^2}$  is integrable (in sense of Improper Integral)

$$\text{For } g(x,y,z) = \frac{1}{(\sqrt{x^2+y^2+z^2})^3} = \frac{1}{\rho^3}$$

$$\Rightarrow \lim_{\varepsilon \rightarrow 0} \iiint_{B \setminus B_\varepsilon} g(x,y,z) dx dy dz$$

$$= \lim_{\varepsilon \rightarrow 0} \int_0^{2\pi} \int_0^\pi \int_\varepsilon^1 \frac{1}{\rho^3} (\rho^2 \sin \phi d\rho d\phi d\theta)$$

$$= \lim_{\varepsilon \rightarrow 0} 4\pi \log \frac{1}{\varepsilon} = +\infty \text{ not exists,}$$

(Hence we said that  $g = \frac{1}{(x^2+y^2+z^2)^{3/2}}$  is not integrable. ~~✗~~)

(Question: determine all  $\beta > 0$  such that

$f = \frac{1}{\rho^\beta}$  is integrable in  $B \subset \mathbb{R}^3$  (Ex!))

# Application of Multiple integrals (Thomas' calculus §15.6)

In applications, we often use the following:

In 2-dim. :  $R$  is a region in  $\mathbb{R}^2$  with density  $\delta(x,y)$ .

- First moment about  $y$ -axis:

$$M_y = \iint_R x \delta(x,y) dA$$

- First moment about  $x$ -axis:

$$M_x = \iint_R y \delta(x,y) dA$$

- Mass :  $M = \iint_R \delta(x,y) dA$

- Center of Mass (Centroid):

$$(\bar{x}, \bar{y}) = \left( \frac{M_y}{M}, \frac{M_x}{M} \right).$$

In 3-dim,  $D$  solid region in  $\mathbb{R}^3$  with  $\delta(x,y,z)$

## First moments

- about  $yz$ -plane:

$$M_{yz} = \iiint_D x \delta(x,y,z) dV$$

- about  $xz$ -plane:

$$M_{xz} = \iiint_D y \delta(x,y,z) dV$$

- about  $xy$ -plane:

$$M_{xy} = \iiint_D z \delta(x,y,z) dV$$

- Mass:  $M = \iiint_D \delta(x,y,z) dV$

- Center of Mass (Centroid)

$$(\bar{x}, \bar{y}, \bar{z}) = \left( \frac{M_{yz}}{M}, \frac{M_{xz}}{M}, \frac{M_{xy}}{M} \right)$$

In 2-dim,  $R$  region in  $\mathbb{R}^2$  with density  $\delta(x,y)$

## Moment of inertia

• about the  $x$ -axis 
$$I_x = \iint_R y^2 \delta(x,y) dA$$

• about the  $y$ -axis 
$$I_y = \iint_R x^2 \delta(x,y) dA$$

• about the line  $L$

$$I_L = \iint_R r(x,y)^2 \delta(x,y) dA$$

where  $r(x,y)$  = distance between  $(x,y)$  and  $L$ .

• about the origin 
$$I_0 = \iint_R (x^2 + y^2) \delta(x,y) dA$$

In 3-dim.  $D$  solid region in  $\mathbb{R}^3$  with density  $\delta(x,y,z)$

## Moments of Inertia

• around  $x$ -axis :  $I_x = \iiint_D (y^2 + z^2) \delta(x,y,z) dV$

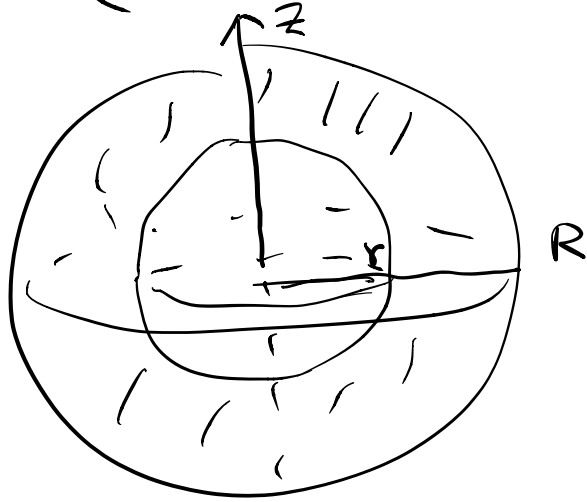
• around  $y$ -axis :  $I_y = \iiint_D (x^2 + z^2) \delta(x,y,z) dV$

• around  $z$ -axis :  $I_z = \iiint_D (x^2 + y^2) \delta(x,y,z) dV$

• around line  $L$  :  $I_L = \iiint_D r(x,y,z)^2 \delta(x,y,z) dV$

where  $r(x,y,z)$  = distance between  $(x,y,z)$  and  $L$ .

eg 28: Consider  $D: r^2 \leq x^2 + y^2 + z^2 \leq R^2$   
 with density  $\delta(x, y, z) \equiv \delta$ . Express  $I_z$  in  
 terms of  $m = \text{mass of } D (= \delta \text{Vol}(D))$   
 $r$  and  $R$ .



$$\begin{aligned}
 \text{Soln: } I_z &= \iiint_D (x^2 + y^2) \cdot 1 \, dV \\
 &= \int_0^{2\pi} \int_0^\pi \int_r^R (\rho^2 \sin^2 \phi) (\rho^2 \sin \phi \, d\rho \, d\phi \, d\theta) \\
 &= \left( \int_0^{2\pi} d\theta \right) \left( \int_0^\pi \sin^3 \phi \, d\phi \right) \left( \int_r^R \rho^4 \, d\rho \right) \\
 &= (2\pi) \left( \frac{4}{3} \right) \left( \frac{R^5 - r^5}{5} \right) \\
 &= \frac{8\pi}{15} (R^2 - r^2) \delta
 \end{aligned}$$

$$\text{Mass } m = \delta \text{Vol}(\Omega) = \frac{4\pi}{3} (R^3 - r^3) \delta$$

$$\Rightarrow \boxed{I_z = \frac{2m}{5} \frac{R^5 - r^5}{R^3 - r^3}} \quad (\text{true for } \delta=1)$$

There are two interesting special cases:

(i)  $r \rightarrow 0$ , i.e. the whole solid ball

$$\Rightarrow \boxed{I_z = \frac{2m}{5} R^2}$$

(ii)  $r \rightarrow R$ , i.e. a (hollow) sphere made of infinitesimally thin sheet.

$$\Rightarrow \boxed{\begin{aligned} I_z &= \lim_{r \rightarrow R} \frac{2m}{5} \frac{R^5 - r^5}{R^3 - r^3} \\ &= \frac{2m}{5} \cdot \frac{5R^4}{3R^2} = \frac{2mR^2}{3} \end{aligned}}$$

Moment of inertia of hollow sphere

> the solid ball (assuming the same mass)