

7. Mobius strip or band

$$[0,1] \times [0,1] / \sim \quad \text{where} \quad (s_1, s_2) \sim (t_1, t_2) \quad \text{if}$$

$$(s_1, s_2) = (t_1, t_2) \quad \text{or} \quad \begin{cases} |s_1 - t_1| = 0, 1 \\ s_2 = 1 - t_2 \end{cases}$$

For simplicity, often say
 identify $(0, t)$ with $(1, 1-t)$ on $[0,1]^2$

8. Klein Bottle

Identify $(s, 0)$ with $(s, 1)$ and
 $(0, t)$ with $(1, 1-t)$ on $[0,1]^2$

Note. Klein Bottle $\not\cong \mathbb{R}^3$

But basic neighborhoods of any point
 \cong homeo.

$$\{z \in \mathbb{C} : |z| < 1\}$$

9. Projective Plane, \mathbb{RP}^2

Identify $(s, 0)$ with $(1-s, 1)$ and
 $(0, t)$ with $(1, 1-t)$ on $[0,1]^2$

OR

Identify z with $-z$ if $|z|=1$ on
 $\{z \in \mathbb{C} : |z| \leq 1\}$

Exercise. Show they are homeomorphic.

Given (X, \mathcal{J}_X) and \sim on X

$$q: X \xrightarrow{\text{onto}} X/\sim \text{ or any } Q$$

$$\mathcal{J}_q = \{ V \subset X/\sim \text{ or } Q : q^{-1}(V) \in \mathcal{J}_X \}$$

QT1 $q: (X, \mathcal{J}_X) \rightarrow (X/\sim \text{ or } Q, \mathcal{J}_q)$ is continuous

Obvious, because if $V \in \mathcal{J}_q$,
by definition, $q^{-1}(V) \in \mathcal{J}_X$

QT2 \mathcal{J}_q is the maximal topology on X/\sim or Q
to make $q: (X, \mathcal{J}_X) \rightarrow X/\sim$ or Q cts.

Suppose $q: (X, \mathcal{J}_X) \rightarrow (X/\sim, \mathcal{J}')$ is continuous

Let $V \in \mathcal{J}'$, Then $q^{-1}(V) \in \mathcal{J}_X$

By def, $V \in \mathcal{J}_q. \therefore \mathcal{J}' \subset \mathcal{J}_q$

QT3 $f: X/\sim \text{ or } Q \rightarrow Z$ is continuous

$\Leftrightarrow f \circ q: X \rightarrow Z$ is continuous

" \Rightarrow " Trivial

" \Leftarrow " Easy. Basically $(f \circ q)^{-1} = q^{-1} \circ f^{-1}$

QT4 \mathcal{J}_q is the minimal topology on X/\sim or Q
to make QT3 true.

Exercise.

Disjoint Union

Put two copies of X together $\neq X \cup X$

Define $X \sqcup X = (X \times \{0\}) \cup (X \times \{1\})$

A useful example

Let $X = [-1, 1] \sqcup [-1, 1]$

Identify $(x, 0)$ with $(x, 1)$ if $x \neq 0$

Picture

Qu. Is X/\sim Hausdorff?

Any nbhds of $(0, 0)$ & $(0, 1)$ intersect!

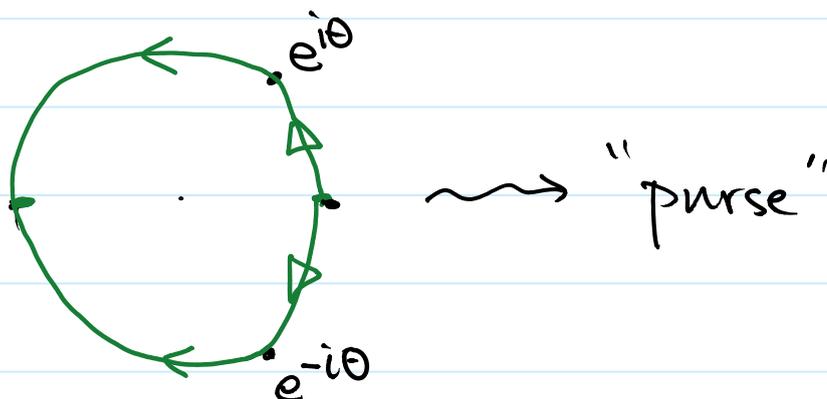
Sphere

Given $\mathbb{D}^2 = \{z \in \mathbb{C} : |z| \leq 1\} \subset \mathbb{R}^2$, standard

1. Identify $S^1 = \{z \in \mathbb{C} : |z| = 1\}$ to one point

i.e. $z \sim w$ if $|z| = |w| = 1$

2. Identify $e^{i\theta}$ with $e^{-i\theta}$ for all θ



Attaching Space

Given $X, Y; A \subset X; f: A \rightarrow Y$

Define $X \cup_f Y$ by $(X \cup Y) / \sim$ where

$(a, 0)$ is identified with $(f(a), 1), a \in A$

Usually, we say:

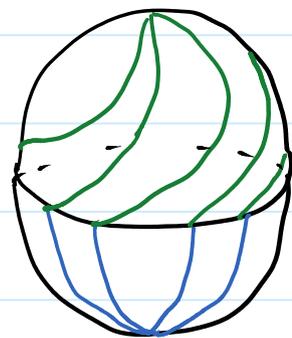
Attach X to Y along A by f

(i) $X = \mathbb{D}^2 = Y, A = S^1, f = \text{id}: S^1 \rightarrow S^1$

$X \cup_f Y = S^2$, just like N-S hemisphere

(ii) $X = \mathbb{D}^2 = Y, A = S^1, f(e^{i\theta}) = e^{i(\theta + \alpha)}$

$X \cup_f Y = S^2$



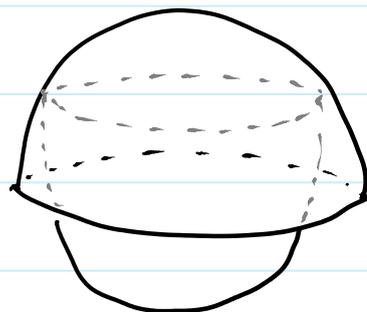
(iii) $X = \mathbb{D}^2 = Y, A = S^1$

$f(e^{i\theta}) = e^{2i\theta}$

$X \cup_f Y$ is not a surface

(iv) $X = \mathbb{D}^2 = Y, A = S^1$

$f(e^{i\theta}) = \frac{1}{2}e^{i\theta}$



Handle Body

(i) $X = S^2 \setminus (D_1 \cup D_2)$ where $D_1 = D_2 = D^2$

$Y = S^1 \times [0, 1]$

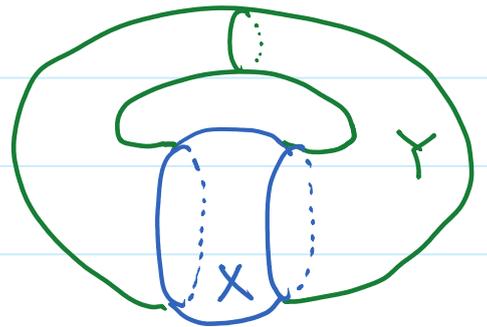
$A = \partial X = S_1 \cup S_2$ where $S_1 = S_2 = S^1$

Note that $\partial Y = S^1 \times \{0\} \cup S^1 \times \{1\}$

Let $f: A \rightarrow \partial Y$

be a homeomorphism

Then $X \cup_f Y = \text{Torus}$



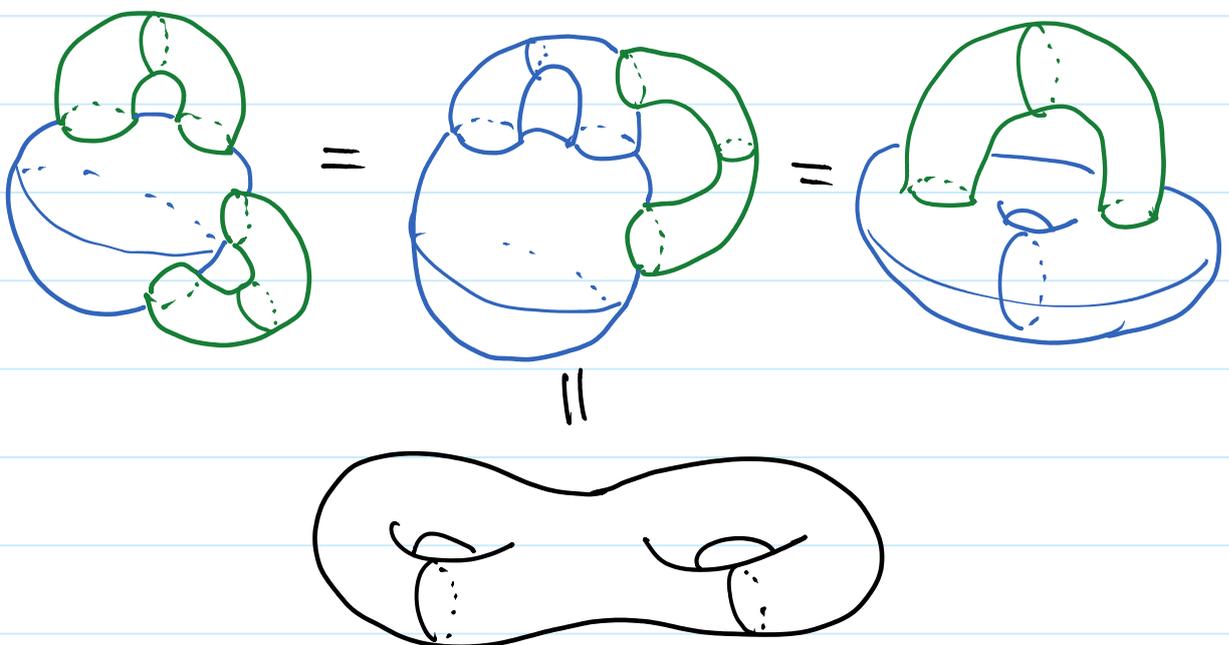
Usual say,

Attach a handle to a sphere

(ii) Attach two handles to a sphere

||

Attach a handle to a torus



Projective Plane $\mathbb{R}P^2$

1. Identify $(s, 0) \sim (1-s, 1)$ and $(0, t) \sim (1, 1-t)$
on $[0, 1] \times [0, 1]$
2. Identify $e^{i\theta} \sim -e^{i\theta}$ on $D^2 = \{ |z| \leq 1 \}$

3. Let $X = \mathbb{R}^3 \setminus \{0\}$ and $x \sim y$ if
 $\exists \lambda \neq 0$ such that $x = \lambda y$
i.e., $x, y, 0$ are on a straight line
 X/\sim becomes the space of lines in \mathbb{R}^3

4. Let $S^2 = \{ u \in \mathbb{R}^3 : \|u\| = 1 \}$

Then $u, -u$ are called **antipodal points**

In fact, $u, 0, -u$ form a diameter

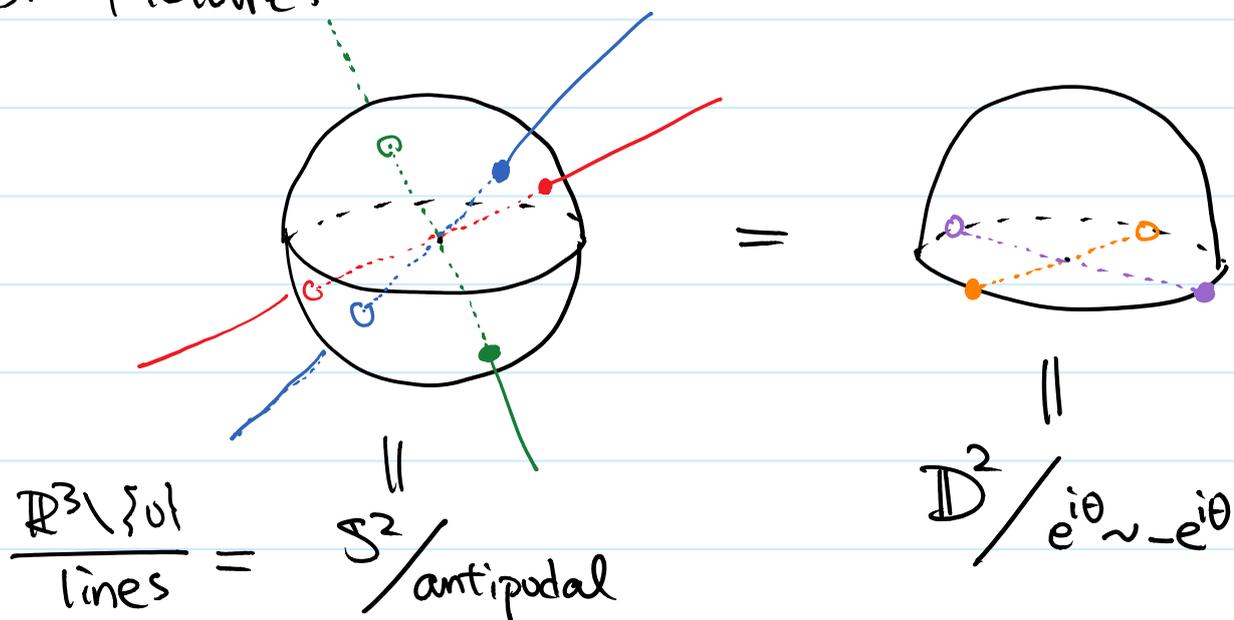
Fact. $S^2 / \text{antipodal points} = \mathbb{R}^3 \setminus \{0\} / \text{st. lines}$

$$[u] \longmapsto [u]$$

$$\left[\frac{x}{\|x\|} \right] \longleftarrow [x]$$

Exercise. Show that it is a homeomorphism

5. Pictures



$$[x] \longmapsto [\pi(x)]$$

where $\pi: \mathbb{R}^3 \rightarrow \mathbb{R}^2$

$$(x_1, x_2, x_3) \longmapsto (x_1, x_2, 0)$$

Exercise. Show that it is a homeomorphism

6. Let $M_n(\mathbb{R}) = \{n \times n \text{ matrices over } \mathbb{R}\}$

$$M_n(\mathbb{R}) \longrightarrow M_{n+1}(\mathbb{R}) : A \longmapsto \begin{pmatrix} 1 & 0 & \dots & 0 \\ \vdots & & & \\ 0 & & & A \end{pmatrix}$$

$$O_n(\mathbb{R}) = \{n \times n \text{ orthogonal matrices}\}$$

$$= \{Q \in M_n(\mathbb{R}) : Q^T Q = Q Q^T = I\}$$

Denote $O_3/O_2 = \{\text{left cosets}\}$

$$= \{A \cdot O_2 : A \in O_3\}$$

In O_3/O_2 , $A \cdot O_2 = B \cdot O_2$ if $A^{-1}B \in O_2$

In other words, $A \sim B$ on O_3 if $A^{-1}B \in O_2$

$$\text{i.e. } A^{-1}B = \begin{bmatrix} 1 & 0 & 0 \\ 0 & Q \\ 0 & & \end{bmatrix} \quad \text{where } Q \in O_2$$

Thus, $A^{-1}B(e_i) = e_i$ or $A(e_i) = B(e_i)$

Also, $A^{-1}B|_{0 \times \mathbb{R}^2} : 0 \times \mathbb{R}^2 \rightarrow 0 \times \mathbb{R}^2$

is an isometry (given by Q)

Anyway, $O_3/O_2 \longrightarrow S^2$ by

$A \cdot O_2 \longmapsto A(e_i)$ is well-defined

Exercise. This is a homeomorphism

Now, denote $\pm O_2 = \left\{ \begin{bmatrix} \pm 1 & 0 & 0 \\ 0 & Q \\ 0 & & \end{bmatrix} : Q \in O_2 \right\}$

Then, only difference, if $A \sim B$

then $A(e_i) = \pm B(e_i)$

And $O_3/\pm O_2 \longrightarrow \mathbb{RP}^2$

$A \cdot (\pm O_2) \longmapsto [\pm A(e_i)]$

Projective Space $\mathbb{RP}^n = O_{n+1}/\pm O_n$
"n-dim spaces in \mathbb{R}^{n+1} "