

Corollary (to Thm 9)

Let \vec{F} be conservative and C^1

($n=3$) If $\vec{F} = M\hat{i} + N\hat{j} + L\hat{k}$ ($m \Omega \subset \mathbb{R}^3$)

then

$$\left\{ \begin{array}{l} \frac{\partial M}{\partial y} = \frac{\partial N}{\partial x} \\ \frac{\partial N}{\partial z} = \frac{\partial L}{\partial y} \\ \frac{\partial L}{\partial z} = \frac{\partial M}{\partial z} \end{array} \right.$$

($n=2$) If $\vec{F} = M\hat{i} + N\hat{j}$ ($m \Omega \subset \mathbb{R}^2$)

then

$$\frac{\partial M}{\partial x} = \frac{\partial N}{\partial y}$$

Pf: \vec{F} conservative $\xrightarrow{\text{Thm 9}} \vec{F} = \vec{\nabla} f$ for some function f

i.e.

$$\begin{aligned} \vec{\nabla} f &= \frac{\partial f}{\partial x} \hat{i} + \frac{\partial f}{\partial y} \hat{j} + \frac{\partial f}{\partial z} \hat{k} \\ &= M\hat{i} + N\hat{j} + L\hat{k} = \vec{F} \end{aligned}$$

$\vec{F} \in C^1 \Rightarrow f \in C^2$. Hence Mixed derivatives theorem

(Clairaut's Thm)

$$\left\{ \begin{array}{l} \frac{\partial M}{\partial y} = \frac{\partial^2 f}{\partial y \partial x} = \frac{\partial^2 f}{\partial x \partial y} = \frac{\partial N}{\partial x} \\ \frac{\partial N}{\partial z} = \frac{\partial^2 f}{\partial z \partial y} = \frac{\partial^2 f}{\partial y \partial z} = \frac{\partial L}{\partial y} \\ \frac{\partial L}{\partial x} = \frac{\partial^2 f}{\partial x \partial z} = \frac{\partial^2 f}{\partial z \partial x} = \frac{\partial M}{\partial z} \end{array} \right.$$

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(Similarly for $n=2$)

eg 42: Show that $\vec{F}(x,y) = \hat{i} + x\hat{j}$ is not conservative on \mathbb{R}^2

Soln: $(\vec{F} \in C^\infty) \begin{cases} M \equiv 1 \\ N = x \end{cases} \Rightarrow \frac{\partial M}{\partial y} = 0 \neq 1 = \frac{\partial N}{\partial x}$.

By Cor to Thm 9, \vec{F} is not conservative. ✘

Remark (Important)

For a C^1 vector field $\vec{F} = M\hat{i} + N\hat{j} + L\hat{k}$

\vec{F} conservative

Cor to Thm 9
 $\xrightarrow{\hspace{2cm}}$
 $\xleftarrow{\hspace{2cm}}$
 ?

M, N, L satisfy the system of PDE in Cor to Thm 9.

Answer: Not true in general, needs extra condition on the domain Ω .

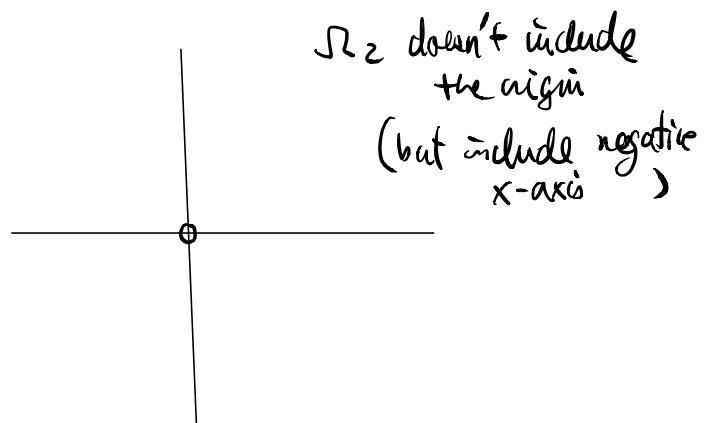
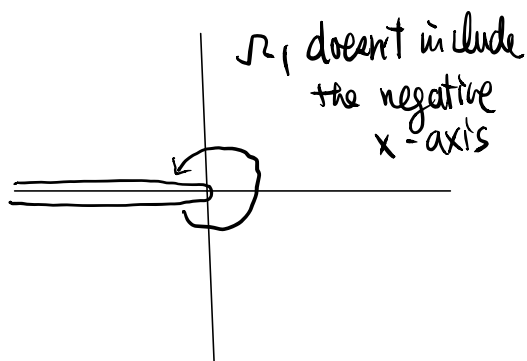
eg 43 Consider the vector field

$$\vec{F} = \frac{-y}{x^2+y^2} \hat{i} + \frac{x}{x^2+y^2} \hat{j}$$

and the domains

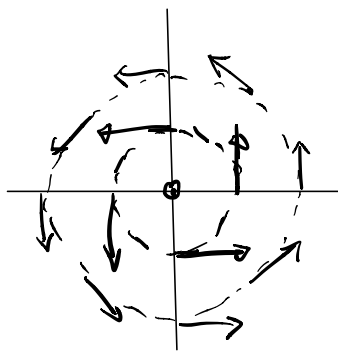
$$\Omega_1 = \mathbb{R}^2 \setminus \{(x,0) \in \mathbb{R}^2 : x \leq 0\}$$

$$\Omega_2 = \mathbb{R}^2 \setminus \{(0,0)\}$$



In polar coordinates

$$\vec{F} = -\frac{\sin\theta}{r} \hat{i} + \frac{\cos\theta}{r} \hat{j}$$



$\Rightarrow \vec{F}$ rotates around the origin anti-clockwise

$$|\vec{F}| = \frac{1}{r} \rightarrow 0 \text{ as } r \rightarrow \infty$$

$|\vec{F}| = \frac{1}{r} \rightarrow +\infty \text{ as } r \rightarrow 0 \Rightarrow \vec{F}$ cannot be extended to a C^1 vector field on \mathbb{R}^2 .

Besides $(0,0)$, \vec{F} is C^1 and hence \vec{F} is C^1 on Ω_1 and also C^1 on Ω_2 .

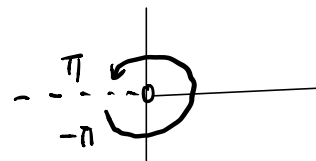
Questions: Is \vec{F} conservative on Ω_1 ?

Is \vec{F} conservative on Ω_2 ?

Soln: (1) For Ω_1 , and (x,y) can be expressed in polar coordinates with

$$\left. \begin{array}{l} r > 0 \\ -\pi < \theta < \pi \end{array} \right\} \text{ ((r, } \theta \text{) are unique)}$$

Define $f(x,y) = \theta$ "smooth" on Ω_1

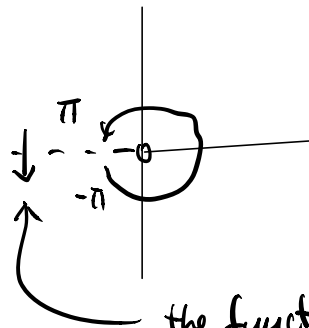


$$\text{Then } \left\{ \begin{array}{l} \frac{\partial f}{\partial x} = -\frac{\sin\theta}{r} \\ \frac{\partial f}{\partial y} = \frac{\cos\theta}{r} \end{array} \right. \quad \left(\theta_x = -\frac{\sin\theta}{r}, \theta_y = \frac{\cos\theta}{r} \right)$$

$$\Rightarrow \vec{F} = \frac{\partial f}{\partial x} \hat{i} + \frac{\partial f}{\partial y} \hat{j} = \vec{\nabla} f$$

$\Rightarrow \vec{F}$ is conservative.

(2) For Ω_2 , the function $f(x,y) = \theta$ cannot be extended to a "smooth" function on (the whole) Ω_2



the function $f = \theta$ "jump" at the negative x-axis, $\Rightarrow f$ is not continuous. $\Rightarrow \nabla f$ doesn't define on whole Ω_2

$\therefore f(x,y) = \theta$ doesn't work in the case of Ω_2

To show that \vec{F} is not conservative,

we consider a closed curve

$$C : \vec{r}(t) = \cos t \hat{i} + \sin t \hat{j}, \quad t \in [-\pi, \pi] \quad \begin{matrix} \text{(unit circle)} \\ \text{in } \Omega_2 \\ \text{(not a curve in } \Omega_1) \end{matrix}$$

Then

$$\begin{aligned} \oint_C \vec{F} \cdot d\vec{r} &= \int_{-\pi}^{\pi} \left(-\frac{\sin \theta}{r} \hat{i} + \frac{\cos \theta}{r} \hat{j} \right) \cdot \vec{r}'(t) dt \\ &= \int_{-\pi}^{\pi} (-\sin t \hat{i} + \cos t \hat{j}) \cdot (-\sin t \hat{i} + \cos t \hat{j}) dt \\ &= \int_{-\pi}^{\pi} 1 \cdot dt = 2\pi \neq 0 \end{aligned}$$

By Thm 9, \vec{F} is not conservative. ~~✗~~

Summary:

Ω_1

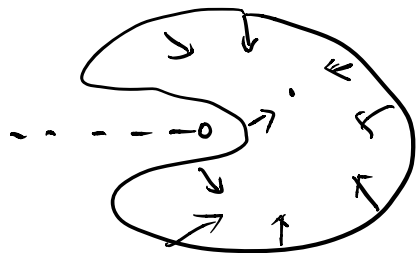
Ω_2

$f(x,y) = \theta$
smooth function on Ω_1

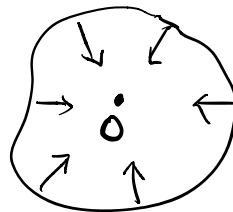
$f(x,y) = \theta$
is not a smooth function on Ω_2
(θ cannot be well-defined on the whole Ω_2)

$C: x^2 + y^2 = 1$
is not a curve in Ω_1
because $(-1, 0) \in C$,
 $(-1, 0) \notin \Omega_1$

$C: x^2 + y^2 = 1$
is a closed curve in Ω_2



Closed curves cannot circle around the origin \Rightarrow
closed curves can be deformed continuously (with in Ω_1) to a point (in Ω_1)




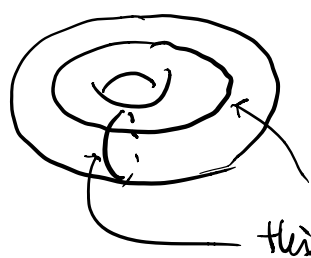
C enclosed the "hole"
 $\Rightarrow C$ cannot be deformed continuously (with in Ω_2) to a point (in Ω_2)

Def 15 A subset $D \subseteq \mathbb{R}^n$, $n=2$ or 3 , is called simply-connected if every closed curve in D can be contracted to a point in D without ever leaving D .

(contracted: deformed continuously)

eg 44: Ω_1 in eg 43 is simply-connected, but Ω_2 is not simply-connected.

eg 45: $S^2 \subset \mathbb{R}^3$ $S^2: x^2 + y^2 + z^2 = 1$
 is simply-connected

eg 46:
 torus $\mathbb{T}^2 \simeq S^1 \times S^1 \subset \mathbb{R}^3$ is not simply-connected
 this closed curve cannot be contracted to a point on \mathbb{T}^2 .

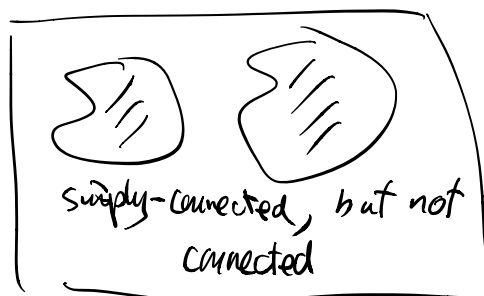
Remark: Simply-connectedness is a global condition to guarantee "egts in Cor to Thm 9" \Rightarrow "conservative".

Thm 10: Suppose $\Omega \subset \mathbb{R}^n$, $n=2$ or 3 , is connected and simply-connected. Let \vec{F} be C^1 vector field on Ω . Then \vec{F} is conservative on $\Omega \iff$ components of \vec{F} satisfy the system of PDE in the Cor to the Thm. 9.

eg 47: Let $\Omega \equiv \mathbb{R}^3$

(connected and simply-connected)

$$\begin{aligned}\vec{F} &= M\hat{i} + N\hat{j} + L\hat{k} \\ &= (y+e^z)\hat{i} + (x+1)\hat{j} + (1+xe^z)\hat{k}\end{aligned}$$



Find the potential function f of \vec{F} , i.e.

$$\vec{\nabla} f = \vec{F}.$$

Soln: This is, we want to solve

$$\frac{\partial f}{\partial x} = M, \quad \frac{\partial f}{\partial y} = N, \quad \frac{\partial f}{\partial z} = L.$$

Checking M, N, L satisfy the system of PDE in Cor to Thm 9:

$$\begin{array}{ccc}\frac{\partial M}{\partial x} = 0 & \frac{\partial M}{\partial y} = 1 & \frac{\partial M}{\partial z} = e^z \\ \frac{\partial N}{\partial x} = 1 & \frac{\partial N}{\partial y} = 0 & \frac{\partial N}{\partial z} = 0 \\ \frac{\partial L}{\partial x} = e^z & \frac{\partial L}{\partial y} = 0 & \frac{\partial L}{\partial z} = xe^z\end{array}$$

Thm 10 \Rightarrow existence of potential function f .

To find f explicitly:

$$\frac{\partial f}{\partial x} = y + e^z$$

$$\Rightarrow f = \int (y + e^z) dx = x(y + e^z) + \text{"const in } x\text{"}$$

\uparrow function indep. of x

$$= xy + xe^z + g(y, z) \quad \text{for some function } g(y, z)$$

$$\Rightarrow x+1 = \frac{\partial f}{\partial y} = \frac{\partial}{\partial y} (xy + xe^z + g(y, z)) = x + \frac{\partial g}{\partial y}$$

$$\Rightarrow \frac{\partial g}{\partial y} = 1$$

$$\Rightarrow g = y + \text{"const in } y\text{"}$$

$$= y + h(z) \quad \text{for some function } h(z)$$

$$\Rightarrow f = xy + xe^z + y + h(z)$$

$$1 + xe^z = \frac{\partial f}{\partial z} = \frac{\partial}{\partial z} (xy + xe^z + y + h(z))$$

$$= xe^z + h'(z)$$

$$\Rightarrow h'(z) = 1$$

$$\Rightarrow h(z) = z + \text{const.}$$

Hence $f(x, y, z) = xy + xe^z + y + z + C$, where C is a constant,
is the required potential. . $\#$

(Note: This is equivalent to find f s.t.

the total differential $df = Mdx + Ndy + Ldz$)

Remark : To prove Thm 10 in \mathbb{R}^2 , we need the Green's Thm
(in \mathbb{R}^3 , we need the Stokes' Thm)

Thm 11 (Green's Theorem)

Let $\Omega \subseteq \mathbb{R}^2$ be open, $\vec{F} = M\hat{i} + N\hat{j}$ be C^1 vector field on Ω ;

C is a piecewise "smooth" simple closed anti-clockwise oriented curve enclosing a region R which lies entirely in Ω .

Then

• Normal Form

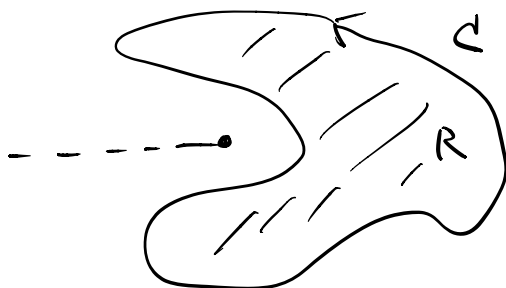
$$\oint_C \vec{F} \cdot \hat{n} \, ds = \oint_C M \, dy - N \, dx = \iint_R \left(\frac{\partial M}{\partial x} + \frac{\partial N}{\partial y} \right) dx \, dy$$

• Tangential Form

$$\oint_C \vec{F} \cdot \hat{T} \, ds = \oint_C M \, dx + N \, dy = \iint_R \left(\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) dx \, dy$$

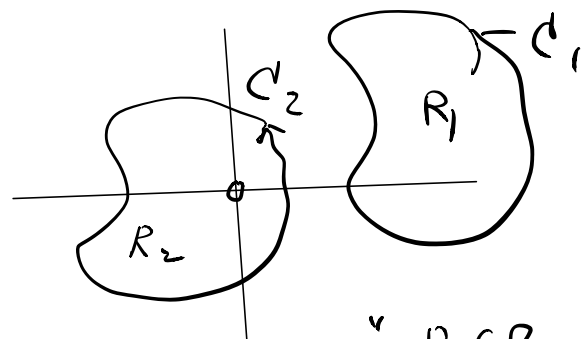
(Remark: The two forms are equivalent.)

Note: $\Omega_1 = \mathbb{R}^2 \setminus \{x \leq 0\}$



Green's Thm applies on $R \subset \Omega_1$

$\Omega_2 = \mathbb{R}^2 \setminus \{(0,0)\}$



$R_2 \not\subset \Omega_2$

(since $(0,0) \notin \Omega_2$)

Green's Thm doesn't apply to $C_2 \& R_2$!

" $R_1 \subset \Omega_2$ "
Green's Thm applies