

# Tutorial 11 for MATH3270a

Rong ZHANG\*

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In this tutorial, we will use an example to illustrate how to solve a 1<sup>st</sup> order nonlinear system.

Consider the following system

$$\begin{aligned}\frac{dx}{dt} &= (2+x)(y-x), \\ \frac{dy}{dt} &= (4-x)(y+x);\end{aligned}$$

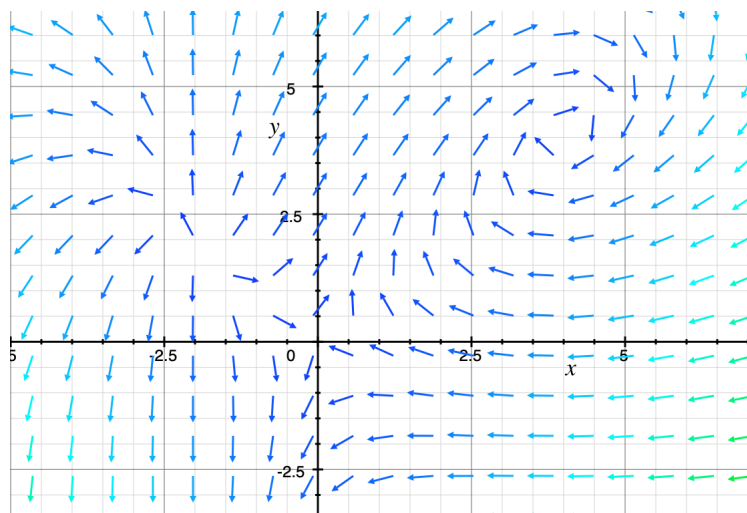
1. Find all the critical points of the system.

Let  $F = (2+x)(y-x)$ ,  $G = (4-x)(y+x)$ , then by solving

$$\begin{aligned}F &= 0, \\ G &= 0,\end{aligned}$$

we find all critical points  $P_1 = (0,0)$ ,  $P_2 = (-2,2)$ ,  $P_3 = (4,4)$ .

2. Draw the direction field of the system.



3. Find the corresponding linear system near each critical points.

Compute

$$\frac{d(F,G)}{d(x,y)} = \begin{pmatrix} y-2x-2 & 2+x \\ 4-y-2x & 4-x \end{pmatrix}$$

so the corresponding linear system near each critical point is given by

$$\frac{d}{dt} \begin{pmatrix} x \\ y \end{pmatrix} = A(P_i) \begin{pmatrix} x \\ y \end{pmatrix}$$

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\*Any questions on tutorial notes, please email me at rzhang@math.cuhk.edu.hk

where

$$A(P_1) = \begin{pmatrix} -2 & 2 \\ 4 & 4 \end{pmatrix}, \quad A(P_2) = \begin{pmatrix} 4 & 0 \\ 6 & 6 \end{pmatrix}, \quad A(P_3) = \begin{pmatrix} -6 & 6 \\ -8 & 0 \end{pmatrix}.$$

4. Determine the type and stability of each critical points;

The eigenvalues of  $A(P_1)$  are  $\lambda_1 = 1 - \sqrt{17} < 0$ ,  $\lambda_2 = 1 + \sqrt{17} > 0$ , so the critical point  $P_1 = (0, 0)$  is a saddle point and unstable. Moreover, the corresponding eigenvectors are

$$r_1 = \begin{pmatrix} 2 \\ 3 - \sqrt{17} \end{pmatrix}, \quad r_2 = \begin{pmatrix} 2 \\ 3 + \sqrt{17} \end{pmatrix}.$$

The eigenvalues of  $A(P_2)$  are  $\lambda_1 = 4$ ,  $\lambda_2 = 6$ , so the critical point  $P_2 = (-2, 2)$  is a node and unstable. Moreover, the corresponding eigenvectors are

$$r_1 = \begin{pmatrix} 1 \\ -3 \end{pmatrix}, \quad r_2 = \begin{pmatrix} 0 \\ 1 \end{pmatrix}.$$

The eigenvalues of  $A(P_3)$  are  $\lambda = -3 \pm \sqrt{39}i$ , so the critical point  $P_3 = (4, 4)$  is a spirial point and stable. Note that the direction at point  $(5, 4)$  is  $\begin{pmatrix} -6 \\ -40 \end{pmatrix}$ , so the trajectory around  $P_3 = (4, 4)$  moves in clockwise direction to  $P_3$ .

5. Draw the phase portrait.

