

Tutorial 8

* (Total) differentiability $\rightarrow \exists$ "good linear approximation"
 \rightarrow Chain rule
 $\rightarrow \forall \vec{a} \cdot \vec{u} = D_{\vec{u}} f(\vec{a})$

A function $f: \mathbb{R} \rightarrow \mathbb{R}$ is differentiable at $a \in \mathbb{R}$ if
 $\exists k \in \mathbb{R}$ such that (def.)

$$\lim_{h \rightarrow 0} \frac{f(a+h) - f(a)}{h} = k$$

$$\lim_{h \rightarrow 0} \frac{f(a+h) - f(a) - kh}{h} = 0$$

$$\lim_{h \rightarrow 0} \frac{f(a+h) - f(a) - T(h)}{h} = 0,$$

where $T: \mathbb{R} \rightarrow \mathbb{R}$ is a linear transformation.
 $h \mapsto kh$

A natural generalization to higher dimensions:

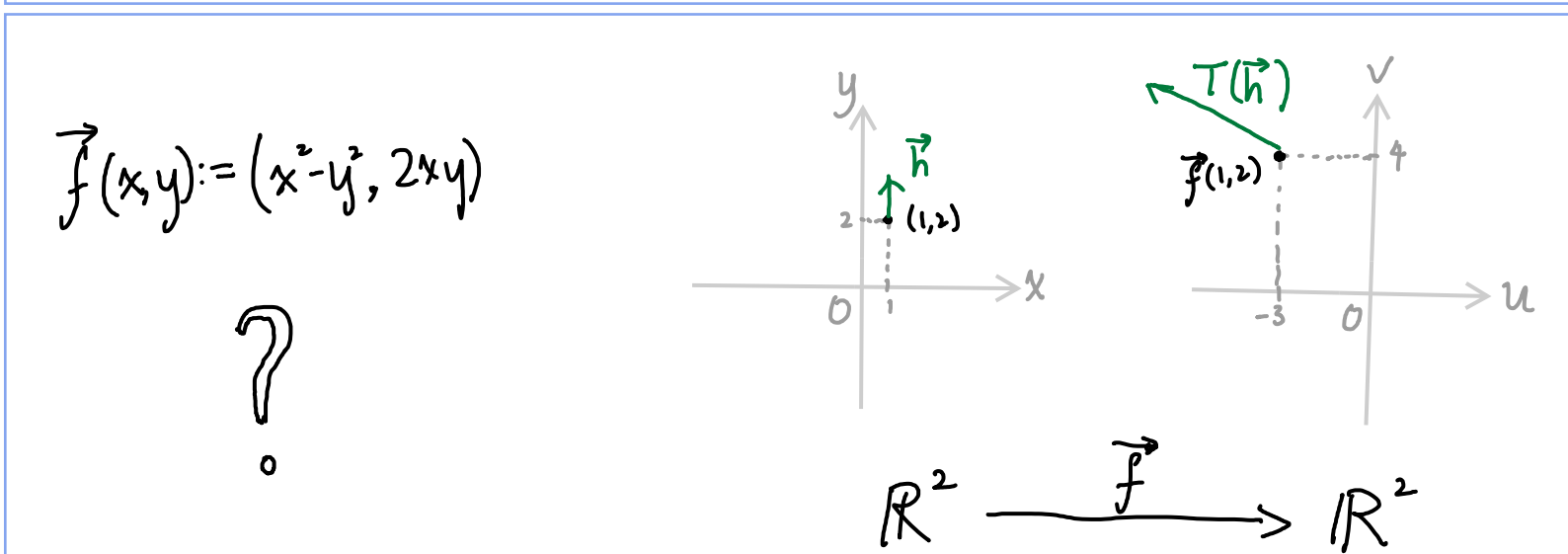
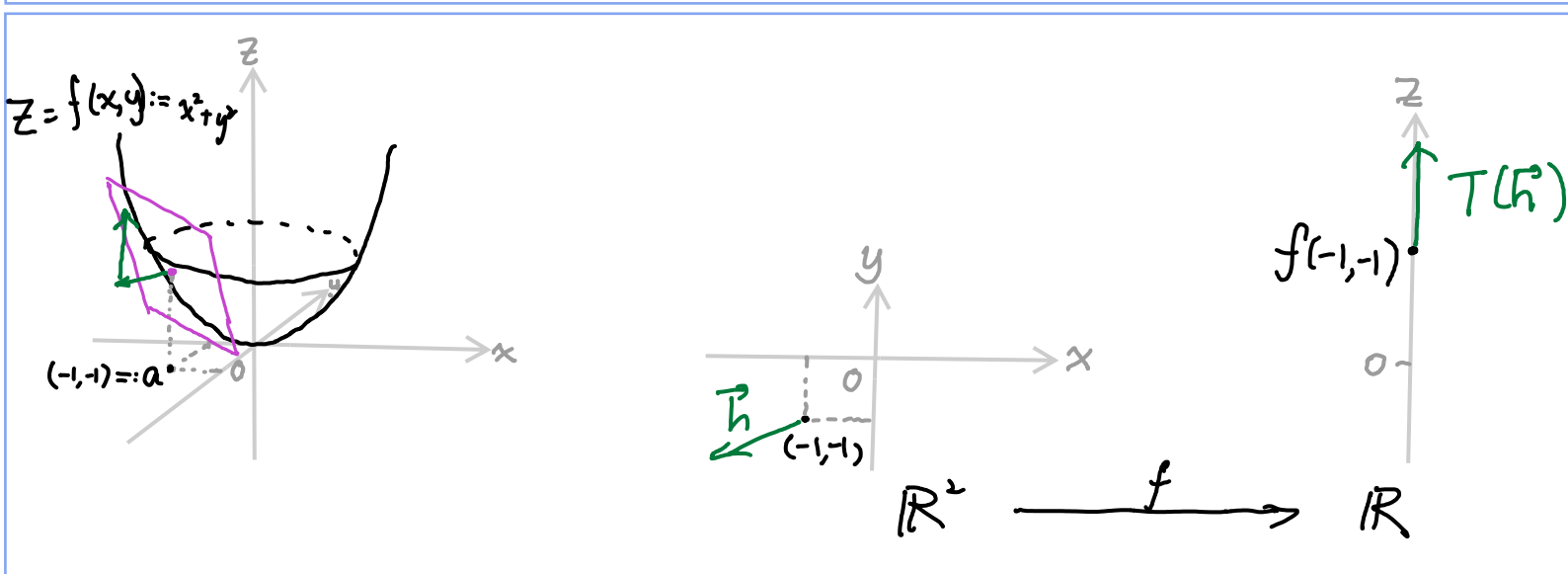
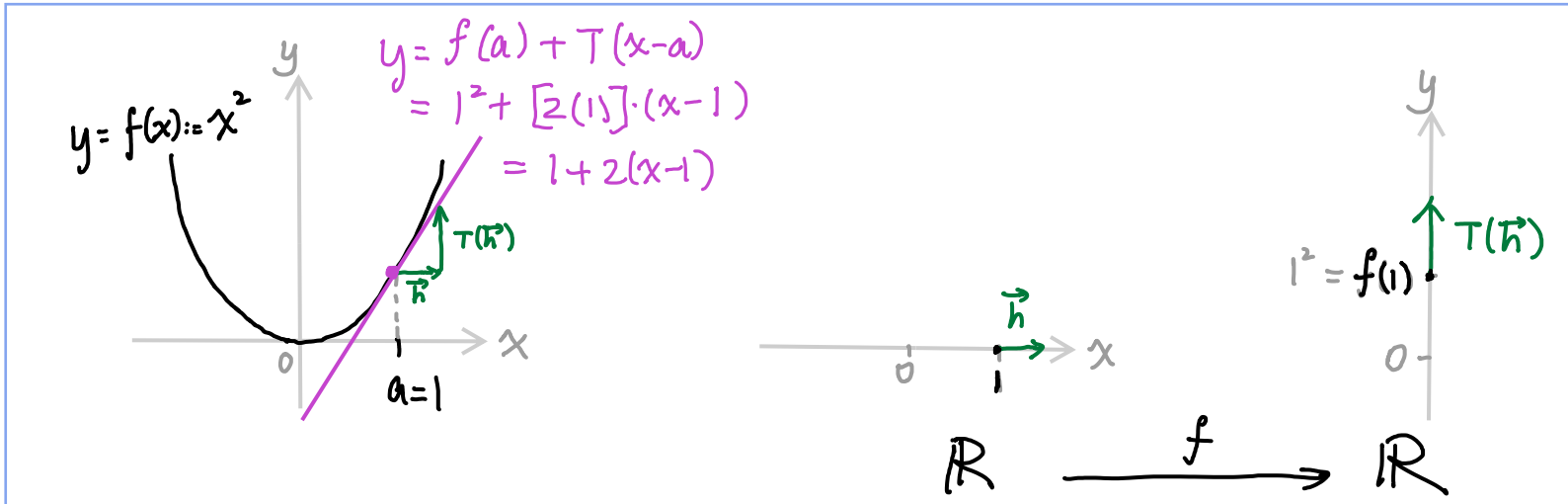
A function $\vec{f}: \mathbb{R}^n \rightarrow \mathbb{R}^m$ is differentiable at $\vec{a} \in \mathbb{R}^n$ if (def.)
 \exists linear transformation $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ such that

$$\lim_{\vec{h} \rightarrow \vec{0}} \frac{\|\vec{f}(\vec{a} + \vec{h}) - \vec{f}(\vec{a}) - T(\vec{h})\|}{\|\vec{h}\|} = 0$$

It could be shown that such linear transformation is unique and its matrix representation is the "matrix of partial derivatives", called Jacobian matrix of \vec{f} at \vec{a} in lecture notes.

We may view the numerator in two ways:

$$\begin{aligned} & \vec{f}(\vec{a}+\vec{h}) - \left(\vec{f}(\vec{a}) + T(\vec{h}) \right) \quad \leftarrow \text{linearization of } \vec{f} \text{ at } \vec{a} \\ &= \left(\vec{f}(\vec{a}+\vec{h}) - \vec{f}(\vec{a}) \right) - T(\vec{h}) \\ & \quad \leftarrow \text{change in } \vec{f} \end{aligned}$$



Using the notations in lecture note : Given $f: \mathbb{R}^n \rightarrow \mathbb{R}^m$,

$$\underbrace{T(\vec{h})}_{\text{linear transformation}} = \underbrace{(D\vec{f}(\vec{a}))}_{\text{Jacobian matrix}}(\vec{h}) = \begin{pmatrix} \text{--- } \vec{\nabla} f_1(\vec{a}) \text{---} \\ \vdots \\ \text{--- } \vec{\nabla} f_m(\vec{a}) \text{---} \end{pmatrix} \begin{pmatrix} h_1 \\ \vdots \\ h_n \end{pmatrix}$$

① Let $\vec{f}: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ be a map defined as follows:

$$\forall (x, y) \in \mathbb{R}^2, \quad \vec{f}(x, y) = \left(\sqrt{xy}, \sqrt{\frac{y}{x}} \right).$$

(a) Find the Jacobian matrix of \vec{f} at $(2, 8)$.

(b) Use the linearization of \vec{f} at $(2, 8)$ to approximate $\vec{f}(1.9, 8.2)$

Ans: (a) Let $f_1(x, y) := \sqrt{xy}$ and $f_2(x, y) := \sqrt{\frac{y}{x}}$.

$$D\vec{f}(x, y) = \begin{pmatrix} \text{--- } \vec{\nabla} f_1(x, y) \text{---} \\ \text{--- } \vec{\nabla} f_2(x, y) \text{---} \end{pmatrix} = \begin{pmatrix} \frac{\partial f_1}{\partial x}(x, y) & \frac{\partial f_1}{\partial y}(x, y) \\ \frac{\partial f_2}{\partial x}(x, y) & \frac{\partial f_2}{\partial y}(x, y) \end{pmatrix} = \begin{pmatrix} \frac{\sqrt{y}}{2\sqrt{x}} & \frac{\sqrt{x}}{2\sqrt{y}} \\ -\frac{1}{2}\sqrt{y}x^{-\frac{3}{2}} & \frac{1}{2\sqrt{xy}} \end{pmatrix}$$

$$\therefore D\vec{f}(2, 8) = \begin{pmatrix} 1 & \frac{1}{4} \\ -\frac{1}{2} & \frac{1}{8} \end{pmatrix} = T$$

(b) ($\vec{f}(\vec{a} + \vec{h}) \approx \vec{f}(\vec{a}) + T(\vec{h})$)

$$\begin{aligned} \vec{f}(1.9, 8.2) &= \vec{f}((2, 8) + (-0.1, +0.2)) \\ &\approx \vec{f}(2, 8) + \begin{pmatrix} 1 & \frac{1}{4} \\ -\frac{1}{2} & \frac{1}{8} \end{pmatrix} \begin{pmatrix} -0.1 \\ +0.2 \end{pmatrix} \\ &= \begin{pmatrix} 4 \\ 2 \end{pmatrix} + \begin{pmatrix} -0.1 + 0.05 \\ 0.05 + 0.025 \end{pmatrix} = \begin{pmatrix} 3.95 \\ 2.075 \end{pmatrix} \end{aligned}$$

(2) A twice continuously differentiable (i.e. C^2) function $f: \mathbb{R}^2 \setminus \{0\} \rightarrow \mathbb{R}$ is a harmonic function if it satisfies the Laplace equation

$$\frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} = 0$$

Show the Laplace equation in polar coordinates, i.e.,

$$\frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial f}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 f}{\partial \theta^2} = 0$$

Ans:

Let $\varphi: (0, \infty) \times \mathbb{R} \rightarrow \mathbb{R}^2 \setminus \{0\}$

$$(r, \theta) \mapsto (r \cos \theta, r \sin \theta)$$

By Chain rule (why can we use this?),

$$D(f \circ \varphi)(r_0, \theta_0) = Df(\varphi(r_0, \theta_0)) \cdot D\varphi(r_0, \theta_0)$$

$$\left(\frac{\partial (f \circ \varphi)}{\partial r}(r_0, \theta_0), \frac{\partial (f \circ \varphi)}{\partial \theta}(r_0, \theta_0) \right) = \left(\frac{\partial f}{\partial x}(\varphi(r_0, \theta_0)), \frac{\partial f}{\partial y}(\varphi(r_0, \theta_0)) \right) \cdot \begin{pmatrix} \frac{\partial \varphi}{\partial r}(r_0, \theta_0) & \frac{\partial \varphi}{\partial \theta}(r_0, \theta_0) \\ \frac{\partial \varphi}{\partial r}(r_0, \theta_0) & \frac{\partial \varphi}{\partial \theta}(r_0, \theta_0) \end{pmatrix}$$

With abuse of notation, we have

$$\frac{\partial f}{\partial r} = \frac{\partial f}{\partial x} \cdot \frac{\partial x}{\partial r} + \frac{\partial f}{\partial y} \cdot \frac{\partial y}{\partial r}$$

$$\frac{\partial f}{\partial \theta} = \frac{\partial f}{\partial x} \cdot \frac{\partial x}{\partial \theta} + \frac{\partial f}{\partial y} \cdot \frac{\partial y}{\partial \theta}$$

$$\frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial f}{\partial r} \right) = \frac{1}{r} \left(\frac{\partial f}{\partial r} + r \frac{\partial}{\partial r} \left(\frac{\partial f}{\partial r} \right) \right)$$

$$= \frac{1}{r} \left[\left(\frac{\partial f}{\partial x} \cdot \cos \theta + \frac{\partial f}{\partial y} \cdot \sin \theta \right) + r \frac{\partial}{\partial r} \left(\frac{\partial f}{\partial x} \cdot \cos \theta + \frac{\partial f}{\partial y} \cdot \sin \theta \right) \right]$$

$$= \frac{1}{r} \left[\left(\frac{\partial f}{\partial x} \cdot \cos \theta + \frac{\partial f}{\partial y} \cdot \sin \theta \right) \right]$$

$$+ r \cos \theta \left(\frac{\partial^2 f}{\partial x^2} \cdot \cos \theta + \frac{\partial}{\partial y} \left(\frac{\partial f}{\partial x} \right) \cdot \sin \theta \right) + r \sin \theta \left(\frac{\partial}{\partial x} \left(\frac{\partial f}{\partial y} \right) \cdot \cos \theta + \frac{\partial^2 f}{\partial y^2} \cdot \sin \theta \right)$$

$$\begin{aligned}
\frac{1}{r^2} \frac{\partial^2 f}{\partial \theta^2} &= \frac{1}{r^2} \cdot \frac{\partial}{\partial \theta} \left(\frac{\partial f}{\partial x} \cdot \frac{\partial x}{\partial \theta} + \frac{\partial f}{\partial y} \cdot \frac{\partial y}{\partial \theta} \right) \\
&= \frac{1}{r^2} \cdot \left[\left(\frac{\partial}{\partial \theta} \left(\frac{\partial f}{\partial x} \right) \cdot \frac{\partial x}{\partial \theta} + \frac{\partial f}{\partial x} \cdot \frac{\partial^2 x}{\partial \theta^2} + \left(\frac{\partial}{\partial \theta} \left(\frac{\partial f}{\partial y} \right) \cdot \frac{\partial y}{\partial \theta} + \frac{\partial f}{\partial y} \cdot \frac{\partial^2 y}{\partial \theta^2} \right) \right] \\
&= \frac{1}{r^2} \left[\left(\frac{\partial^2 f}{\partial x^2} \frac{\partial x}{\partial \theta} \cdot \frac{\partial x}{\partial \theta} + \frac{\partial}{\partial y} \left(\frac{\partial f}{\partial x} \right) \cdot \frac{\partial y}{\partial \theta} \right) \cdot \frac{\partial x}{\partial \theta} + \frac{\partial f}{\partial x} \cdot \frac{\partial}{\partial \theta} (-r \sin \theta) \right. \\
&\quad \left. + \left(\frac{\partial}{\partial x} \left(\frac{\partial f}{\partial y} \right) \cdot \frac{\partial x}{\partial \theta} + \frac{\partial^2 f}{\partial y^2} \cdot \frac{\partial y}{\partial \theta} \right) \cdot \frac{\partial y}{\partial \theta} + \frac{\partial f}{\partial y} \cdot \frac{\partial}{\partial \theta} (r \cos \theta) \right] \\
&= \frac{1}{r^2} \left[\left(\frac{\partial^2 f}{\partial x^2} \cdot (-r \sin \theta) + \frac{\partial}{\partial y} \left(\frac{\partial f}{\partial x} \right) \cdot (r \cos \theta) \right) \cdot (-r \sin \theta) + \frac{\partial f}{\partial x} \cdot (-r \cos \theta) \right. \\
&\quad \left. + \left(\frac{\partial}{\partial x} \left(\frac{\partial f}{\partial y} \right) \cdot (-r \sin \theta) + \frac{\partial^2 f}{\partial y^2} \cdot (r \cos \theta) \right) \cdot (r \cos \theta) + \frac{\partial f}{\partial y} \cdot (-r \sin \theta) \right]
\end{aligned}$$

$$\therefore \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial f}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 f}{\partial \theta^2}$$

$$= \left(\frac{\partial^2 f}{\partial x^2} \cos^2 \theta + \frac{\partial^2 f}{\partial y^2} \sin^2 \theta \right) + \left(\frac{\partial^2 f}{\partial x^2} \sin^2 \theta + \frac{\partial^2 f}{\partial y^2} \cos^2 \theta \right)$$

$$= \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} = 0$$