

Tutorial 5.

1. let S be a regular surface, $p \in \text{int}(S)$, $X: U \rightarrow S$ is a parametrization around p .
Show that there is a reparametrization around p such that

$$\tilde{g}|_p = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, \quad \tilde{h}|_p = \begin{bmatrix} k_1 & 0 \\ 0 & k_2 \end{bmatrix} \text{ for some } k_1, k_2 \in \mathbb{R}$$

where k_1, k_2 are called the principle curvatures of S .

pf: let S_p be the shape operator at p .

$\therefore S_p: T_p S \rightarrow T_p S$ is linear, $T_p S$ can be regarded as $\mathbb{R}^2$

$\therefore \exists \vec{v}_1, \vec{v}_2 \in T_p S$ such that

$$\begin{cases} \|\vec{v}_1\| = \|\vec{v}_2\| = 1 \\ \langle \vec{v}_1, \vec{v}_2 \rangle = 0 \\ S_p(\vec{v}_1) = k_1 \vec{v}_1, S_p(\vec{v}_2) = k_2 \vec{v}_2 \text{ for some } k_1, k_2 \end{cases}$$

and we can assume $\langle X_u \times X_v, \vec{v}_1 \times \vec{v}_2 \rangle > 0$ [the same orientation]

$\therefore \exists$ a non-singular matrix A with $\det(A) > 0$ such that

$$A \begin{bmatrix} \vec{v}_1 \\ \vec{v}_2 \end{bmatrix} = \begin{bmatrix} X_u \\ X_v \end{bmatrix}$$

• let $(u_0, v_0) \in U$ such that $X(u_0, v_0) = p$

define $\varphi: \mathbb{R}^2 \rightarrow U$ by

$$\varphi(\vec{u}, \vec{v}) = (A^{-1})^T \begin{bmatrix} \vec{u} - u_0 \\ \vec{v} - v_0 \end{bmatrix} + (u_0, v_0)^T$$

$\therefore \varphi$ is a local diffeomorphism around (u_0, v_0)

and $\varphi(u_0, v_0) = (u_0, v_0)$, $\det(d\varphi(u_0, v_0)) > 0$

• Define $\gamma(\vec{u}, \vec{v}) = X \circ \varphi: U \rightarrow S$

$$\text{then } \begin{cases} \frac{\partial \gamma}{\partial u} = \frac{\partial X}{\partial u} \cdot \frac{\partial u}{\partial \vec{u}} + \frac{\partial X}{\partial v} \cdot \frac{\partial v}{\partial \vec{u}} \\ \frac{\partial \gamma}{\partial v} = \frac{\partial X}{\partial u} \cdot \frac{\partial u}{\partial \vec{v}} + \frac{\partial X}{\partial v} \cdot \frac{\partial v}{\partial \vec{v}} \end{cases}$$

$$\therefore \begin{bmatrix} \frac{\partial \gamma}{\partial u} \\ \frac{\partial \gamma}{\partial v} \end{bmatrix} = (d\varphi)^T \begin{bmatrix} \frac{\partial X}{\partial u} \\ \frac{\partial X}{\partial v} \end{bmatrix} = A^{-1} \begin{bmatrix} X_u \\ X_v \end{bmatrix} = \begin{bmatrix} \vec{v}_1 \\ \vec{v}_2 \end{bmatrix}$$

$\therefore \tilde{g}(p) = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$ since $\{\vec{v}_1, \vec{v}_2\}$ is an orthonormal basis

$$\tilde{h}(p) = \begin{bmatrix} k_1 & 0 \\ 0 & k_2 \end{bmatrix} \text{ since } S_p(\vec{v}_1) = k_1 \vec{v}_1, S_p(\vec{v}_2) = k_2 \vec{v}_2$$

2. show that $K(P) = k_1 \cdot k_2$, $H(P) = \frac{1}{2}(k_1 + k_2)$

pf: $K(P) = \frac{\det(h)}{\det(g)} = \frac{k_1 \cdot k_2}{1} = k_1 \cdot k_2$

$$H(P) = \frac{1}{2} \cdot \frac{k_1 + k_2}{1} = \frac{1}{2}(k_1 + k_2)$$

3. let S be a regular surface

Suppose $H(P) = 0$

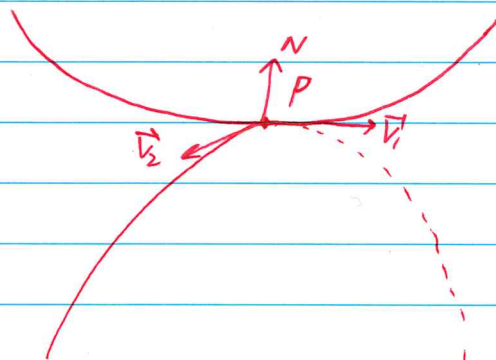
show that $K(P) \leq 0$

pf: choose a parametrization around P
such that $g(P) = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$, $h(P) = \begin{bmatrix} k_1 & 0 \\ 0 & k_2 \end{bmatrix}$

then $H(P) = 0 \Rightarrow k_1 + k_2 = 0 \Rightarrow k_1 = -k_2$

$$\therefore K(P) = k_1 \cdot k_2$$

$$= -k_1 \cdot k_1 = -k_1^2 \leq 0$$



4. let S be a regular compact surface without boundary.

Show that there is a point $P \in S$ such that

$$K(P) > 0$$

pf: 1° since S is compact

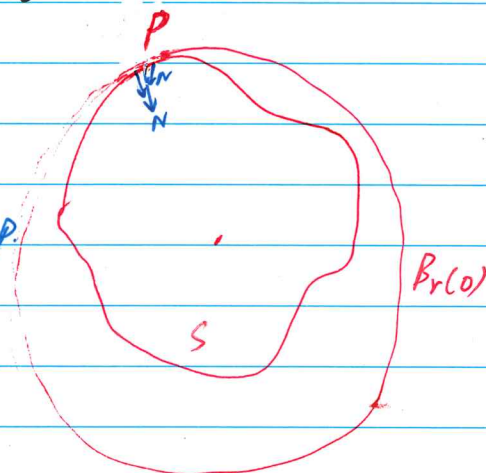
$\therefore \exists r > 0$ such that

S is inside $B_r(0)$ and $B_r(0)$ is tangent to S at P .

choose $\vec{N}$ to be the unit normal vector

2° choose a reparametrization around P

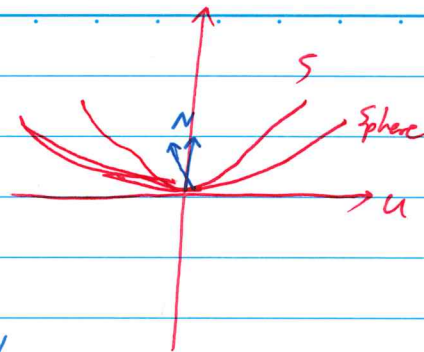
such that $g = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$, $h = \begin{bmatrix} k_1 & 0 \\ 0 & k_2 \end{bmatrix}$



3°. After rotation and translation

$$P = (0, 0, 0), \quad \partial_u|_P = (1, 0, 0), \quad \partial_v|_P = (0, 1, 0)$$

$$N(P) = (0, 0, 1)$$



and S is a graph over $\mathbb{R}^2$ around P

let $(u, v, F(u, v))$ denote S

$(u, v, G(u, v) = r - \sqrt{r^2 - (u^2 + v^2)})$ denote the sphere.

$$\therefore \begin{cases} F(0, 0) = G(0, 0) = 0, & \partial_u F(0, 0) = \partial_v F(0, 0) = \partial_u G(0, 0) = \partial_v G(0, 0) = 0 \\ F(u, v) \geq G(u, v) \end{cases}$$

$$\Rightarrow \partial_u F(0, 0) \geq \partial_u G(0, 0) \quad \text{and} \quad \partial_u^2 F(0, 0) \geq \partial_u^2 G(0, 0)$$

use $f'(x) = \lim_{h \rightarrow 0} \frac{f(x+h) + f(x-h) - 2f(x)}{h^2}$

$$\bullet \quad N(u, v) = (f, g, h) \quad \text{and} \quad h(0, 0) = 1$$

$$\therefore \langle N, \partial_u S \rangle = 0$$

$$\Rightarrow f + h \partial_u F = 0$$

$$\Rightarrow f_u + h \partial_u \partial_u F + h \partial_u^2 F = 0$$

$$\therefore \langle \partial_u N, \partial_u S \rangle|_{(0,0)}$$

$$= f_u + h \partial_u \partial_u F$$

$$= -h \partial_u^2 F$$

$$\leq -h \partial_u^2 G \quad \text{since } h > 0, \quad \partial_u^2 F \geq \partial_u^2 G$$

$$< 0 \quad \text{since } |h| = 1 \text{ at } P$$

$$\partial_u^2 G > 0 \text{ at } P \quad (G = r - \sqrt{r^2 - (u^2 + v^2)})$$

$$\therefore \langle k_1 \partial_u S, \partial_u S \rangle < 0 \text{ at } P$$

$$\therefore k_1 < 0 \text{ at } P$$

Similarly, $k_2 < 0 \text{ at } P$

$$\therefore K(P) = k_1 \cdot k_2 > 0 \text{ at } P.$$