

Tutorial 4.

1. show that the equation of the tangent plane of a surface which is the graph of a differentiable function $z = f(x, y)$, at point $P_0 = (x_0, y_0, f(x_0, y_0))$ is given by

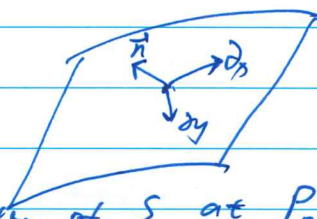
$$z = f(x_0, y_0) + f_x(x_0, y_0)(x - x_0) + f_y(x_0, y_0)(y - y_0)$$

pf: let $X: (x, y) \rightarrow (x, y, f(x, y))$ be a parametrization of S

$$\therefore \partial_x X = (1, 0, f_x)$$

$$\partial_y X = (0, 1, f_y)$$

$\therefore \vec{n} = (\partial_x X) \times (\partial_y X) = (-f_x, -f_y, 1)$ is a normal vector of S at P_0



$\therefore$ the tangent space is

$$\langle (x, y, z) - (x_0, y_0, f(x_0, y_0)), \vec{n} \rangle = 0$$

$$\therefore z = f(x_0, y_0) + f_x(x_0, y_0)(x - x_0) + f_y(x_0, y_0)(y - y_0)$$

2. let S be a regular surface. let $\bar{P}$ be a plane.

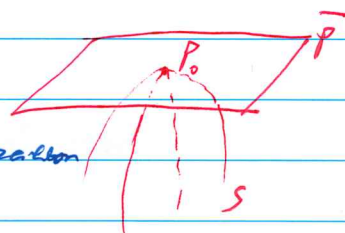
suppose $S \cap \bar{P} = \{P_0\}$ and $P_0 \in \text{int}(S)$, $P_0 \in \text{int}(\bar{P})$

Show $\bar{P}$ is tangent to S at P_0

pf: $\therefore P_0 \in \text{int}(S)$

$\therefore \exists$ an open set $U \subseteq \mathbb{R}^2$, $X: U \rightarrow S$ a parametrization

such that $\begin{cases} X(0,0) = P_0, (0,0) \in U \\ \text{and } B_\varepsilon(0) \subseteq U \text{ for some } \varepsilon > 0 \end{cases}$



let $\vec{n}$ be a unit normal vector of $\bar{P}$ at P_0

define $f(u, v) = \langle X(u, v) - P_0, \vec{n} \rangle: U \rightarrow \mathbb{R}$

$\therefore S \cap \bar{P} = \{P_0\}$, $P_0 \in \text{int}(\bar{P})$

$\therefore f(u, v) \neq 0$ for $\forall (u, v) \in U \setminus \{(0,0)\}$, and $f(0,0) = 0$

[claim: $f_u(0,0) = f_v(0,0) = 0$]

Suppose $f_u(0,0) > 0$, then $\exists \varepsilon_1 \in (0, \varepsilon)$ such that

$$f(\varepsilon_1, 0) > 0, f(-\varepsilon_1, 0) < 0$$

$\therefore \exists \varepsilon_2 > 0$ such that $f(\varepsilon_1, \varepsilon_2) > 0, f(-\varepsilon_1, \varepsilon_2) < 0$

$\therefore f(\cdot, \varepsilon_2): \mathbb{R} \rightarrow \mathbb{R}$ is smooth, $f(\varepsilon_1, \varepsilon_2) > 0, f(-\varepsilon_1, \varepsilon_2) < 0$

$\therefore \exists t_0 \in (-\varepsilon_1, \varepsilon_1)$ such that $f(t_0, \varepsilon_2) = 0$, contradiction

$\therefore f_u(0,0) = 0$, similarly, $f_v(0,0) = 0$ $\therefore \langle \partial_u X(0,0), \vec{n} \rangle = \langle \partial_v X(0,0), \vec{n} \rangle = 0$

3. [Reparametrization]

let S be a regular surface. $P \in \text{int}(S)$

let U be an open set in $\mathbb{R}^2$, and $X: U \rightarrow S$ be a parametrization around P . W.L.O.G, we can assume $(0,0) \in U$ and $X(0,0) = P$

Show that there is a reparametrization of S around P such that $\tilde{g}_{ij}(P) = \delta_{ij}$ where $\delta_{ij} = \begin{cases} 1 & \text{if } i=j \\ 0 & \text{if } i \neq j \end{cases}$

Pf: let $\tilde{U}$ be an open set in $\mathbb{R}^2$ around $(0,0)$

and $\varphi: \tilde{U} \rightarrow U$ be a diffeomorphism with $\det(d\varphi) > 0$ everywhere.

let $Y = X \circ (\varphi^{-1}): \tilde{U} \rightarrow S$ be a reparametrization.

$$\therefore \partial_u Y = \partial_u X \cdot \frac{\partial u}{\partial \tilde{u}} + \partial_v X \cdot \frac{\partial v}{\partial \tilde{u}}$$

$$\partial_v Y = \partial_u X \cdot \frac{\partial u}{\partial \tilde{v}} + \partial_v X \cdot \frac{\partial v}{\partial \tilde{v}}$$

$$\therefore \begin{cases} g_{\tilde{u}\tilde{u}} = \langle \partial_u Y, \partial_u Y \rangle = \left(\frac{\partial u}{\partial \tilde{u}}\right)^2 g_{uu} + 2 \frac{\partial u}{\partial \tilde{u}} \frac{\partial v}{\partial \tilde{u}} g_{uv} + \left(\frac{\partial v}{\partial \tilde{u}}\right)^2 g_{vv} \\ \dots \end{cases}$$

$$\therefore \tilde{g} = \begin{bmatrix} \frac{\partial u}{\partial \tilde{u}} & \frac{\partial v}{\partial \tilde{u}} \\ \frac{\partial u}{\partial \tilde{v}} & \frac{\partial v}{\partial \tilde{v}} \end{bmatrix} \begin{bmatrix} g_{uu} & g_{uv} \\ g_{uv} & g_{vv} \end{bmatrix} \begin{bmatrix} \frac{\partial u}{\partial \tilde{u}} & \frac{\partial u}{\partial \tilde{v}} \\ \frac{\partial v}{\partial \tilde{u}} & \frac{\partial v}{\partial \tilde{v}} \end{bmatrix} \\ = (d\varphi^{-1})^T g (d\varphi^{-1})$$

$\therefore g$ is a matrix with $\det(g) > 0$

$\therefore \exists$ such $d\varphi^{-1}$ as a change of coordinate such that

$$\tilde{g} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$(I = A^T g A \Leftrightarrow g = (A^{-1})^T A^{-1})$$

choose $\tilde{v}_1, \tilde{v}_2 \in \mathbb{R}^2$ such that $\tilde{g}_{ij} = \langle \tilde{v}_i, \tilde{v}_j \rangle$, let $(A^{-1})^T = \begin{bmatrix} \tilde{v}_1 \\ \tilde{v}_2 \end{bmatrix}$

$\therefore \varphi^{-1}$ exists and $(d\varphi^{-1})^T g (d\varphi^{-1})(0,0) = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$ check $g = (A^{-1})^T A^{-1}$

• Remark: we can only guarantee that $\tilde{g}(P) = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$

because we can only choose $d\varphi^{-1}|_{(0,0)}$ to satisfy $\tilde{g}(P) = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$

• Actually, we can choose a coordinate such that

$$\begin{cases} \tilde{g}_{ij}(P) = \delta_{ij} \\ \partial_k \tilde{g}_{ij}(P) = 0 \text{ for } \forall i, j, k \end{cases}$$

such coordinate is called normal coordinate.

So if we want to define something which is independent of the choice of coordinate, then it must involve 2nd-derivatives of g .