

27/9/2018

(1)

Proof of Prop 1

(i) let $\vec{w} \in T_p(M)$, $\vec{w} = (a\vec{X}_u + b\vec{X}_v)|_p$
 a, b are numbers.

let $\alpha(t)$ as in the definition s.t.

$$\alpha(t) = \vec{X}(u(t), v(t))$$

$$\vec{w} = \alpha'(0) = \vec{X}_u u'(0) + \vec{X}_v v'(0) =$$

$$\left. \frac{dN}{dt} \right|_{t=0} = \frac{\partial N}{\partial u} u'(0) + \frac{\partial N}{\partial v} v'(0)$$

$$= a \underline{N_u} + b \underline{N_v}|_p$$

= depends only on w .

$\therefore$ well-defined.

(ii) Need to prove (a) $S_p(\vec{w}) \in T_p(M)$.

Suff. to prove $N_v, N_u \in T_p(M)$

$$\text{Now: } 2 \langle N_u, \overset{N}{\cancel{N_u}} \rangle = \frac{\partial}{\partial u} \langle N, N_u \rangle$$

$$= 0$$

$\therefore N_u \perp N$, and $N_u \in T_p(M)$

etc.

(b) S_p is linear. (Why?)

(iii) Let $Y(\xi, \eta)$ be another parametrization ⁽²⁾
defined on V s.t.

$Y = X \circ \phi$ $\phi: V \rightarrow U$ is
a diffeomorphism.

$N \equiv$ ^{unit} normal vector field

$N = N(u, v)$, $u = u(\xi, \eta)$, $v = v(\xi, \eta)$

$$\begin{aligned}\vec{w} \in T_p(M) &= a \vec{X}_u + b \vec{X}_v \\ &= a \left(\vec{Y}_\xi \frac{\partial \xi}{\partial u} + \vec{Y}_\eta \frac{\partial \eta}{\partial u} \right) \\ &\quad + b \left(\vec{Y}_\xi \frac{\partial \xi}{\partial v} + \vec{Y}_\eta \frac{\partial \eta}{\partial v} \right) \\ &= \left(a \frac{\partial \xi}{\partial u} + b \frac{\partial \xi}{\partial v} \right) \vec{Y}_\xi \\ &\quad + \left(a \frac{\partial \eta}{\partial u} + b \frac{\partial \eta}{\partial v} \right) \vec{Y}_\eta.\end{aligned}$$

In (u, v) coord.

$$S_p(w) = -(a \vec{N}_u + b \vec{N}_v)$$

In (ξ, η) coord

$$\begin{aligned}S_p(w) &= -(a \xi_u + b \xi_v) N_\xi \\ &\quad - (a \eta_u + b \eta_v) N_\eta.\end{aligned}$$

But $N_u = N_\xi \xi_u + N_\eta \eta_u$ etc. (3)

Hence $S_p(w)$ gives same vector in both coord.

(iv) Self-adjoint means for $w_1, w_2 \in T_p(M)$

$$\langle S_p(w_1), w_2 \rangle = \langle w_1, S_p(w_2) \rangle.$$

Sufficient to prove

$$\langle S_p(X_u), X_v \rangle = \langle X_u, S_p(X_v) \rangle.$$

(Why?)

$$S_p(X_u) = -N_u.$$

$$\begin{aligned} \text{L.S.} &= \langle -N_u, X_v \rangle = -\frac{\partial}{\partial u} \langle N, X_v \rangle \\ &\quad + \langle N, X_{vu} \rangle \end{aligned}$$

$$= \langle N, X_{vu} \rangle.$$

$$\text{R.S.} = \langle X_{uv}, N \rangle.$$

$\therefore X_{uv} = X_{vu} \quad \therefore$ results follows.

(V) S_p is smooth means:

(4)

If $\vec{w}$ is a smooth tangential vector field,

then $S_p(\vec{w})$ is a smooth tangential vector field.

Now: let $\vec{w}$ = smooth, then

$$\vec{w} = a(u,v) \vec{X}_u + b(u,v) \vec{X}_v.$$

a, b are smooth.

$$S_p(w) = -(a N_u + b N_v).$$

$\therefore N_u, N_v$ are smooth.

So $S(w)$ is smooth.

Def. 2nd fundamental form Π_p at p
is the bilinear form $\Pi_p(w_1, w_2)$
 $= \langle S_p(w_1), w_2 \rangle.$

Prop 2 (Proof).

$$\Pi_p(w_1, w_2) = \Pi_p(w_2, w_1)$$

(Why?)

To compute the 2nd fundamental (5)
form:

Let $\vec{X}: U \rightarrow \mathbb{R}^3$ as before.

$$\text{Let } N = \frac{X_u \times X_v}{|X_u \times X_v|}.$$

$\therefore \Pi_p$ is determined by its values on basis vectors X_u, X_v , we let

$$e = \Pi_p(X_u, X_u), \quad f = \Pi_p(X_u, X_v) \\ = \Pi_p(X_v, X_u)$$

$$g = \Pi_p(X_v, X_v)$$

Then if $w_1 = a_1 X_u + b_1 X_v$
 $w_2 = a_2 X_u + b_2 X_v$, then

$$\Pi_p(w_1, w_2) = a_1 a_2 e + (a_1 b_2 + b_1 a_2) f \\ + b_1 b_2 g.$$

$$\Pi_p(w_1, w_1) = a_1^2 e + 2a_1 b_1 f + b_1^2 g. \\ = \text{quadratic form.}$$

~~Fact~~:

Notation: If we use (u^1, u^2) as coord.

then we let $h_{11} = \Pi_p(\vec{X}_1, \vec{X}_1)$

$$h_{12} = \Pi_p(\vec{X}_1, \vec{X}_2) = \Pi_p(\vec{X}_2, \vec{X}_1) = h_{21}$$

$$h_{22} = \Pi_p(\vec{X}_2, \vec{X}_2)$$

If $w = a^1 \vec{X}_1 + a^2 \vec{X}_2$, then

$$\begin{aligned} \Pi_p(w, w) &= (a^1)^2 h_{11} + 2a^1 a^2 h_{12} + (a^2)^2 h_{22} \\ &= \sum_{i,j=1}^2 h_{ij} a^i a^j. \end{aligned}$$

Fact: a, b, c, d are vectors in $\mathbb{R}^3$

Then $\langle a \times b, c \times d \rangle$

$$= \begin{vmatrix} \langle a, c \rangle & \langle a, d \rangle \\ \langle b, c \rangle & \langle b, d \rangle \end{vmatrix}$$

$$\begin{aligned} \text{Hence } |X_u \times X_v|^2 &= \begin{vmatrix} \langle X_u, X_u \rangle & \langle X_u, X_v \rangle \\ \langle X_v, X_u \rangle & \langle X_v, X_v \rangle \end{vmatrix} \\ &= EG - F^2. \end{aligned}$$

Prop 3 (Proof). Here $N = \frac{X_u \times X_v}{|X_u \times X_v|}$.

(7)

$$e = \langle \Pi(X_u, X_u) = -\langle N_u, X_u \rangle \\ = \langle N, X_{uu} \rangle. \quad (\text{Why?})$$

$$= \frac{\langle X_u \times X_v, X_{uu} \rangle}{\sqrt{EG - F^2}}$$

$$= \frac{\det(X_u, X_v, X_{uu})}{\sqrt{EG - F^2}}.$$

etc.

In (u^1, u^2) coord.,

$$h_{11} = \frac{\det(X_1, X_2, X_{11})}{\sqrt{h_{11}h_{22} - h_{12}^2}} \quad \leftarrow \sqrt{\det(h)}$$

$$\det h = \det \begin{pmatrix} h_{11} & h_{12} \\ h_{21} & h_{22} \end{pmatrix}.$$