

(1) An exercise in last tutorial :

$$X(u, v) = (g(u), h(u) \cos v, h(u) \sin v) \quad \left(\begin{array}{l} \text{General form of} \\ \text{surfaces of revolution} \\ \text{(corresponding to x-axis)} \end{array} \right)$$

Show that ~~$X_u \times X_v \neq 0 \forall (u, v)$~~ $\Leftrightarrow \alpha(u) = (g(u), h(u), 0)$ is regular and has no intersection with x-axis.

Pf: (\Rightarrow) We compute
$$\begin{cases} X_u = (g', h' \cos v, h' \sin v) \\ X_v = (0, -h \sin v, h \cos v) \end{cases}$$

$$\Rightarrow X_u \times X_v = (h'h, -g'h \cos v, -g'h \sin v)$$

And compute $\alpha' = (g', h', 0)$

If $g' = h' = 0$, then $X_u \times X_v = 0 \rightarrow \Leftarrow$

If $h = 0$, then $X_u \times X_v = 0 \rightarrow \Leftarrow$

So α is regular and has no intersection with x-axis.

(\Leftarrow) Assume \downarrow , we have

$h \neq 0$ and g', h' can't equ. to 0 at the same time.

12

If $h' = 0$, $X_u \times X_v = (0, -g'h \cos v, -g'h \sin v) \neq 0$

If $g' = 0$, $X_u \times X_v = (h'h, 0, 0) \neq 0$

If $h' \neq 0$ and $g' \neq 0$, $X_u \times X_v \neq 0$.

So we have $X_u \times X_v \neq 0$.

#

(2) Ex: Let $M: X(u, v) = \beta(u) + v\delta(u)$ be a ruled surface with $|\beta'| \equiv 1$ and $|\delta'| \equiv 1$. Show that if $\delta' \neq 0 \forall u$, M may be reparametrized by $\Upsilon(z, w) = \gamma(z) + w\delta(z)$ s.t. $\langle \gamma', \delta' \rangle = 0$.
($= X(u, v)$)

One may consider $r(u) = \beta(u) + s(u)\delta(u)$ where $s(u)$ is a C^∞ function on

Then $r' = \beta' + s'\delta + s\delta'$. Using $\langle r', \delta' \rangle = 0$,

$$\langle \beta', \delta' \rangle + s' \langle \delta, \delta' \rangle + s |\delta'|^2 = 0$$

Since $|\delta'| = 1$

$$s(u) = \frac{-\langle \beta', \delta' \rangle}{|\delta'|^2} \quad \text{Note that } \delta' \neq 0 \forall u.$$

Let $\begin{cases} z = u \\ w = v - s(u) \end{cases}$

$$\Upsilon(z, w) \stackrel{\Delta}{=} r(z) + \cancel{s(z)} w \delta(z)$$

$$= \beta(u) + s(u)\delta(u) + (v - s(u))\delta(u)$$

$$= X(u, v).$$

At last, we should check

$$\det \begin{pmatrix} \frac{\partial z}{\partial u} & \frac{\partial z}{\partial v} \\ \frac{\partial w}{\partial u} & \frac{\partial w}{\partial v} \end{pmatrix} = \det \begin{pmatrix} 1 & 0 \\ -s' & 1 \end{pmatrix} = 1 \neq 0$$

(It's actually a coordinate change!) $\#$

(3) We may def the tangent plane $T_p M$ of M at p in this way (Global one):

$$T_p M \triangleq \left\{ \alpha'(0) \mid \alpha: (-\varepsilon, \varepsilon) \rightarrow M, \text{ for some } \varepsilon > 0 \right. \\ \left. \alpha(0) = p \right\}$$

Elements in $T_p M$ are called tangent vectors to M at p .

One can show the following lemma (Lemma 2.2.1 of Oprea)

Let $M =$ regular surface

• $p \in M$

• $X(u, v) =$ regular patch on M s.t. $p = X(u_0, v_0)$

Then $T_p M$ is a vector space with basis $\{X_u, X_v\}_{(u_0, v_0)}$

Let's compute some examples.

$M =$ graph of " $z = f(x, y)$ "

Monge patch: $X(u, v) = (u, v, f(u, v))$

$$\Rightarrow \begin{cases} X_u = (1, 0, f_u) \\ X_v = (0, 1, f_v) \end{cases}$$

$$\Rightarrow X_u \times X_v = (-f_u, -f_v, 1) = \text{normal (may be not unit)}$$

$$p = (u_0, v_0, f(u_0, v_0))$$

$$\langle (x, y, z) - p, X_u \times X_v|_{(u_0, v_0)} \rangle = 0.$$

i.e the eqn. of T_pM

$$-f_u(u_0, v_0)(x - u_0) - f_v(u_0, v_0)(y - v_0) + (z - f(u_0, v_0)) = 0.$$

Explicit eq: $f(x, y) = x^2 + y^2$ (Paraboloid)

$$p = (1, 0, 1)$$

$$f_u = 2u$$

$$f_v = 2v$$

~~0, 1, 1~~

$$-2(x-1) + z-1 = 0$$

i.e

$$2x - z = 1$$

④ Recall: The Gauss map is a unit normal vector field on M

i.e $\mathbb{U}: M \rightarrow \mathbb{S}^2$. In the case of a coordinate patch

$X(u, v)$

$$\mathbb{U} = \frac{X_u \times X_v}{|X_u \times X_v|}$$

If we write $\mathbb{U} = u^1 e_1 + u^2 e_2 + u^3 e_3$

where $e_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$, $e_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$, $e_3 = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$

then u^1, u^2, u^3 are functions on M .

for any $v \in T_p M$, we denote $(\frac{\partial}{\partial x}, \frac{\partial}{\partial y})$

$$\nabla_v \mathbb{U} \triangleq \sum_{i=1}^3 v[u^i] e_i$$

directional derivative

$$v = a \frac{\partial}{\partial x} + b \frac{\partial}{\partial y}$$

$$v(f) = a \frac{\partial f}{\partial x} + b \frac{\partial f}{\partial y}$$

Def: The shape operator (or Weingarten Map) of a surface M at p is def. by

$$S_p(v) = -\nabla_v \mathbb{U}, \quad \forall v \in T_p M$$

where \mathbb{U} is the Gauss map of M .

Lemma: S_p is a linear transformation from $T_p M$ into itself

Pf: (1) Want $\nabla_v \mathbb{U} \in T_p M$.

$$|\mathbb{U}| = 1$$

$$0 = v[\langle \mathbb{U}, \mathbb{U} \rangle] = v\left[\sum_{i=1}^3 u_i^2\right]$$

$$= \sum_{i=1}^3 2u^i v[u^i] = 2 \langle \mathbb{U}, \nabla_v \mathbb{U} \rangle$$

So $\nabla_v \mathbb{U} \in T_p M$.

(2) S_p is linear

$\forall v, w \in T_p M, a \in \mathbb{R}$

$$\begin{aligned}
S_p(av+w) &= -\nabla_{av+w} \Gamma \\
&= - (av+w)(u^i) e_i \\
&= - (av(u^i) e_i + w(u^i) e_i) \\
&= -a \nabla_v \Gamma - \nabla_w \Gamma \\
&= a S_p(v) + S_p(w) \quad \#
\end{aligned}$$

Ex: Try to compute the shape^{operator} of $S^2(\mathbb{R})$ at any pt p .

One may consider the parametrization (covers most of $S^2(\mathbb{R})$)

$$X(u, v) = (R \cos u \cos v, R \sin u \cos v, R \sin v)$$

$$\Rightarrow \begin{cases} X_u = R (-\sin u \cos v, \cos u \cos v, 0) \\ X_v = R (-\cos u \sin v, -\sin u \sin v, \cos v) \end{cases}$$

$$\Rightarrow X_u \times X_v = R^2 \cos v (\cos u \cos v, \sin u \cos v, \sin v)$$

$$\Rightarrow \Gamma = (\cos u \cos v, \sin u \cos v, \sin v)$$

$$S_p(X_u) = -\nabla_{X_u} U = -\sum_i X_u[u^i] e_i$$

□

$$= -(-\sin u \cdot \cos v, \cos u \cdot \cos v, 0)$$

$$= -\frac{1}{R} X_u$$

$$S_p(X_v) = -\frac{1}{R} X_v$$

Therefore $\forall v = \lambda X_u + \mu X_v \in T_p M$

$$S_p(v) = -\frac{1}{R} v$$

$$(i.e. S_p = -\frac{1}{R} \text{Id}_{T_p M})$$

