

THE CHINESE UNIVERSITY OF HONG KONG
Department of Mathematics
MATH4030 Differential Geometry
Solution of Assignment 3

1. (a)

$$\begin{aligned}X(u, v) &= (f(u) \cos v, f(u) \sin v, g(u)) \\X_u &= (f'(u) \cos v, f'(u) \sin v, g'(u)) \\X_v &= (-f(u) \sin v, f(u) \cos v, 0)\end{aligned}$$

$\{X_u, X_v\}$ is linearly independent since $g'(u) > 0$.
So the image S is a surface.

(b)

$$X_u \times X_v = (-fg' \cos v, -fg' \sin v, ff')$$

So the equation of the normal line is

$$\begin{aligned}\alpha(t) &= X(u, v) + tX_u \times X_v \\&= (f \cos v(1 - tg'), f \sin v(1 - tg'), g - tff')\end{aligned}$$

When $t = \frac{1}{g'}$, $\alpha(t) = (0, 0, g - \frac{ff'}{g'})$.

So the normal lines of S pass through the z-axis.

2. Let $x_0 \in S$, for any $y_0 \in S$

S is connected, so there is a smooth curve $\alpha(s) : [0, l] \rightarrow S$ such that

$$\alpha(0) = x_0, \alpha(l) = y_0$$

So $\alpha'(s) \in T_{\alpha(s)}S$ for any s .

By the assumption, all normal lines of S pass through p_0 ,

$$(p_0 - \alpha(s)) \perp T_{\alpha(s)}S$$

$$\langle p_0 - \alpha(s), \alpha'(s) \rangle = 0$$

$$\langle p_0 - \alpha(s), p_0 - \alpha(s) \rangle' = 0$$

So $|\alpha(s) - p_0| = R$ for some positive constant R . ($R > 0$ because $\alpha(s)$ contains not only one point)

$$|x_0 - p_0| = |y_0 - p_0| = R$$

So S lies on a sphere since y_0 is arbitrary.

3. Let $A = \sup\{|x - y| : x, y \in S\}$.
S is compact, so there are $x_0, y_0 \in S$ such that

$$|x_0 - y_0| = A$$

Let l be the straight line joining x_0 and y_0 .

Let $\alpha(s) : (-\epsilon, \epsilon) \rightarrow S$ be any regular curve in S with $\alpha(0) = x_0$.

So $\langle \alpha(s) - y_0, \alpha(s) - y_0 \rangle$ attains a maximum at $t = 0$,

$$\langle \alpha'(0), x_0 - y_0 \rangle = 0$$

So we have $\alpha'(0) \perp l$.

Then $T_{x_0}S \perp l$ since α is arbitrary.

Similarly, $T_{y_0}S \perp l$.

So l cuts S orthogonally at at least two points.

4. (a) Let $\{v_1, v_2\}$ be two unit vectors such that $\{v_1, v_2, a\}$ forms an orthonormal basis of \mathbb{R}^3 and,

$$\begin{aligned}v_1 \times v_2 &= a \\v_2 \times a &= v_1 \\a \times v_1 &= v_2\end{aligned}$$

Let $X(\theta, t) = r \cos \theta v_1 + r \sin \theta v_2 + ta$.

Then $X(\theta, t)$ is a parametrization of S .

For any $p_0 \in S$, then $t_0 = \langle p_0, a \rangle$ and $|p_0|^2 = r^2 + t_0^2$.

$$\begin{aligned}X_\theta &= -r \sin \theta v_1 + r \cos \theta v_2 \\X_t &= a \\X_\theta \times X_t &= r \sin \theta v_2 + r \cos \theta v_1 \\&= p_0 - t_0 a \\&= p_0 - \langle p_0, a \rangle a\end{aligned}$$

$v \in T_{p_0}S$

$$\Leftrightarrow \langle v, X_\theta \times X_t \rangle = 0$$

$$\Leftrightarrow \langle v, p_0 - \langle p_0, a \rangle a \rangle = 0$$

$$\Leftrightarrow \langle v, p_0 \rangle - \langle p_0, a \rangle \langle v, a \rangle = 0$$

$$\text{So } T_p S = \{v \in \mathbb{R}^3 : \langle v, p \rangle - \langle p, a \rangle \langle v, a \rangle = 0\}$$

- (b) The normal line of S at p is

$$\begin{aligned}\alpha(s) &= p + sX_\theta \times X_t \\&= p + s(p - \langle p, a \rangle a)\end{aligned}$$

$\alpha(-1) = \langle p, a \rangle a$ lies on the axis and $\langle X_\theta \times X_t, a \rangle = \langle X_\theta \times a, a \rangle = 0$.

So the normal lines of S cut the axis orthogonally.

- (c) Assume S is a connected surface whose normal lines all intersect a fixed straight line $l \subset \mathbb{R}^3$ orthogonally.

Let a be a unit direction vector of l .

Fix $x_0 \in S$, for any $y \in S$, there is a smooth regular curve $\beta(t) : [0, 1] \rightarrow S$ such that $\beta(0) = x_0, \beta(1) = y$.

Let $N(p)$ be a unit normal vector field of S .

Then by the assumption, $N // (p - \langle p, a \rangle a)$.

$$\begin{aligned}0 &= \langle \beta'(t), N \rangle \\&= \langle \beta'(t), p - \langle p, a \rangle a \rangle \\&= \langle \beta'(t), \beta(t) - \langle \beta(t), a \rangle a \rangle \\&= \langle \beta'(t), \beta(t) \rangle - \langle \beta'(t), a \rangle \langle \beta(t), a \rangle \\&= \frac{1}{2} [\langle \beta(t), \beta(t) \rangle - \langle \beta(t), a \rangle^2]'\end{aligned}$$

So $\langle \beta(t), \beta(t) \rangle - \langle \beta(t), a \rangle^2 = r^2$ for some positive constant r . (r is positive because β contains not only one point)

So $S \subset \{p \in \mathbb{R}^3 : |p|^2 - \langle p, a \rangle^2 = r^2\}$ since y is arbitrary.

5. (a) For any $p \in S$, let $X : U \subset \mathbb{R}^2 \rightarrow S$ be a parametrization of S around p .
 Then $(f \circ X)(u, v) = |X(u, v) - p_0| = \langle X(u, v) - p_0, X(u, v) - p_0 \rangle^{\frac{1}{2}}$.
 By the assumption $p_0 \notin S$, we have $X(u, v) - p_0 \neq 0$ for all $(u, v) \in U$.
 So $f \circ X$ is a smooth function near $X^{-1}(p)$.
 Then f is a smooth function on S .
 Let $\alpha(t) : (-\epsilon, \epsilon) \rightarrow S$ be any regular curve on S with $\alpha(0) = p$.

$$\begin{aligned} (f \circ \alpha)'(t) &= [\langle \alpha(t) - p_0, \alpha(t) - p_0 \rangle^{\frac{1}{2}}]' \\ &= \frac{\langle \alpha'(t), \alpha(t) - p_0 \rangle}{|\alpha(t) - p_0|} \end{aligned}$$

$$(f \circ \alpha)'(0) = 0 \iff \langle \alpha'(0), p - p_0 \rangle = 0$$

So $p \in S$ is a critical point of $f(p)$

$$\iff (f \circ \alpha)'(0) = 0 \text{ for any such } \alpha$$

$$\iff \langle \alpha'(0), p - p_0 \rangle = 0 \text{ for any such } \alpha$$

$$\iff (p - p_0) \perp T_p S$$

- (b) Let $Y : U \subset \mathbb{R}^2 \rightarrow S$ be a parametrization of S around p .
 $(h \circ Y)(u, v) = \langle Y(u, v), v \rangle$ is a smooth function near $Y^{-1}(p)$.
 So h is a smooth function on S .
 Let $\beta(t) : (-\epsilon, \epsilon) \rightarrow S$ be any regular curve on S with $\beta(0) = p$.

$$\begin{aligned} (h \circ \beta)'(t) &= \langle \beta(t), v \rangle' \\ &= \langle \beta'(t), v \rangle \end{aligned}$$

$$(h \circ \beta)'(0) = 0 \iff \langle \beta'(0), v \rangle = 0$$

So $p \in S$ is a critical point of $h(p)$

$$\iff (h \circ \beta)'(0) = 0 \text{ for any such } \beta$$

$$\iff \langle \beta'(0), v \rangle = 0 \text{ for any such } \beta$$

$$\iff v \perp T_p S$$

6. Let $X : [0, 2\pi) \times [0, 2\pi) \rightarrow \mathbb{R}^3$ be

$$X(\theta, \phi) = \langle \cos \phi(a + r \cos \theta), \sin \phi(a + r \cos \theta), r \sin \theta \rangle$$

Then X is a parametrization of S and X is bijective.

$$X_\theta = \langle -r \cos \phi \sin \theta, -r \sin \phi \sin \theta, r \cos \theta \rangle$$

$$X_\phi = \langle -\sin \phi(a + r \cos \theta), \cos \phi(a + r \cos \theta), 0 \rangle$$

$$|X_\theta|^2 = r^2, |X_\phi|^2 = (a + r \cos \theta)^2, \langle X_\theta, X_\phi \rangle = 0$$

So the area of S is

$$\begin{aligned} \text{Area} &= \int_0^{2\pi} \int_0^{2\pi} \sqrt{|X_\theta|^2 |X_\phi|^2 - \langle X_\theta, X_\phi \rangle^2} d\phi d\theta \\ &= \int_0^{2\pi} \int_0^{2\pi} r(a + r \cos \theta) d\phi d\theta \\ &= \int_0^{2\pi} (2\pi ar + 2\pi r^2 \cos \theta) d\theta \\ &= 4\pi^2 ar \end{aligned}$$

7. Let a be a regular value of F .

Then $S = F^{-1}(a)$ is a regular surface and $\nabla F \neq 0$ on S .

Let $p \in S$, let $\alpha(t) : (-\epsilon, \epsilon) \rightarrow S$ be any regular curve on S with $\alpha(0) = p$.

$$\begin{aligned}\alpha(t) &\subset S \\ (F \circ \alpha)(t) &= a \\ (F \circ \alpha)'(0) &= 0 \\ \langle \nabla F(p), \alpha'(0) \rangle &= 0\end{aligned}$$

So $\nabla F(p) \perp T_p S$ since such α is arbitrary.

F is a smooth function and $\nabla F \neq 0$ on S .

So $\frac{\nabla F}{|\nabla F|}$ defines a smooth unit normal vector field on S .

Then S is orientable.

8. $X_u = \langle \cos v, \sin v, 0 \rangle$, $X_v = \langle -u \sin v, u \cos v, b \rangle$

$$g_{uv} = \begin{bmatrix} 1 & 0 \\ 0 & b^2 + u^2 \end{bmatrix}$$

the area of the surface is

$$\begin{aligned} \text{area} &= \int_0^{2\pi} \int_1^3 \sqrt{\det(g_{uv})} du dv \\ &= \int_0^{2\pi} \int_1^3 \sqrt{b^2 + u^2} du dv \\ &= \int_0^{2\pi} \frac{1}{2} \left[u\sqrt{u^2 + b^2} + b^2 \ln |u + \sqrt{u^2 + b^2}| \right]_1^3 dv \\ &= \pi \left[3\sqrt{9 + b^2} - \sqrt{1 + b^2} + b^2 \ln(3 + \sqrt{9 + b^2}) - b^2 \ln(1 + \sqrt{1 + b^2}) \right] \end{aligned}$$

9. $\psi = \bar{X}^{-1} \circ X$

$$\bar{X}(\psi) = X$$

$$\bar{X}(\bar{u}(u, v), \bar{v}(u, v)) = X(u, v)$$

So we have

$$\begin{aligned} \frac{\partial X}{\partial u} &= \frac{\partial \bar{X}}{\partial \bar{u}} \frac{\partial \bar{u}}{\partial u} + \frac{\partial \bar{X}}{\partial \bar{v}} \frac{\partial \bar{v}}{\partial u} \\ \frac{\partial X}{\partial v} &= \frac{\partial \bar{X}}{\partial \bar{u}} \frac{\partial \bar{u}}{\partial v} + \frac{\partial \bar{X}}{\partial \bar{v}} \frac{\partial \bar{v}}{\partial v} \\ \begin{bmatrix} \frac{\partial X}{\partial u} \\ \frac{\partial X}{\partial v} \end{bmatrix} &= \begin{bmatrix} \frac{\partial \bar{u}}{\partial u} & \frac{\partial \bar{v}}{\partial u} \\ \frac{\partial \bar{u}}{\partial v} & \frac{\partial \bar{v}}{\partial v} \end{bmatrix} \begin{bmatrix} \frac{\partial \bar{X}}{\partial \bar{u}} \\ \frac{\partial \bar{X}}{\partial \bar{v}} \end{bmatrix} \end{aligned}$$

By the assumption

$$\begin{aligned} \begin{bmatrix} a_1 & a_2 \end{bmatrix} \begin{bmatrix} \frac{\partial X}{\partial u} \\ \frac{\partial X}{\partial v} \end{bmatrix} &= \begin{bmatrix} a_1 & a_2 \end{bmatrix} \begin{bmatrix} \frac{\partial \bar{u}}{\partial u} & \frac{\partial \bar{v}}{\partial u} \\ \frac{\partial \bar{u}}{\partial v} & \frac{\partial \bar{v}}{\partial v} \end{bmatrix} \begin{bmatrix} \frac{\partial \bar{X}}{\partial \bar{u}} \\ \frac{\partial \bar{X}}{\partial \bar{v}} \end{bmatrix} \\ &= \begin{bmatrix} b_1 & b_2 \end{bmatrix} \begin{bmatrix} \frac{\partial \bar{X}}{\partial \bar{u}} \\ \frac{\partial \bar{X}}{\partial \bar{v}} \end{bmatrix} \end{aligned}$$

So we get

$$\begin{bmatrix} b_1 & b_2 \end{bmatrix} = \begin{bmatrix} a_1 & a_2 \end{bmatrix} \begin{bmatrix} \frac{\partial \bar{u}}{\partial u} & \frac{\partial \bar{v}}{\partial u} \\ \frac{\partial \bar{u}}{\partial v} & \frac{\partial \bar{v}}{\partial v} \end{bmatrix}$$

which is

$$\begin{bmatrix} b_1 \\ b_2 \end{bmatrix} = \begin{bmatrix} \frac{\partial \bar{u}}{\partial u} & \frac{\partial \bar{v}}{\partial u} \\ \frac{\partial \bar{u}}{\partial v} & \frac{\partial \bar{v}}{\partial v} \end{bmatrix} \begin{bmatrix} a_1 \\ a_2 \end{bmatrix}$$

10. (a)

$$x^2 + y^2 + z^2 = ax$$

$$\left(x - \frac{a}{2}\right)^2 + y^2 + z^2 = \left(\frac{a}{2}\right)^2$$

So S_1 is the sphere centered at $(\frac{a}{2}, 0, 0)$ with radius $\frac{a}{2}$.

Similarly, S_2 is the sphere centered at $(0, \frac{b}{2}, 0)$ with radius $\frac{b}{2}$ and S_3 is the sphere centered at $(0, 0, \frac{c}{2})$ with radius $\frac{c}{2}$.

(b) Since S_1 and S_2 are spheres,

$$N_1 = \frac{2}{a}\left(x - \frac{a}{2}, y, z\right)$$

$$N_2 = \frac{2}{b}\left(x, y - \frac{b}{2}, z\right)$$

are unit normal vector fields of S_1 and S_2 .

Let $p = (x_0, y_0, z_0) \in S_1 \cap S_2$, then p satisfies

$$x_0^2 + y_0^2 + z_0^2 = ax_0$$

$$x_0^2 + y_0^2 + z_0^2 = by_0$$

So we have

$$ax_0 = by_0$$

Then we compute the angle between S_1 and S_2 ,

$$\begin{aligned} \langle N_1(p), N_2(p) \rangle &= \frac{4}{ab}\left(x_0^2 - \frac{a}{2}x_0 + y_0^2 - \frac{b}{2}y_0 + z_0^2\right) \\ &= \frac{4}{ab}\left(x_0^2 + y_0^2 + z_0^2 - \frac{a}{2}x_0 - \frac{b}{2}y_0\right) \\ &= \frac{4}{ab}\left(ax_0 - \frac{a}{2}x_0 - \frac{b}{2}y_0\right) \\ &= \frac{2}{ab}\left(ax_0 - by_0\right) \\ &= 0 \end{aligned}$$

So S_1 meets S_2 orthogonally.

Similarly, S_1 , S_2 , and S_3 all meet orthogonally.

11. Let $\phi : S_1 \rightarrow \mathbb{R}^3$ be

$$\phi(x, y, z) = \left(\frac{x}{a}, \frac{y}{b}, \frac{z}{c} \right)$$

Then we need to show that ϕ is a bijective differentiable map between S_1 and S_2 .

(a) Show that $\phi(S_1) \subset S_2$

Let $(x, y, z) \in S_1$, then

$$\begin{aligned} \frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} &= 1 \\ \left(\frac{x}{a}\right)^2 + \left(\frac{y}{b}\right)^2 + \left(\frac{z}{c}\right)^2 &= 1 \\ \|\phi(x, y, z)\| &= 1 \end{aligned}$$

So $\phi(x, y, z) \in S_2$.

(b) Show that ϕ is injective

$$\begin{aligned} \phi(x_1, y_1, z_1) &= \phi(x_2, y_2, z_2) \\ \left(\frac{x_1}{a}, \frac{y_1}{b}, \frac{z_1}{c}\right) &= \left(\frac{x_2}{a}, \frac{y_2}{b}, \frac{z_2}{c}\right) \\ (x_1, y_1, z_1) &= (x_2, y_2, z_2) \end{aligned}$$

So ϕ is injective.

(c) Show that ϕ is surjective

For any $(\bar{x}, \bar{y}, \bar{z}) \in S_2$, $\bar{x}^2 + \bar{y}^2 + \bar{z}^2 = 1$.

Let $(x, y, z) = (a\bar{x}, b\bar{y}, c\bar{z})$, then

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} = \bar{x}^2 + \bar{y}^2 + \bar{z}^2 = 1$$

So $(x, y, z) \in S_1$ and $\phi(x, y, z) = (\bar{x}, \bar{y}, \bar{z})$.

This means ϕ is surjective.

(d) Show that ϕ is differentiable

For any $p \in S_1$, let $X : U \rightarrow S_1$ be parametrization of S_1 around p .

So $\phi \circ X : \mathbb{R}^2 \rightarrow \mathbb{R}^3$ is smooth since X is smooth from \mathbb{R}^2 to \mathbb{R}^3 and ϕ is smooth from \mathbb{R}^3 to \mathbb{R}^3 .

So ϕ is a differentiable map from S_1 to S_2 .