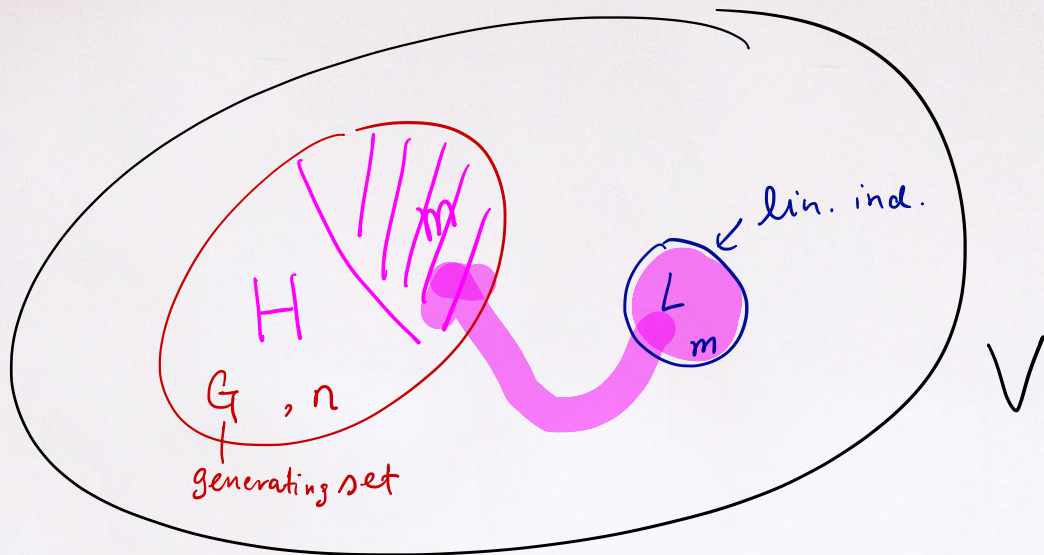


Lecture 6:

Recall:



① $m \leq n$

② $L \cup H \text{ span } V.$
 $L \subset G$

Dimension

Cor 1: Let V be a vector space having a finite basis.

Then, every basis of V contains the same number of vectors.

Pf: Let β and γ be two bases of V .

Since β spans V and γ is lin. independent,

then $|\gamma| \leq |\beta|$ (by replacement Thm)

Similarly, $|\beta| \leq |\gamma|$

$$\Rightarrow |\gamma| = |\beta|.$$

Definition: A vector space V is called finite-dimensional if it has a finite basis. The dimension of V , denoted as $\dim(V)$, is the number of vectors in a basis for V .

A vector space which is not finite-dimensional is called infinite-dimensional.

Example:

- F^n has dimension n .
- $P_n(F)$ has dimension $n+1$
- $P(F)$ is infinite dimensional
- $M_{n \times n}(F)$ has dimension n^2
- \mathbb{C} is a vector space over $F = \mathbb{C}$, has dimension 1
(Basis $\beta = \{1\}$)
- \mathbb{C} is a vector space over $F = \mathbb{R}$ has dimension 2
($\beta = \{1, i\}$)

Cor: Let V be a n -dimensional vector space.

- (a) Any finite spanning set has at least n vectors, and a spanning set with exactly n vectors is a basis for V .
- (b) Any linearly independent subset of V of size n is a basis for V .
- (c) Every linearly independent subset of V can be extended to a basis of V .

Pf: Let β be a basis for V ($|\beta| = n$)

(a) Let G be a finite spanning set for V . Then:

$\exists \gamma \subset G$ which is a basis for V (last time)

$$\therefore |\gamma| = n \leq |G|$$

If $|G| = |\gamma|$, then: $G = \gamma$ is a basis for V .



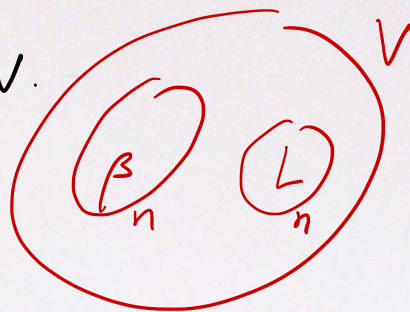
(b) Let $L \subset V$ be a lin. independent subset of size n .

By the replacement theorem, $\exists H \subset \beta$ of size $|\beta| - |L| = 0$ such that $L \cup H$ span V .

But $|H| = 0. \therefore H = \emptyset$.

$\therefore L \cup H = L \cup \emptyset = L$ span V .

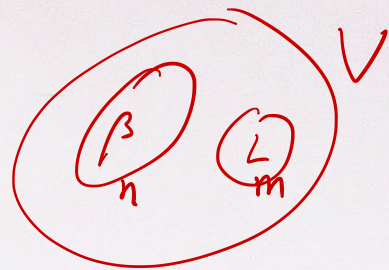
$\therefore L$ is a basis



(c) Let $L \subset V$ be a linearly independent subset of size m .

By the replacement theorem, ① $m \leq n$

② $\exists H \subset \beta$ of size $n-m$ such
that $\underbrace{L}_m \cup \underbrace{H}_{n-m}$ span V .



$$\therefore |L \cup H| = m + n - m = n$$

By (a), $L \cup H$ is a spanning set with exactly
 n elements $\Rightarrow L \cup H$ is a basis.
" "
 $\dim(V)$

Theorem: Let V be a finite-dimensional vector space.

Then any subspace $W \subset V$ is finite-dimensional and $\dim(W) \leq \dim(V)$

Moreover, if $\dim(W) = \dim(V)$, then $W = V$.

Proof: Let $n = \dim(V)$. If $W = \{\vec{0}\}$, then

$$\dim(W) = 0 \leq n \quad (\text{span}(\emptyset) = \{\vec{0}\})$$



Otherwise, W contains a non-zero \vec{u}_1 . So, $\{\vec{u}_1\}$ is lin. indep subset of W . If $\text{span}\{\vec{u}_1\} = W$, then $\{\vec{u}_1\}$ is a basis of W .

Otherwise, choose $\vec{u}_2 \in W \setminus \text{Span}\{\vec{u}_1\}$. Then, by a thm before,

$\{\vec{u}_1, \vec{u}_2\}$ is linearly indep. of W .

If $\{\vec{u}_1, \vec{u}_2\}$ span W , then $\{\vec{u}_1, \vec{u}_2\}$ is a basis.

Repeat this process to produce a larger and larger lin. indep.

But a lin. indep. subset of V has size $\leq n$.

The above process must stop, say, it stops at

producing a lin. indep. subset $\beta = \{ \vec{u}_1, \vec{u}_2, \dots, \vec{u}_k \}$ of W
with $k \leq n$. Then, β is a basis of W .

$\therefore \dim(W) = k \leq n$.

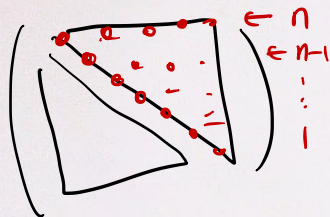
If $\dim(W) = \dim(V) = n$ and $\beta = \{ \vec{u}_1, \vec{u}_2, \dots, \vec{u}_n \}$
is a lin. indep. subset of V . Then, β is a basis of V

and $W = \text{span}(\beta) = V$ //

e.g. . Set W of symmetric $n \times n$ matrices ($A^t = A$) is
 a subspace of $M_{n \times n}(F)$ of $\dim = 1 + 2 + \dots + (n-1) + n$

$$= \frac{1}{2} (n)(n+1) \leq n^2$$

" $\dim(V)$



Corollary: If W is a subspace of a fin-dimensional vector space V , then any basis of W can be extended to a basis of V .

Proof: Exercise

Linear Transformation

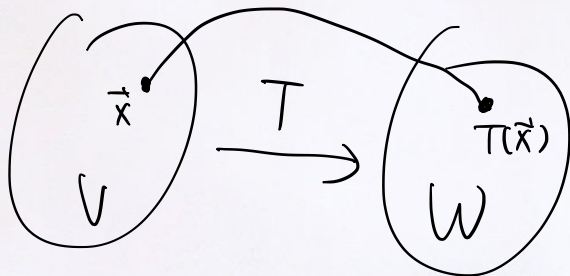
Definition: Let V and W be vector spaces over F .

A linear transformation from V to W is a map $T: V \rightarrow W$

such that: (a) $T(\vec{x} + \vec{y}) = T(\vec{x}) + T(\vec{y})$

(b) $T(a\vec{x}) = aT(\vec{x})$

for all $\vec{x}, \vec{y} \in V$, $a \in F$.



Proposition: Let $T: V \rightarrow W$ be a linear transformation. Then:

$$(i) \quad T(\vec{0}_V) = \vec{0}_W$$

$$(ii) \quad T\left(\sum_{i=1}^n a_i \vec{x}_i\right) = \sum_{i=1}^n a_i T(\vec{x}_i) \quad \forall \vec{x}_1, \vec{x}_2, \dots, \vec{x}_n \in V$$

(T preserves linear combination) $a_1, a_2, \dots, a_n \in F.$

$$(i) \quad T(\vec{0}_V) = T(\vec{0}_V + \vec{0}_V) = T(\vec{0}_V) + T(\vec{0}_V)$$

$$\Rightarrow T(\vec{0}_V) = \vec{0}_W. \quad (\text{Cancellation law})$$

(ii) Use math. induction (exercise)

Examples: • For any vector spaces V and W , we have:

(a) The zero transformation $T_0: V \rightarrow W$ defined by $T_0(\vec{x}) := \vec{0}_W$
for $\forall \vec{x} \in V$

(b) The identity transformation $I_V: V \rightarrow V$ defined by $I_V(\vec{x}) = \vec{x}$
for $\forall \vec{x} \in V$.

• Let $A \in M_{m \times n}(F)$ be a $m \times n$ matrix in F .

Define: $L_A: F^n \rightarrow F^m$ as: ($F^n =$ space of col vectors of size n)

$$L_A(\vec{x}) \stackrel{\text{def}}{=} A\vec{x}$$

L_A is called the left multiplication by A .

• $T: M_{m \times n}(F) \rightarrow M_{n \times m}(F)$ defined by $T(A) \stackrel{\text{def}}{=} A^t$ (transpose of A)

- $T: P_n(\mathbb{R}) \rightarrow P_{n-1}(\mathbb{R})$ defined by $T(f(x)) = f'(x)$
is a lin. transf. (derivative of f)

- Let a and $b \in \mathbb{R}$, $a < b$. Then,

$T: C(\mathbb{R}) \rightarrow \mathbb{R}$ defined by =
(Space of continuous functions)

$$T(f) \stackrel{\text{def}}{=} \int_a^b f(t) dt$$

Null space or Range

Definition: Let V and W be vector spaces and $T: V \rightarrow W$ be a linear transformation

Then, the null space (or kernel) of T is defined as:

$$N(T) := \text{def } \{ \vec{x} \in V : T(\vec{x}) = \vec{0}_W \} \subset V$$

the range (or image) of T is defined as:

$$R(T) := \{ T(\vec{x}) : \vec{x} \in V \} \subset W$$

e.g. For $I_V: V \rightarrow V$, $N(I_V) = \{ \vec{0}_V \}$, $R(I_V) = V$
(identity)

For $T_0: V \rightarrow W$, $N(T_0) = V$, $R(T_0) = \{ \vec{0}_W \}$
(zero transf)

• $L_A: F^n \rightarrow F^m$ ($A \in M_{m \times n}(F)$)

$$N(L_A) = N(A) = \text{null space of } A$$

$$R(L_A) = \mathcal{C}(A) = \text{col space of } A$$

(space of linear combination of col vectors of A)

• For $T: P_n(\mathbb{R}) \rightarrow P_{n-1}(\mathbb{R})$ defined by

$$T(f(x)) = f'(x), \text{ then:}$$

$$N(T) = \{ a_0 \in P_n(\mathbb{R}) : a_0 \in \mathbb{R} \}$$

$$R(T) = P_{n-1}(\mathbb{R})$$

$$A = \begin{pmatrix} | & | & \dots & | \end{pmatrix}$$

Proposition: Let $T: V \rightarrow W$ be a linear transformation.

Then: $N(T)$ and $R(T)$ are subspaces of V and W respectively,

Proof: $\because T(\vec{0}_V) = \vec{0}_W$

$\therefore \vec{0}_V \in N(T)$ and $\vec{0}_W \in R(T)$

Let \vec{x} and $\vec{y} \in N(T)$ and $a \in F$. Then:

$$T(\vec{x} + \vec{y}) = T(\vec{x}) + T(\vec{y}) = \vec{0}_W + \vec{0}_W = \vec{0}_W \quad \text{and}$$

$$T(a\vec{x}) = aT(\vec{x}) = a\vec{0}_W = \vec{0}_W$$

$\therefore \vec{x} + \vec{y} \in N(T)$ and $a\vec{x} \in N(T)$

$\therefore N(T)$ is a subspace of V .

Now, let $\vec{u}, \vec{v} \in R(T)$ and $a \in F$.

Then: $\exists \vec{x}, \vec{y} \in V$ such that $\vec{u} = T(\vec{x})$ and $\vec{v} = T(\vec{y})$

$$\text{So, } T(\vec{x} + \vec{y}) = T(\vec{x}) + T(\vec{y}) = \vec{u} + \vec{v} \Rightarrow \vec{u} + \vec{v} \in R(T)$$

$$T(a\vec{x}) = aT(\vec{x}) = a\vec{u} \Rightarrow a\vec{u} \in R(T)$$

$\therefore R(T)$ is a subspace of W .

Remark: $T: V \rightarrow W$ is onto iff $R(T) = W$
(follows from the def)

Proposition: A linear transformation $T: V \rightarrow W$ is one-to-one iff $N(T) = \{\vec{0}\}$.

Pf: (Recap: One-to-one \Leftrightarrow " $T(\vec{x}) = T(\vec{y}) \Rightarrow \vec{x} = \vec{y}$ ")

(\Rightarrow) If T is one-to-one, then: for any $\vec{x} \in N(T)$,

$$\text{we have } T(\vec{x}) = \vec{0}_W = T(\vec{0}_V)$$

$$\Rightarrow \vec{x} = \vec{0}_V$$

This implies $N(T) = \{\vec{0}_V\}$.

(\Leftarrow) Suppose $N(T) = \{\vec{0}_V\}$

Let $\vec{x}, \vec{y} \in V$ such that $T(\vec{x}) = T(\vec{y})$.

Then: $T(\vec{x}) - T(\vec{y}) = T(\vec{x} - \vec{y}) = \vec{0}$

This implies $\vec{x} - \vec{y} \in N(T) = \{\vec{0}_V\}$

$\therefore \vec{x} - \vec{y} = \vec{0}_V$ or $\vec{x} = \vec{y}$.

$\therefore T$ is 1-1.