

# Regular surfaces 1

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A subset  $M \subset \mathbb{R}^3$  is said to be a *regular surface* if for any  $p \in M$ , there is an open neighborhood  $U$  of  $p$  in  $M$ , an open set  $D$  in  $\mathbb{R}^2$  and a map  $\mathbf{X} : D \rightarrow M \cap U$  such that the following are true:

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(rs1)  $\mathbf{X}$  is *smooth*.

(rs2)  $d\mathbf{X}$  is *full rank*:  $\mathbf{X}_u = \frac{\partial \mathbf{X}}{\partial u}$  and  $\mathbf{X}_v = \frac{\partial \mathbf{X}}{\partial v}$  are linearly independent, for any  $(u, v) \in D$ .

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- (rs2)  $d\mathbf{X}$  is *full rank*:  $\mathbf{X}_u = \frac{\partial \mathbf{X}}{\partial u}$  and  $\mathbf{X}_v = \frac{\partial \mathbf{X}}{\partial v}$  are linearly independent, for any  $(u, v) \in D$ .
- (rs3)  $\mathbf{X}$  is a *homeomorphism from  $D$  onto  $M \cap U$* . (That is:  $\mathbf{X}$  is bijective,  $\mathbf{X}$  and  $\mathbf{X}^{-1}$  are continuous).

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So a regular surface is a set  $M$  in  $\mathbb{R}^3$  which can be covered by a family of coordinate charts.



$X$  has full rank

# $X$ is a homeomorphism

# Example 1: graphs, $z = f(x, y)$

Example 2: spheres,  $\{x^2 + y^2 + z^2 = 1\}$

# Spherical coordinates

# Stereographic projection

## Proposition

Let  $f : U \rightarrow \mathbb{R}$  be a smooth function on an open set  $U \subset \mathbb{R}^2$ .

Then the graph of  $f$  defined by the following is a regular surface:

$$\text{graph}(f) = \{(x, y, f(x, y)) \mid (x, y) \in U\}.$$

# Regular surfaces are graphs locally

## Proposition

*Let  $M$  be regular surface and let  $\mathbf{X} : U \rightarrow M$  be a coordinate parametrization. Then for any  $p = (u_0, v_0) \in U$  there is a open set  $V \subset U$  with  $p \in V$  such that  $\mathbf{X}(V)$  is a graph over an open set in one of the coordinate plane.*



# Review on inverse function theorem

Let  $F : U \subset \mathbb{R}^n \rightarrow \mathbb{R}^m$  be a smooth map from an open set  $U$  to  $\mathbb{R}^m$ ,  $F(\mathbf{x}) = \mathbf{y}(\mathbf{x}) = (y^1, \dots, y^m)$  where  $\mathbf{x} = (x^1, \dots, x^n)$ ,  $\mathbf{y} = (y^1, \dots, y^m)$ . Let  $\mathbf{x}_0 = (x_0^1, \dots, x_0^n) \in U$ . The Jacobian matrix of  $F$  at  $\mathbf{x}_0$  is the  $m \times n$  matrix

$$dF_{\mathbf{x}_0} = \left( \frac{\partial y^i}{\partial x^j}(\mathbf{x}_0) \right).$$

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## Theorem

**(Inverse Function Theorem)** Let  $F : U \subset \mathbb{R}^n \rightarrow \mathbb{R}^n$  be a smooth map. Suppose  $F(\mathbf{x}_0) = \mathbf{y}_0$  and  $dF_{\mathbf{x}_0}$  is nonsingular. Then there exist open sets  $U \supset V \ni \mathbf{x}_0$  and  $W \ni \mathbf{y}_0$ , such that  $F$  is a diffeomorphism from  $V$  to  $W$ . That is to say,  $F : V \rightarrow W$  is bijective and  $F^{-1}$  is also smooth on  $W$ .

# Proof of the inverse function theorem

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May assume that  $\mathbf{x}_0 = \mathbf{0} = \mathbf{y}_0$ . Let  $A = dF_{\mathbf{x}_0}$ .

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$$F(\mathbf{x}) = A\mathbf{x} + G(\mathbf{x}),$$

$$G(\mathbf{x}_1) - G(\mathbf{x}_2) = o(|\mathbf{x}_1 - \mathbf{x}_2|) \text{ as } \mathbf{x}_1, \mathbf{x}_2 \rightarrow \mathbf{0}.$$

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Hence for any  $\epsilon > 0$ , we can find  $\delta > 0$  such that if  $\mathbf{x}_1, \mathbf{x}_2 \in B(\mathbf{0}, \delta) = \{|\mathbf{x}| < \delta\}$ , we have ,

$$|F(\mathbf{x}_1) - F(\mathbf{x}_2)| \geq |A(\mathbf{x}_1 - \mathbf{x}_2)| - \epsilon|\mathbf{x}_1 - \mathbf{x}_2|$$

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From this we conclude that  $F$  is one-one in  $B(\mathbf{0}, \delta)$  if  $\epsilon > 0$  is small enough.

# Proof (cont.)

Let  $\mathbf{y}_1 \in \mathbb{R}^n$ . Want to find  $\mathbf{x}$  so that  $F(\mathbf{x}) = A\mathbf{x} + G(\mathbf{x}) = \mathbf{y}_1$ .

# Proof (cont.)

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$\exists \mathbf{x}_1, A\mathbf{x}_1 = \mathbf{y}_1$ . (?) Inductively,  $\exists \mathbf{x}_{n+1}$  with  
 $A\mathbf{x}_{n+1} = \mathbf{y}_1 - G(\mathbf{x}_n)$ .



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There is  $\rho > 0$  such that if  $|\mathbf{y}_1| < \rho$ , then  $\mathbf{x}_n \in B(\mathbf{0}, \frac{1}{2}\delta)$  and  
 $\mathbf{x}_n \rightarrow \mathbf{x} \in B(\mathbf{0}, \delta)$ . (Why?)

# Idea of proof

## Proof:

(Sketch) Let  $\mathbf{X}(u, v) = (x(u, v), y(u, v), z(u, v))$ . May assume that at  $(u_0, v_0)$

$$\det \begin{pmatrix} x_u & x_v \\ y_u & y_v \end{pmatrix} \neq 0.$$

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Let  $(x_0, y_0) = (x(u_0, v_0), y(u_0, v_0))$ . By the inverse function theorem, there is a nbh of  $U_1$  of  $(u_0, v_0)$  and  $W$  of  $(x_0, y_0)$  so that  $(u, v) \rightarrow (x, y)$  has a smooth inverse .

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Then the image of  $U_1$  under  $\mathbf{X}$  is of the form

$$\begin{aligned} (x, y) &\rightarrow (u(x, y), v(x, y)) \\ &\rightarrow (x(u(x, y)), y(u(x, y)), z(u(x, y), v(x, y))) \\ &= (x, y, f(x, y)). \end{aligned}$$

## Proposition

Let  $U$  be an open set in  $\mathbb{R}^3$  and let  $f : \mathbb{R}^3 \rightarrow \mathbb{R}$  be a smooth function. Suppose  $a$  is a regular value of  $f$ . (That is: if  $f(x, y, z) = a$ , then  $\nabla f(x) \neq \mathbf{0}$ .) Then

$$M = \{(x, y, z) \in U \mid f(x) = a\}$$

is a regular surface.

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Consider the map:  $F : U \rightarrow \mathbb{R}^3$  defined by  
 $F(x, y, z) = (x, y, f(x, y, z))$ . Then the Jacobian matrix is invertible at  $p = (x_0, y_0, z_0)$ .



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Let  $F(x_0, y_0, z_0) = (u_0, v_0, t_0) = q$ , with  $t_0 = a$ . Then there exist nbh  $V$  of  $p$  and  $W$  of  $q$  so that  $F$  has a smooth inverse  $F^{-1}$ .

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Let  $W_1 = \{(u, v) | (u, v, a) \in W\}$ . Then for  $(x, y, z) \in V \cap M$ ,  $F(x, y, z) = (x, y, a) = (u, v, g(u, v, a))$  and so this set is the graph of over  $(u, v)$ .

# More examples: Quadratic surfaces



# Surfaces of revolution

# Ruled surfaces