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- Let $M = \{ax + by + cz + d = 0\}$. Then we can choose $\mathbf{N} = \frac{(a,b,c)}{\sqrt{a^2+b^2+c^2}}$. So $\mathcal{S}_p(\mathbf{v}) = \mathbf{0}$.

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  So $\mathcal{S}_p(\mathbf{v}) = -\frac{d}{dt} N(x(t), y(t), z(t))|_{t=0} = -\mathbf{v}$. And $\mathcal{S}_p = -\mathrm{Id}$.

More examples

- Let $M = \{x^2 + y^2 = 1\}$ the circular cylinder. Parametrize M by $\mathbf{X}(u, v) = (\cos u, \sin u, v)$. Then $\mathbf{X}_u = (-\sin u, \cos u, 0), \mathbf{X}_v = (0, 0, 1)$.

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The second fundamental form

Definition

Let $\mathcal{S}$ be the shape operator with respect to a unit normal vector field $\mathbf{N}$, the second fundamental form $\mathbb{II}_p$ of M at p (with respect to $\mathbf{N}$) is the bilinear form $\mathbb{II}_p(\mathbf{v}, \mathbf{w}) = g(\mathcal{S}_p(\mathbf{v}), \mathbf{w}) = \langle \mathcal{S}_p(\mathbf{v}), \mathbf{w} \rangle$.

Proposition

$\mathbb{II}_p$ is a symmetric bilinear form on $T_p(M)$.

Proof:

$$\mathbb{II}_p(\mathbf{v}, \mathbf{w}) = \langle \mathcal{S}_p(\mathbf{v}), \mathbf{w} \rangle = \langle \mathbf{v}, \mathcal{S}_p(\mathbf{w}) \rangle = \mathbb{II}_p(\mathbf{w}, \mathbf{v})$$

because $\mathcal{S}_p$ is self-adjoint.

Coefficients of the second fundamental form

With the same notation as in the previous section of M. Let $\mathbf{N} = \mathbf{X}_u \times \mathbf{X}_v / |\mathbf{X}_u \times \mathbf{X}_v|$.

Definition

The coefficients of the second fundamental form e, f, g at p are defined as:

$$\begin{aligned} e =& \mathrm{II}_p(\mathbf{X}_u, \mathbf{X}_u); \\ f =& \mathrm{II}_p(\mathbf{X}_u, \mathbf{X}_v); \\ g =& \mathrm{II}_p(\mathbf{X}_v, \mathbf{X}_v). \end{aligned}$$

Notation: Suppose we use (u^1, u^2) as coordinates, and $\mathbf{N} = \mathbf{X}_1 \times \mathbf{X}_2 / |\mathbf{X}_1 \times \mathbf{X}_2|$, then the coefficients of the second fundamental form are denoted by

$$h_{11} = \mathrm{II}_p(\mathbf{X}_1, \mathbf{X}_1); h_{12} = \mathrm{II}_p(\mathbf{X}_1, \mathbf{X}_2) = h_{21}; h_{22} = \mathrm{II}_p(\mathbf{X}_2, \mathbf{X}_2).$$

Coefficients of the second fundamental form, cont.

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Similarly, $f = \langle \mathbf{N}, \mathbf{X}_{uv} \rangle, g = \langle \mathbf{N}, \mathbf{X}_{vv} \rangle$.

To compute e, f, g

Proposition

$$
\begin{aligned}
e =& \langle \mathbf{N}, \mathbf{X}_{uu} \rangle = \frac{\det\left(\mathbf{X}_u, \mathbf{X}_v, \mathbf{X}_{uu}\right)}{\sqrt{EG - F^2}} \\
f =& \langle \mathbf{N}, \mathbf{X}_{uv} \rangle = \frac{\det\left(\mathbf{X}_u, \mathbf{X}_v, \mathbf{X}_{uv}\right)}{\sqrt{EG - F^2}}; \\
g =& \langle \mathbf{N}, \mathbf{X}_{vv} \rangle = \frac{\det\left(\mathbf{X}_u, \mathbf{X}_v, \mathbf{X}_{vv}\right)}{\sqrt{EG - F^2}}.
\end{aligned}
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Examples

- Consider the torus: $\mathbf{X}(u,v) = ((a + r\cos u)\cos v, (a + r\cos u)\sin v, r\sin u)$. Then

$$\begin{cases} \mathbf{X}_u = (-r\sin u\cos v, -r\sin u\sin v, r\cos u) \\ \mathbf{X}_v = (-(a + r\cos u)\sin v, (a + r\cos u)\cos v, 0) \\ \mathbf{X}_{uu} = (-r\cos u\cos v, -r\cos u\sin v, -r\sin u) \\ \mathbf{X}_{uv} = (r\sin u\sin v, -\sin u\cos v, 0) \\ \mathbf{X}_{vv} = (-(a + r\cos u)\cos v, -(a + r\cos u)\sin v, 0) \end{cases}$$

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Gaussian curvature and mean curvature

- Recall: suppose V^2 is vector space V^2. Let $\beta = \{\mathbf{e}_1, \mathbf{e}_2\}$ be an *ordered* basis for V_2. Let $\mathbf{v} \in V^2$, then $\mathbf{v} = c_1\mathbf{e}_1 + c_2\mathbf{e}_2$. Then $[c_1, c_2]^T$ as a column vector if called the coordinates of $\mathbf{v}$ w.r.t. β, denoted by $[\mathbf{v}]_\beta$.

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- Let T be a linear map on V^2. Then $T(\mathbf{e}_i) = \sum_{j=1}^{2} a_i^j \mathbf{e}_j$. Then the matrix of T w.r.t. β is $[T]_\beta = \begin{pmatrix} a_1^1 & a_2^1 \\ a_1^2 & a_2^2 \end{pmatrix}$.

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- We have $[T(\mathbf{v})]_\beta = [T]_\beta [\mathbf{v}]_\beta$. E.g.

$$[T(\mathbf{e}_1)]_\beta = \begin{pmatrix} a_1^1 & a_2^1 \\ a_1^2 & a_2^2 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} a_1^1 \\ a_1^2 \end{pmatrix}.$$

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- There are two invariants of T: its determinant and its trace. They are independent of the ordered basis chosen.

Gaussian curvature and mean curvature, cont.

Suppose $\mathcal{S}_p(\mathbf{X}_u) = a_1^1\mathbf{X}_u + a_1^2\mathbf{X}_v, \mathcal{S}_p(\mathbf{X}_v) = a_2^1\mathbf{X}_u + a_2^2\mathbf{X}_v$. Then the matrix of S_p with respect to the ordered basis $\beta = \{\mathbf{X}_u, \mathbf{X}_v\}$ is given by

$$[\mathcal{S}_p]_\beta = \begin{pmatrix} a_1^1 & a_2^1 \\ a_1^2 & a_2^2 \end{pmatrix}$$

Definition

The Gaussian curvature $K(p)$ of M at p is the determinant of $\mathcal{S}_p$. The mean curvature $H(p)$ of M at p is $1/2\times$ the trace of $\mathcal{S}_p$.

Proposition

1. *Let*

$$\begin{pmatrix} a_1^1 & a_2^1 \\ a_1^2 & a_2^2 \end{pmatrix}$$

be the matrix of $\mathcal{S}_p$ with respect to the ordered basis $\{\mathbf{X}_u, \mathbf{X}_v\}$. Then

$$\begin{pmatrix} a_1^1 & a_2^1 \\ a_1^2 & a_2^2 \end{pmatrix} = \begin{pmatrix} e & f \\ f & g \end{pmatrix} \begin{pmatrix} E & F \\ F & G \end{pmatrix}^{-1}.$$

2. *The Gaussian curvature $K(p)$ and the mean curvature $H(p)$ of M at p are given by*

$$K(p) = \frac{eg - f^2}{EG - F^2},$$

and

$$H(p) = \frac{1}{2}\frac{eG - 2fF + gE}{EG - F^2}.$$

If we use coordinates (u^1, u^2) and coefficients of the first and second fundamental forms are g_{ij}, h_{ij}, then

$$\begin{pmatrix} a_1^1 & a_2^1 \\ a_1^2 & a_2^2 \end{pmatrix} = (h_{ij}) \times (g_{ij})^{-1}.$$

$$K(p) = \frac{h_{11}h_{22} - h_{12}^2}{g_{11}g_{22} - g_{12}^2} = \frac{\det(h_{ij})}{\det(g_{ij})},$$

and

$$H(p) = \frac{1}{2}\frac{h_{11}g_{22} - 2h_{12}g_{12} + h_{22}g_{11}}{g_{11}g_{22} - g_{12}^2} = \frac{1}{2}\sum_{i,j} h_{ij}g^{ij}.$$

where $(g^{ij}) = (g_{ij})^{-1}$.

Two remarks

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- Gaussian curvature is invariant under reparametrization.

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- Gaussian curvature is invariant under reparametrization.
- Mean curvature is invariant under *orientation preserving* reparametrization.

Proof of the proposition

Proof:

It is more easy to use parametrization of the form $\mathbf{X}(u^1, u^2)$. Denote $\mathbf{X}_1 = \mathbf{e}_1$, $\mathbf{X}_2 = \mathbf{e}_2$. If the matrix of $\mathcal{S}_p$ w.r.t. this ordered basis β is given above. Then

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Let $g_{ij} = \langle e_i, e_j \rangle$

Now $h_{ij} = \langle \mathcal{S}_p(\mathbf{e}_i), \mathbf{e}_j \rangle = \langle \sum_k a_i^k \mathbf{e}_k, \mathbf{e}_j \rangle = \sum_k a_i^k g_{jk}$. Hence $[h_{ij}] = [\mathcal{S}]_\beta [g_{ij}]$. So

$$[\mathcal{S}]_\beta = [h_{ij}][g_{ij}]^{-1}.$$

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- Let M be the unit sphere. If we choose $\mathbf{N}$ as before, then $\mathcal{S}$ is negative of the identity. So Gaussian curvature is 1 and mean curvature is -1.
- For the torus, and the choice of normal vector as before, we have $E = r^2, F = 0, G = (a + r\cos u)^2$.
  $e = \det(\mathbf{X}_u, \mathbf{X}_v, \mathbf{X}_{uu})/r(a + r\cos u) = r$.
  $f = 0, g = \cos u(a + r\cos u)$. Hence

  $$K = \frac{\cos u}{r(a + r\cos u)}.$$

  So $K > 0$ for $-\frac{3}{2}\pi < u < \frac{1}{2}\pi$, $K = 0$ on $u = \frac{1}{2}\pi, -\frac{3}{2}\pi$, $K < 0$ for $\frac{1}{2}\pi < u < \frac{3}{2}\pi$.