

1. (a) No

Clearly, $(1, 0, 1) \in W_1$, $(0, 1, 1) \in W_1$.

But, $(1, 0, 1) + (0, 1, 1) = (1, 1, 2) \notin W_1$.

(b) No

Clearly, $\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \in W_2$, $\begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} \in W_2$,

but $\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} + \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \notin W_2$.

2. (a) No.

$$T(i) = i - \bar{i} = 2i,$$

$$iT(i) = -2 \neq T(i \cdot i) = T(-1) = -1 - \bar{-1} = 0$$

Remark:

(1) So if you consider two cases: $\mathbb{F} = \mathbb{R}$ and $\mathbb{F} = \mathbb{C}$.

But this is not necessary.

The reason is that as stated in the question,

\mathbb{C} is taken to be a one-dimensional complex space here.

If $\mathbb{F} = \mathbb{R}$, the dimension of \mathbb{C} over \mathbb{R} is 2.

(2) For 1(a), 1(b), and 2(a),

the best way to prove some statement is not correct

is to directly give a counter-example.

$$(b) \cdot T \mathbf{0} = \mathbf{0}.$$

$$\cdot \text{Let } \mathbf{a} = (a_1, a_2, \dots), \mathbf{b} = (b_1, b_2, \dots)$$

$$\begin{aligned} \text{Then, } T \mathbf{a} + T \mathbf{b} &= (a_1 + a_1, a_2 + a_1, \dots) + (b_1 + b_1, b_2 + b_1, \dots) \\ &= \left((a_1 + b_1) + (a_1 + b_1), (a_2 + b_2) + (a_1 + b_1), \dots \right) \\ &= T(\mathbf{a} + \mathbf{b}) \end{aligned}$$

$$\cdot \text{Let } c \in \mathbb{F},$$

$$\begin{aligned} \text{then } cT(\mathbf{a}) &= c(a_1 + a_1, a_2 + a_1, \dots) \\ &= (ca_1 + ca_1, ca_2 + ca_1, \dots) \\ &= T(c\mathbf{a}) \end{aligned}$$

Hence, T is linear.

$$3. \text{ Suppose } T(x, y, z) = (x_1, y_1, z_1).$$

Then, we know $\left(\frac{x+x_1}{2}, \frac{y+y_1}{2}, \frac{z+z_1}{2}\right)$ is on the plane $x - 2z = 0$,

$$\text{namely, } \frac{x+x_1}{2} - 2 \cdot \frac{z+z_1}{2} = 0 \quad - (1)$$

Also, note that $(2, 0, 1)$, $(2, 1, 1)$ and $(4, 0, 2)$ are all contained by the plane $x - 2z = 0$.

$$\text{Hence } \left((x, y, z) - (x_1, y_1, z_1)\right) \cdot \left((2, 1, 1) - (2, 0, 1)\right) = 0 \quad - (2)$$

$$\left((x, y, z) - (x_1, y_1, z_1)\right) \cdot \left((4, 0, 2) - (2, 0, 1)\right) = 0 \quad - (3)$$

Combining (1), (2), and (3),

we see $(x_1, y_1, z_1) = T(x, y, z)$

$$= \left(\frac{3x}{5} + \frac{4z}{5}, y, \frac{4x}{5} - \frac{3z}{5} \right)$$

4. (a) Let $p \in V$.

Then, $T(p) = 0 \Leftrightarrow p(1) = p(2) = \dots = p(100) = 0$.

So, $p(x) = (x-1)(x-2)\dots(x-100)q(x)$,

where $\deg q(x) \leq 999 - 100 = 899$.

Since $q(x)$ can be arbitrary,

$\dim \ker T = 899 + 1 = 900$.

(b) $\dim \text{range } T = \dim V - \dim \ker T = 100$.

5.

- If $E = \emptyset$, then the result is trivial.

- If $E \neq \emptyset$, then there exists some $T \in E$,

s.t., $Tv = w$ for some non-zero $v, w \in V$.

Let $\{v_1, \dots, v_n\}$ be a basis of V .

Then, for $i = 1, 2, \dots, n$,

define $R_i(v_j) = \begin{cases} v, & \text{if } j=i \\ 0, & \text{else} \end{cases}$ for $j = 1, \dots, n$.

$$S_i(u) = \begin{cases} v_i, & \text{if } u = w \text{ for arbitrary } u \in V. \\ 0, & \text{else} \end{cases}$$

$$\text{Hence, } S_i T R_i (v_j) = \begin{cases} v_i, & \text{if } i = j \\ 0, & \text{else} \end{cases}$$

$$\text{Let } T_0 = S_1 T R_1 + S_2 T R_2 + \dots + S_n T R_n \in \bar{E}.$$

Clearly, T_0 is the identity map I .

Then, for any $S \in \mathcal{L}(V)$,

$$S = S I \in \bar{E}.$$

$$\Rightarrow \bar{E} = \mathcal{L}(V).$$