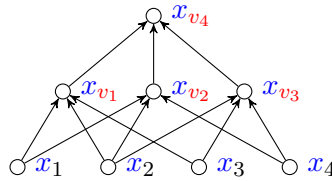


Notes 16: Neural networks

What is the VC dimension of a neural network?

Define **neural network** N as directed acyclic graph G with LTFs at internal nodes



G specifies the network architecture and is fixed

G has n input nodes $1, \dots, n$ and s internal nodes v_1, \dots, v_s

Input nodes (those without incoming edges) receive input signals $x_1, \dots, x_n \in \mathbb{R}$

Node/neuron v is **internal** if it has at least one incoming edge

Internal neuron v computes a linear threshold function on its predecessor neurons

$$x_v = \mathbb{1}\left(\sum_{u \in \text{Pred}(v)} w_{uv} \cdot x_u \geq \theta_v\right) \quad \text{where } \text{Pred}(v) = \{\text{predecessors of } v\}$$

v is activated (i.e. $x_v = 1$) if the weighted sum of incoming signals exceeds threshold θ_v

When G has a single output node (that has no outgoing edges)

the network N computes a function $f_N : \mathbb{R}^n \rightarrow \{0, 1\}$ (given w_{uv} and θ_v)

If learning algorithm A searches for weights and thresholds to minimize training error

A 's hypothesis class is $\mathcal{H}_N = \{f_N \mid w_{uv} \in \mathbb{R}, \theta_v \in \mathbb{R}\}$

$\text{VCDim}(\mathcal{H}_N) \leq ?$

Will answer this question for a more general class of neural networks:

Redefine neural network N as directed acyclic graph G with concept classes at internal nodes

\mathcal{C}_j over $\mathbb{R}^{\text{Pred}(v_j)}$ is the concept class at internal node v_j

Internal neuron v_j computes $x_{v_j} = \mathbb{1}(x_{\text{Pred}(v_j)} \in \mathcal{C}_j)$ for some $\mathcal{C}_j \in \mathcal{C}_j$

Original definition has $\mathcal{C}_j = \{\text{LTFs}\}$ for all v_j ; New definition allows other activation functions

Hypothesis class $\mathcal{H}_N = \{f_N \mid \mathcal{C}_j \in \mathcal{C}_j\}$ (now $f_N : \mathbb{R}^n \rightarrow \{0, 1\}$ implicitly depends on \mathcal{C}_j 's)

Theorem 1. Growth function of \mathcal{H}_N is at most the product of growth functions of \mathcal{C}_j over internal nodes v_1, \dots, v_s of G ,

$$\Pi_{\mathcal{H}_N}(m) \leq \Pi_{\mathcal{C}_1}(m) \cdots \Pi_{\mathcal{C}_s}(m) \quad \text{for all } m \in \mathbb{N}$$

Proof. Order internal nodes v_1, \dots, v_s by the order they get evaluated (i.e. topological order)

e.g. in above diagram, v_4 comes after v_1, \dots, v_3 because x_{v_4} depends on x_{v_1}, \dots, x_{v_3}

Fix m input samples $S = \{x^1, \dots, x^m\}$ where every $x^i \in \mathbb{R}^n$

How many different labelings/dichotomies $T \in \Pi_{\mathcal{H}_N}(S)$ are induced as $\mathcal{C}_j \in \mathcal{C}_j$ vary?

Imagine choosing $\mathcal{C}_1, \dots, \mathcal{C}_s$ sequentially and suppose $\mathcal{C}_1, \dots, \mathcal{C}_{j-1}$ have been fixed

For every $u \in \text{Pred}(v_j)$, the function $f_u : \mathbb{R}^n \rightarrow \mathbb{R}$ of the subnetwork ending at u is fixed

Every sample x^i yields a vector $(f_u(x^i))_{u \in \text{Pred}(v_j)}$ of evaluations of these functions

Call this vector $f_{\text{Pred}(v_j)}(x^i)$; It belongs to $\mathbb{R}^{\text{Pred}(v_j)}$

Collection of these vectors $S_j = \{f_{\text{Pred}(v_j)}(x^i) \mid x^i \in S\}$ has size $\leq m$

Varying \mathcal{C}_j may induce different dichotomies $T_j \in \Pi_{\mathcal{C}_j}(S_j)$ on S_j

Choosing all $\mathcal{C}_1, \dots, \mathcal{C}_s$ yields a labeling T of S , together with a sequence (T_1, \dots, T_s) as above

Distinct labelings T and T' must correspond to different sequences (T_1, \dots, T_s) and (T'_1, \dots, T'_s)

Because a sequence (T_1, \dots, T_s) contains enough information to recover T

via computing $f_{v_j}(x^i) = \mathbb{1}(f_{\text{Pred}(v_j)}(x^i) \in T_j)$ iteratively for $j = 1, \dots, s$

Every T_j is induced by $\mathcal{C}_j \in \mathcal{C}_j$ on S_j of size $\leq m \implies$ At most $\Pi_{\mathcal{C}_1}(m) \cdots \Pi_{\mathcal{C}_s}(m)$ sequences \square

Corollary 2. If $\text{VCDim}(\mathcal{C}_j) \leq d$ for all $1 \leq j \leq s$, then $\text{VCDim}(\mathcal{H}_N) \leq 2ds \log(es)$ when $s \geq 2$

Proof. By above Theorem and Sauer–Shelah lemma, when $m \geq d$,

$$\Pi_{\mathcal{H}_N}(m) \leq \Pi_{\mathcal{C}_1}(m) \cdots \Pi_{\mathcal{C}_s}(m) \leq \left(\left(\frac{em}{d} \right)^d \right)^s$$

$$\text{VCDim}(\mathcal{H}_N) < m \iff \Pi_{\mathcal{H}_N}(m) < 2^m, \text{ so we want } \left(\frac{em}{d} \right)^{ds} < 2^m \iff ds \log \left(\frac{em}{d} \right) < m$$

How to choose m ?

Clearly $m \geq ds$ is needed, but then $\log(em/d) \geq \log(es)$, so $m \geq ds \log(es)$

Turns out $m = 2ds \log(es)$ suffices when $s \geq 2$ (exercise) □

Back to original question, if G has fan-in r (i.e. every internal node takes signals from r other nodes)

$$\text{VCDim}(\{\text{LTFs over } \mathbb{R}^r\}) = r + 1 \implies \text{VCDim}(\mathcal{H}_N) \leq 2(r + 1)s \log(es)$$

Neural networks in practice typically have internal nodes with real-valued outputs, not just $\{0, 1\}$

Above Theorem does not apply to these networks

The end of Notes15 considers

$$\mathcal{H}_R = \left\{ \text{sign} \left(\sum_{1 \leq t \leq R} \alpha_t h_t \mid \alpha_t \in \mathbb{R}, h_t \in \mathcal{H} \text{ for } 1 \leq t \leq R \right) \right\}$$

where \mathcal{H} denotes the hypothesis class of weak learner A in AdaBoost

Proposition in Notes15 can be proved using above Theorem and calculations in above Corollary

Question: Which neural network corresponds to \mathcal{H}_R ? What are the \mathcal{C}_j 's?