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Notes 4: Perceptron and Halving algorithms

1. Perceptron algorithm

Update weights additively

Learn well-separated (i.e. large margin) LTF with possibly negative weights

Let $c(x) = \mathbb{1}(v \cdot x \ge \theta)$ be the unknown LTF

Normalization: threshold $\theta = 0$ (halfspace through the origin)

Reason: Add extra coordinate $x_{n+1} = 1$ to every instance

$$v \cdot (x_1, \dots, x_n) \geqslant \theta \qquad \iff \qquad (v, -\theta) \cdot (x_1, \dots, x_{n+1}) \geqslant 0$$

(recall $||x|| = \sqrt{x_1^2 + \dots + x_n^2}$) **Normalization:** Every sample x has unit length, i.e. ||x|| = 1

Reason: By previous assumption $\theta = 0$; rescaling x doesn't change the sign of $v \cdot x$

Normalization: weight vector v has unit length

-Perceptron-

w = 0Initialize:

On input x, output hypothesis $h(x) = \mathbb{1}(w \cdot x \ge 0)$ and get c(x)

False positive (h(x) = 1, c(x) = 0): Update w as w - x

False negative (h(x) = 0, c(x) = 1): Update w as w + x

On false positive, $w \cdot x$ is too big, so subtract x from w, so that $(w - x) \cdot x = w \cdot x - ||x||^2 = w \cdot x - 1$ On false negative, $w \cdot x$ is too small, so add x to w, so that $(w+x) \cdot x = w \cdot x + ||x||^2 = w \cdot x + 1$

Theorem 1. (Perceptron convergence) Let $c(x) = \mathbb{1}(v \cdot x \ge 0)$ be centered LTF with ||v|| = 1. Suppose all samples x have unit length, let margin δ be min $|v \cdot x|$ over all samples x received by the algorithm. Then Perceptron Algorithm learns c with at most $1/\delta^2$ mistakes

Claim 2. After M mistakes, $w \cdot v \geqslant \delta M$

Proof. True when M=0 since w=0

Will show that every mistake increases $w \cdot v$ by $\geq \delta$

On false positive, $w \cdot v$ becomes $(w - x) \cdot v = w \cdot v - x \cdot v \geqslant w \cdot v + \delta$

On false negative, $w \cdot v$ becomes $(w + w) \cdot v = w \cdot v + x \cdot v \geqslant w \cdot v + \delta$

Claim 3. After M mistakes, $||w||^2 \leq M$

Proof. True when M=0 since w=0

Will show that every mistake increases $||w||^2$ by ≤ 1 On false positive, $||w||^2$ becomes $||w-x||^2 = (w-x) \cdot (w-x) = ||w||^2 - 2\underbrace{w \cdot x}_{\geqslant 0} + \underbrace{||x||^2}_{=1}$

On false negative, $||w||^2$ becomes $||w + x||^2 = (w + x) \cdot (w + x) = ||w||^2 + 2\underbrace{w \cdot x}_{0} + \underbrace{||x||^2}_{0}$

Proof of Perceptron Convergence.

$$\delta M \leqslant w \cdot v \leqslant \|w\| \stackrel{=1}{\|v\|} \leqslant \sqrt{M}$$
Cauchy–Schwarz

The above bound is tight!

Claim 4. When $X = \{x \in \mathbb{R}^d \mid ||x|| = 1\}$ and $d \ge |1/\delta^2|$, any deterministic algorithm for learning LTF makes $|1/\delta^2|$ mistakes on certain sample sequences and LTF with margin δ

Proof. ith x^i sample is ith standard basis vector e_i (i.e. 1 at position i and 0 elsewhere)

Number of samples is $n \stackrel{\text{def}}{=} |1/\delta^2|$ (as most d by assumption)

All samples will be labeled as the opposite of algorithm's prediction

Will find $v \in \mathbb{R}^d$ with $||v|| \leq 1$ that "correctly" classifies all e_i with margin δ , i.e.

 \forall "correct label sequence" $y \in \{1, -1\}^n$, $y_i \delta = v \cdot e$

This forces $v_i = \delta y_i$ for all $i \leq n$ Indeed $||v||^2 = \delta^2 ||y||^2 = \delta^2 n \leq 1$ (e.g. $v = \{+\delta, -\delta, -\delta, +\delta\}$)

2. Dual perceptron

In Perceptron Algorithm w always ± 1 -sum of samples, i.e. \exists signs $\sigma_1, \ldots, \sigma_\ell \in \{1, -1\}$ s.t.

$$w = \sigma_1 x^{i_1} + \dots + \sigma_\ell x^{i_\ell}$$

Initially w = 0; Every mistake adds a new term $\sigma_i x^{i_j}$ to w

Memorizing all mistakes, on sample x,

$$w \cdot x = \sum_{1 \le j \le \ell} \sigma_j(x^{i_j} \cdot x)$$

Computable given inner products $x^{i_j} \cdot x$ between samples

Now takes #mistakes time to compute w (slower)

Can replace inner product \cdot with any **kernel function** K(,)

3. Halving algorithm

Given any finite concept class \mathcal{C}

-Halving Algorithm-

K always contains all $c \in \mathcal{C}$ consistent with all the labeled samples so far Hypothesis h is the majority vote over concepts in K

(initially $K = \mathcal{C}$)

Every mistake removes at least half of concepts from K

Claim: Halving Algorithm makes $\leq \log |\mathcal{C}|$ mistakes

Slow: |K| per round

Hypothesis isn't from \mathcal{C} , but the majority over a subset of \mathcal{C}

4. Randomized halving algorithm

Randomized Halving Algorithm

K always contains all $c \in \mathcal{C}$ consistent with all the labeled samples so far (initially $K = \mathcal{C}$) Randomly choose a concept $c \in K$ to be the hypothesis h

Claim 5. On any sequence of samples x^1, \ldots, x^m labeled by any $c \in \mathcal{C}$,

$$\mathbb{E}[\#mistakes\ of\ the\ algorithm] \leqslant \ln |\mathcal{C}| + O(1)$$

Proof. Fix $c \in \mathcal{C}$ and x^1, \ldots, x^m

Suppose at some point |K| = r

We will bound $\mathbb{E}[\#\text{future mistakes}] \leq M_r$ for some upper bound M_r defined below

Order concepts c_1, \ldots, c_r in K according to when they are eliminated by the sequence e.g. first eliminated batch c_1, \ldots, c_3 , next c_4, c_5 etc, finally $c_r = c$ never eliminated

On first sample x^1 , Algorithm randomly chooses one of c_1, \ldots, c_r

If c_r is chosen, no mistake (1/r chance)

If chosen c_t makes mistake on x^1 (1/r chance for each t < r)

 c_1, \ldots, c_t (and possibly more) must be eliminated

K shrinks to (at most) size r-t, expect M_{r-t} more mistakes

$$M_r \leqslant \sum_{1 \leqslant t < r} \frac{1}{r} (1 + M_{r-t}) \implies rM_r \leqslant \sum_{1 \leqslant t < r} (1 + M_{r-t}) = r - 1 + M_1 + \dots + M_{r-1}$$

Similarly for
$$r-1$$
: $(r-1)M_{r-1} = (r-2) + M_1 + \dots + M_{r-2}$
Subtracting, $r(M_r - M_{r-1}) \le 1$ (*)

$$M_r \leqslant \frac{1}{r} + M_{r-1} \leqslant \frac{1}{r} + \frac{1}{r-1} + M_{r-2} \leqslant \dots \leqslant \underbrace{\frac{1}{r} + \frac{1}{r-1} + \dots + \frac{1}{1}}_{\text{Harmonic number}} = \ln r + O(1)$$

In the above, we defined M_r by (*)

Constant factor improvement over deterministic halving: $\log |\mathcal{C}|/\ln |\mathcal{C}| = \log e = 1.44...$